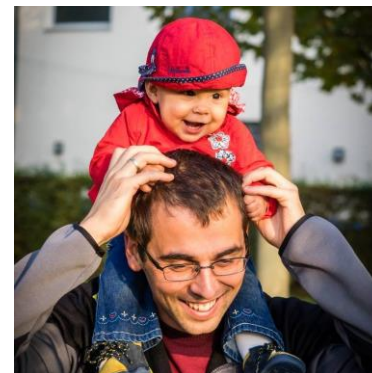
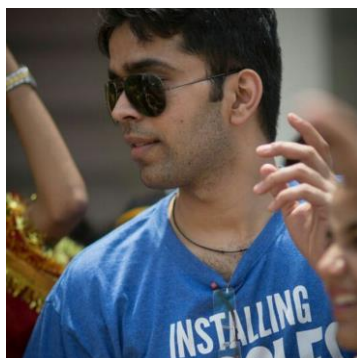


# Finding Best LP Relaxations for Directed Cut Problems

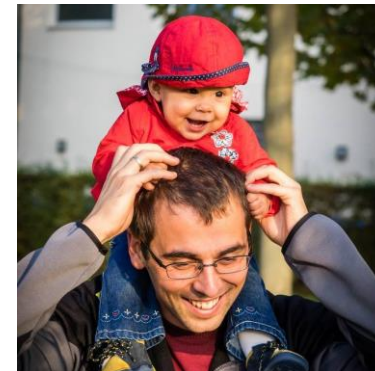
Euiwoong Lee

CMU → *Simons*

# People & Papers



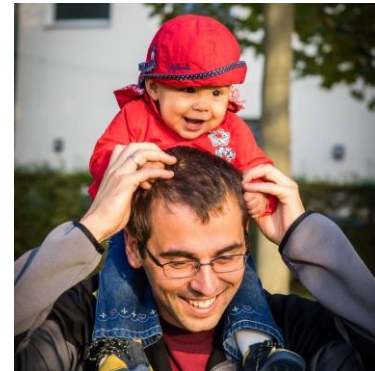
# People & Papers



Multicut(H)

# People & Papers

Multicut,  
Interdiction,  
Firefighter



Multicut(H)



# People & Papers

Multicut,  
Interdiction,  
Firefighter



Global cut  
problems



Multicut(H)



# People & Papers

Multicut,  
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Global cut  
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Multicut(H)



Linear 3-cut



# People & Papers

Multicut,  
Interdiction,  
Firefighter



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Multicut(H)

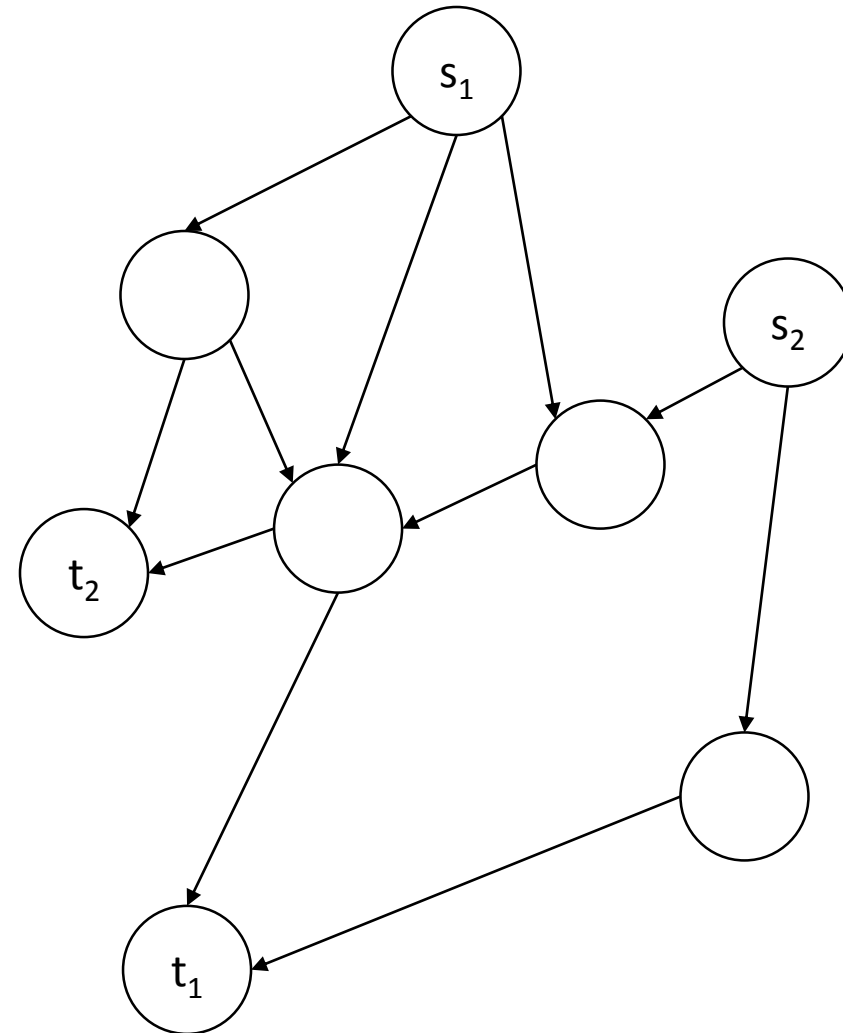


Linear 3-cut



# Directed Multicut

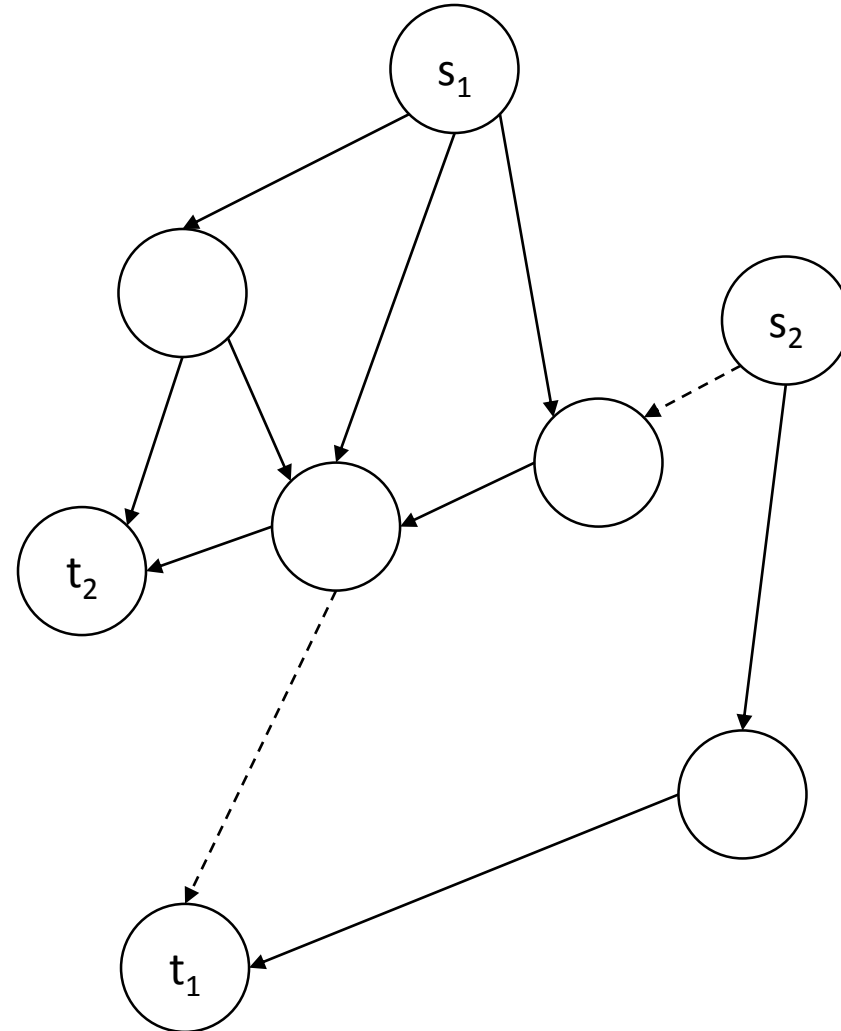
- Input
  - Directed Graph  $G=(V, E)$ ,  $k$  pairs  $(s_1, t_1), \dots, (s_k, t_k)$
- Goal
  - Remove minimum # of edges to cut all  $s_i$ - $t_i$  path.





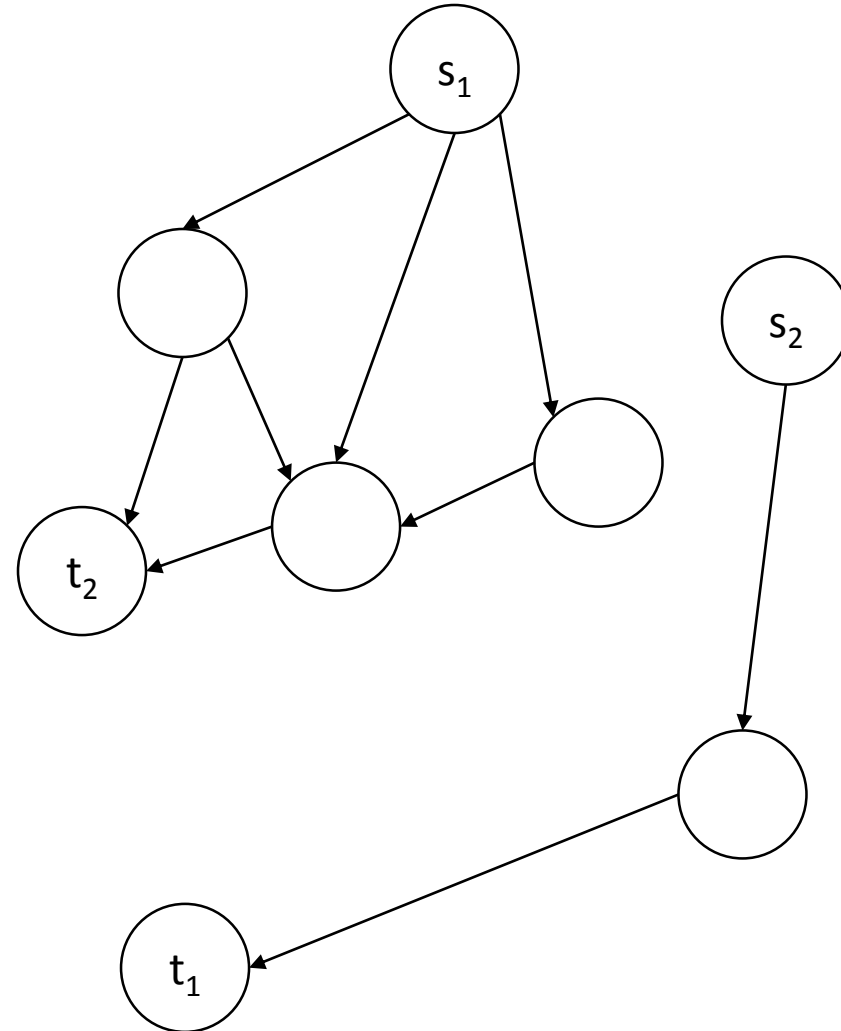
# Directed Multicut

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# Directed Multicut

- Input
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- Goal
  - Remove minimum # of edges to cut all  $s_i$ - $t_i$  path.



# Directed Multicut (before 2017)

- In terms of  $n$ ,
  - [CKR 01]  $\tilde{O}(n^{1/2})$ -approx.
  - [Gupta 03]  $O(n^{1/2})$ -approx.
  - [AAC 07]  $\tilde{O}(n^{11/23})$ -approx.
  - [CK 07]
    - $\tilde{\Omega}(n^{1/7})$  flow-cut gap.
    - $2^{\Omega(\log^{1-\epsilon} n)}$ -(NP) hard.
- In terms of  $k$ ,
  - Easy  $k$ -approx.
  - [SSZ 00]  $k = O(\log n / \log \log n)$ ,
    - Flow-cut gap is  $k - o(1)$ .
  - [CM 16, EVW 13] 1.5-(UG) hard when  $k = 2$ .
    - From Undir. Node Multiway Cut
    - Best for any constant  $k$ ?

# In 2017

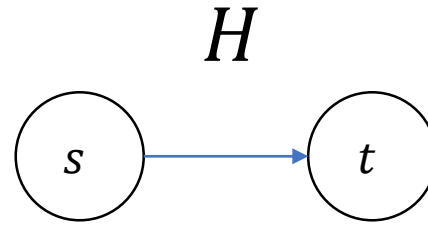
- [CM 17, L 17]
  - Directed Multicut with  $k$  pairs is  $k$ -(UG) hard.
- [CM 17]
  - Reduction from CSP [EVW 13].
  - Interesting connections between different LP relaxations.
- [L 17]
  - Direct reduction from UG.
  - Easy(?) to adapt to other cut problems.



# Only in [CM 17]

- Let  $H = (V_H, E_H)$  be a fixed demand graph.
- Multicut( $H$ )
  - Input: Supply graph  $G = (V_G, E_G)$  and injective map  $\pi: V_H \rightarrow V_G$ .
  - Goal: Remove min # edges from  $G$  such that
    - $\forall (u, v) \in E_H$ , there is no path from  $\pi(u)$  to  $\pi(v)$  in  $G$ .

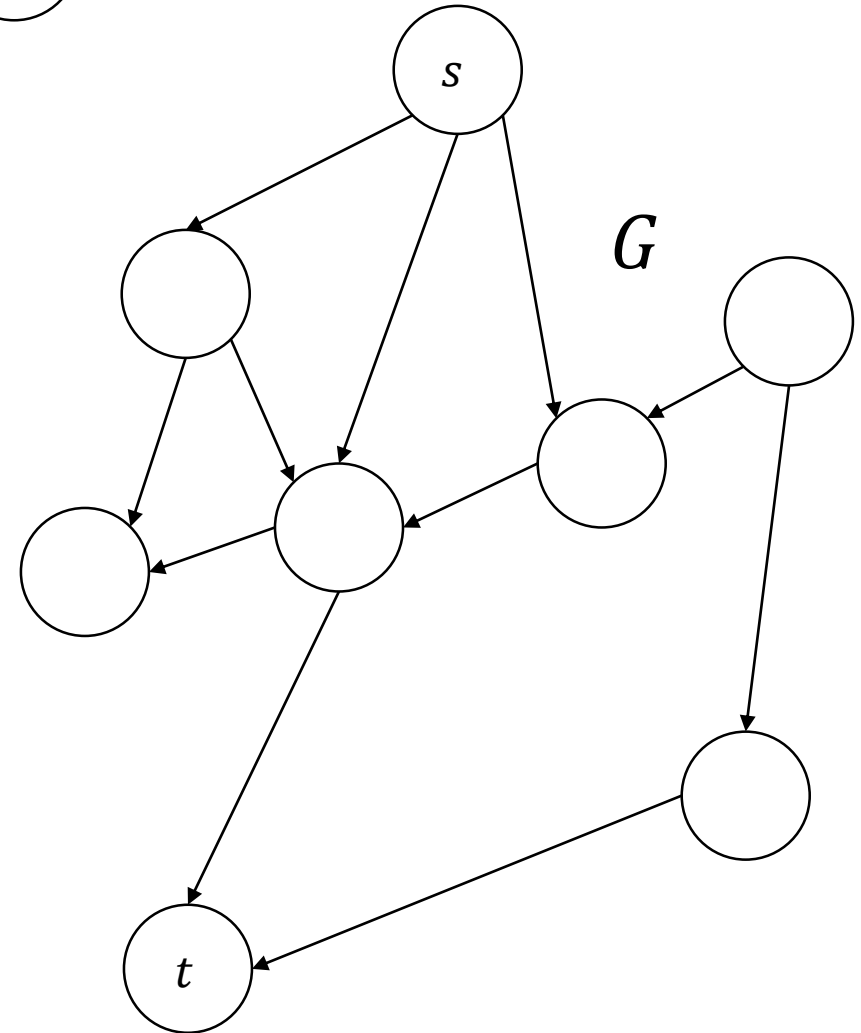
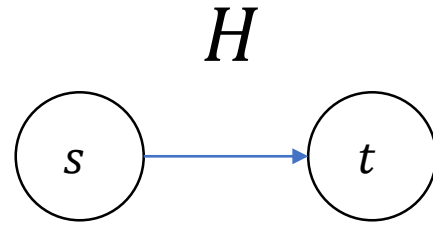
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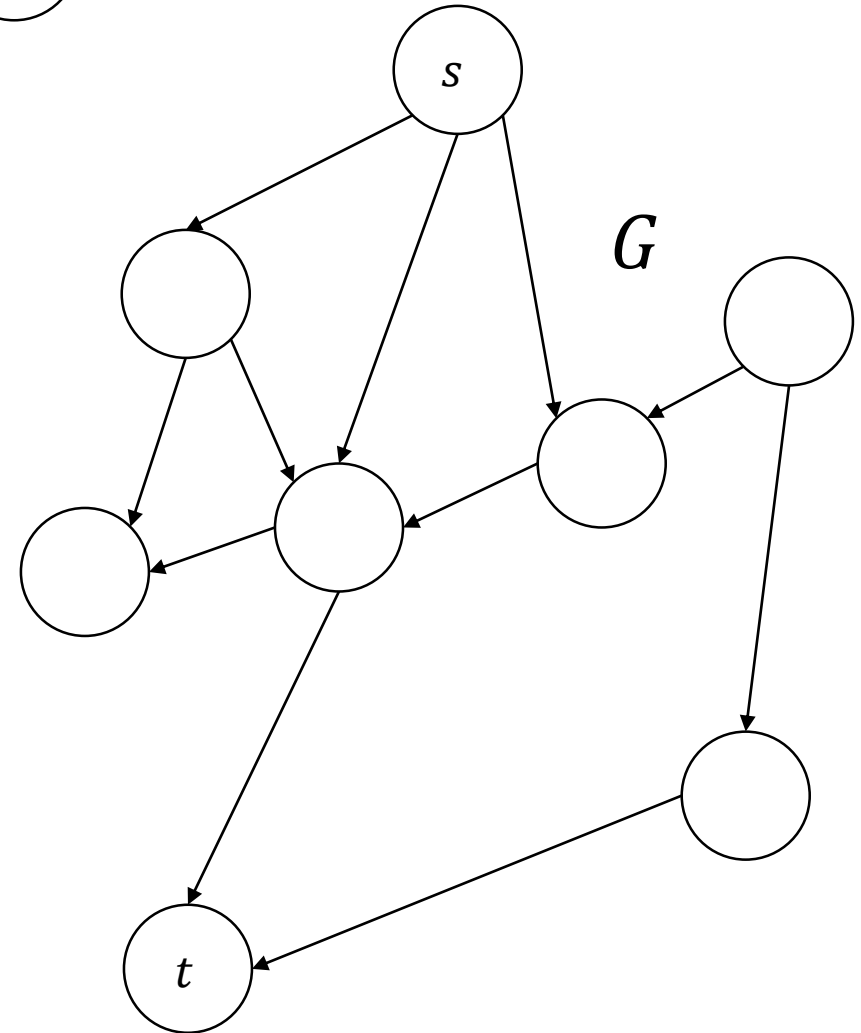
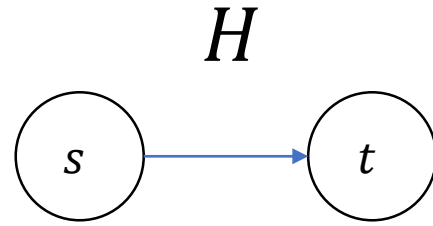
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# Only in [CM 17]

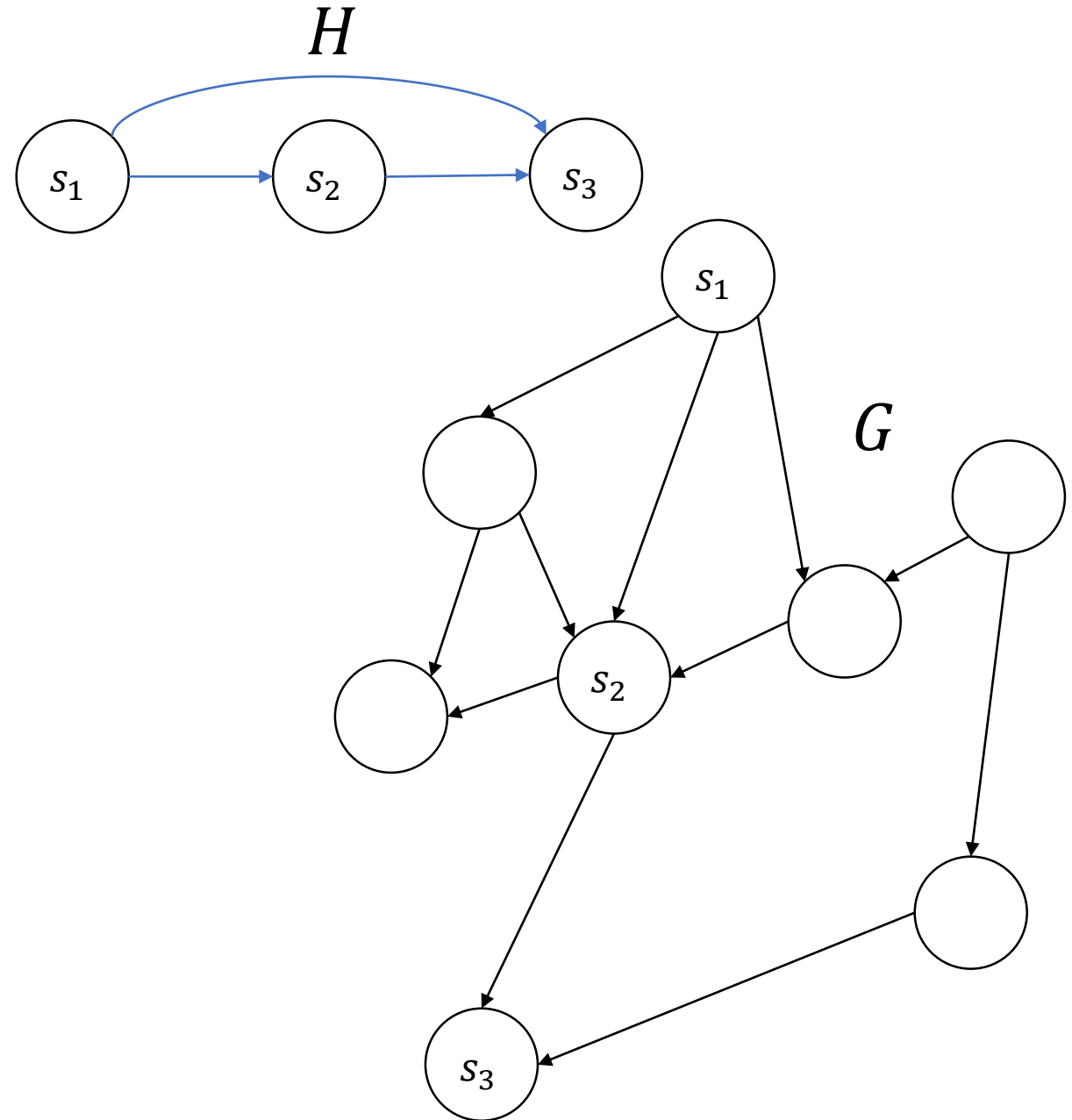
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  - Goal: Remove min # edges from  $G$  such that
    - $\forall (u, v) \in E_H$ , there is no path from  $\pi(u)$  to  $\pi(v)$  in  $G$ .
- Multicut(1 edge) = Min s-t cut!





# Only in [CM 17]

- Let  $H = (V_H, E_H)$  be a fixed demand graph.
- Multicut( $H$ )
  - Input: Supply graph  $G = (V_G, E_G)$  and injective map  $\pi: V_H \rightarrow V_G$ .
  - Goal: Remove min # edges from  $G$  such that
    - $\forall (u, v) \in E_H$ , there is no path from  $\pi(u)$  to  $\pi(v)$  in  $G$ .
- Multicut(complete DAG) = Linear  $k$ -cut ( $k = |V_H|$ ).



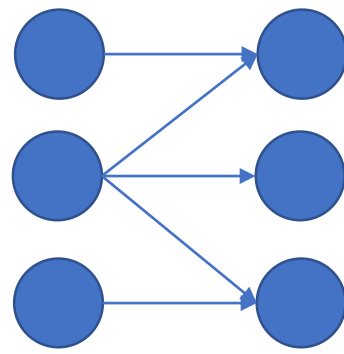
# Multicut( $H$ )

- Multicut( $H$ ):
  - Easy  $|E_H|$ -approximation.
  - Tight when  $H$  has  $k$  disjoint edges.
- Directed Multiway Cut ( $H$  = Complete Bidirected Graph)
  - [NZ97, CM16] 2-approx.
- $k$ -Linear Cut ( $H$  = Complete DAG)
  - $O(\log k)$ -approx. (Flow-cut gap open)
  - [BCKM 18?] 3-Linear Cut:  $\sqrt{2}$ -approx. (Matches flow-cut gap)

# Multicut( $H$ )

- Much better approximation ratio for some  $H$ !
  - All algorithms use flow-cut LP.
- Question] For some fixed  $H$ , will there a better relaxation?

# Multicut( $H$ )



- [CM 17] When  $H$  is a directed bipartite, Multicut( $H$ ) is UG-hard to approximate better than the worst flow-cut gap.
- What about general  $H$ ?
- It is still open whether flow-cut gap is the best.
- [LM ??] There exists another LP relaxation (or estimation algorithm) such that it is UG-hard to do better.



# Multicut( $H$ )

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# Multicut( $H$ )

- **[CM 17] When  $H$  is a directed bipartite, Multicut( $H$ ) is UG-hard to approximate better than the worst flow-cut gap.**
  - Another proof based on [L 17]
- What about general  $H$ ?
- It is still open whether flow-cut gap is the best.
- [LM ??] There exists another LP relaxation (or estimation algorithm) such that it is UG-hard to do better.

# Flow-Cut (Distance) LP

- Will consider vertex deletion version.
  - Cannot delete terminals ( $T := \pi(V_H)$ ).

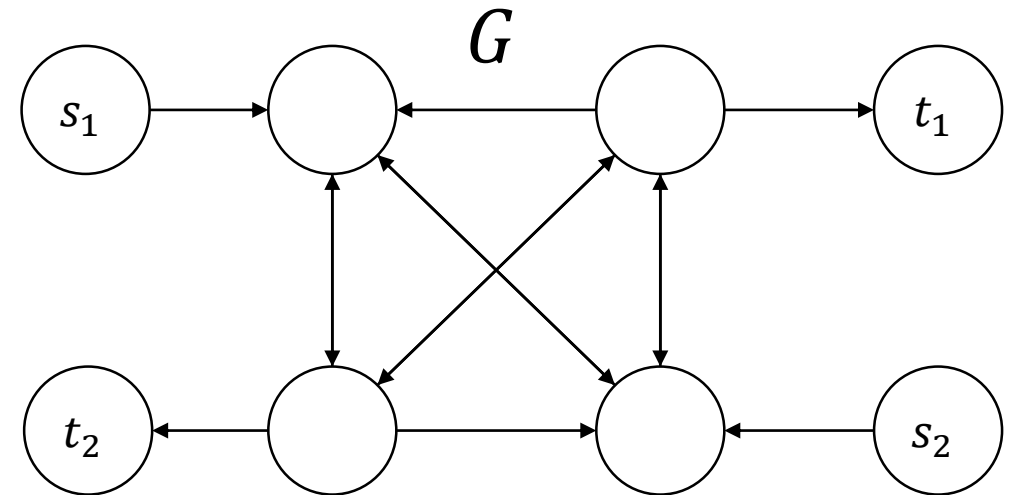
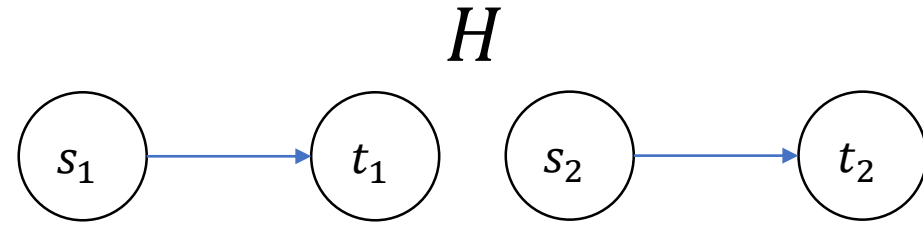
- Minimize  $\sum_{v \in V \setminus T} x_v$

- Subject to  $\sum_{v \in P \setminus T} x_v \geq 1$  for  $\forall (u, v) \in E_H$ , and  $\pi(u)$ - $\pi(v)$  path  $P$

- $x \geq 0$

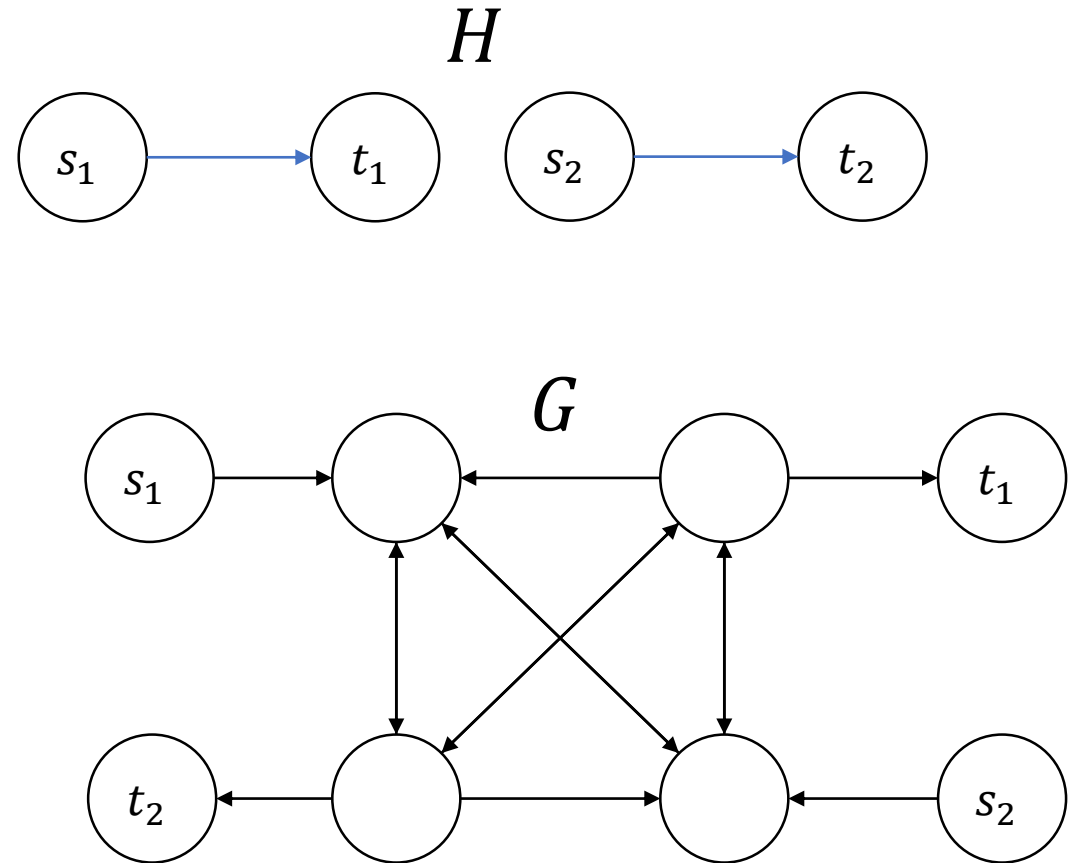
# LP Gap

- $OPT = 2$
- $LP = 4/3$ 
  - $x_v = 1/3$  for all  $v \in V \setminus T$
  - Every  $s_1-t_1$  or  $s_2-t_2$  path involves 3 internal (non-terminal) vertices.



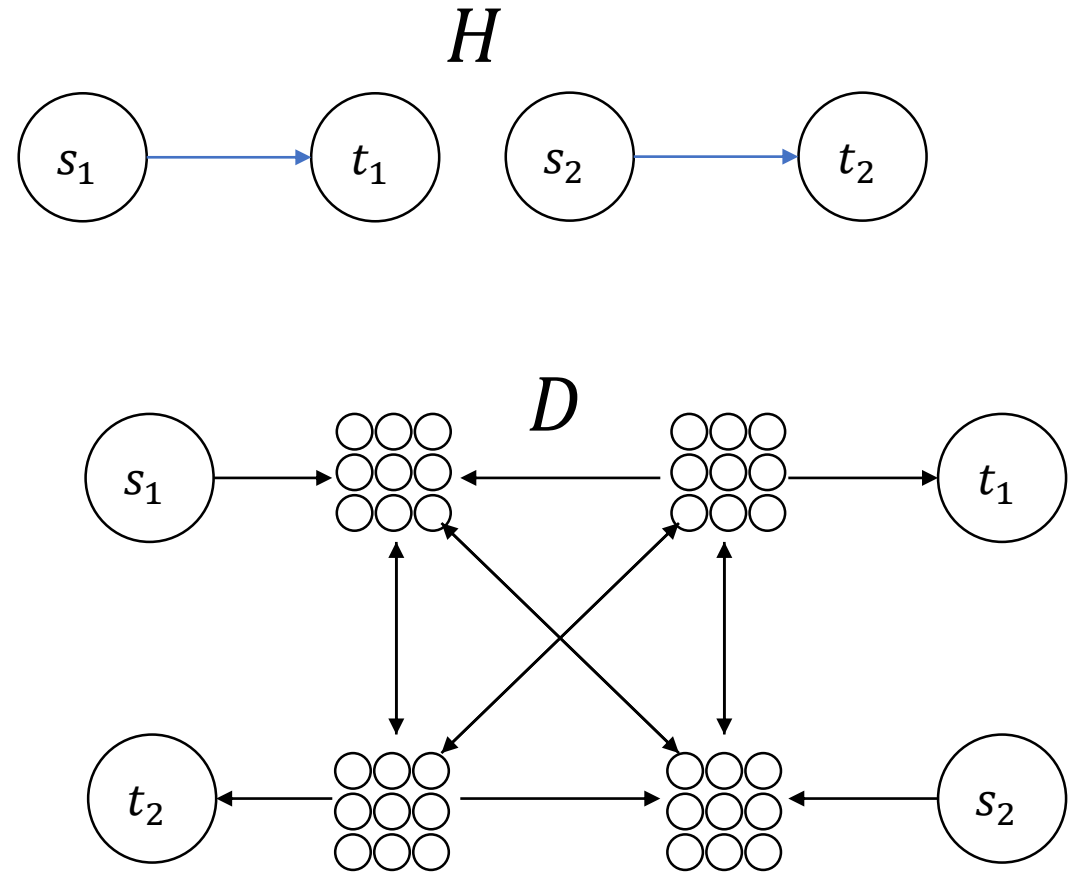
# Dictator Test

- Just another instance of  $\text{Multicut}(H)$
- Replace every internal vertex by a hypercube  $[\ell]^R$



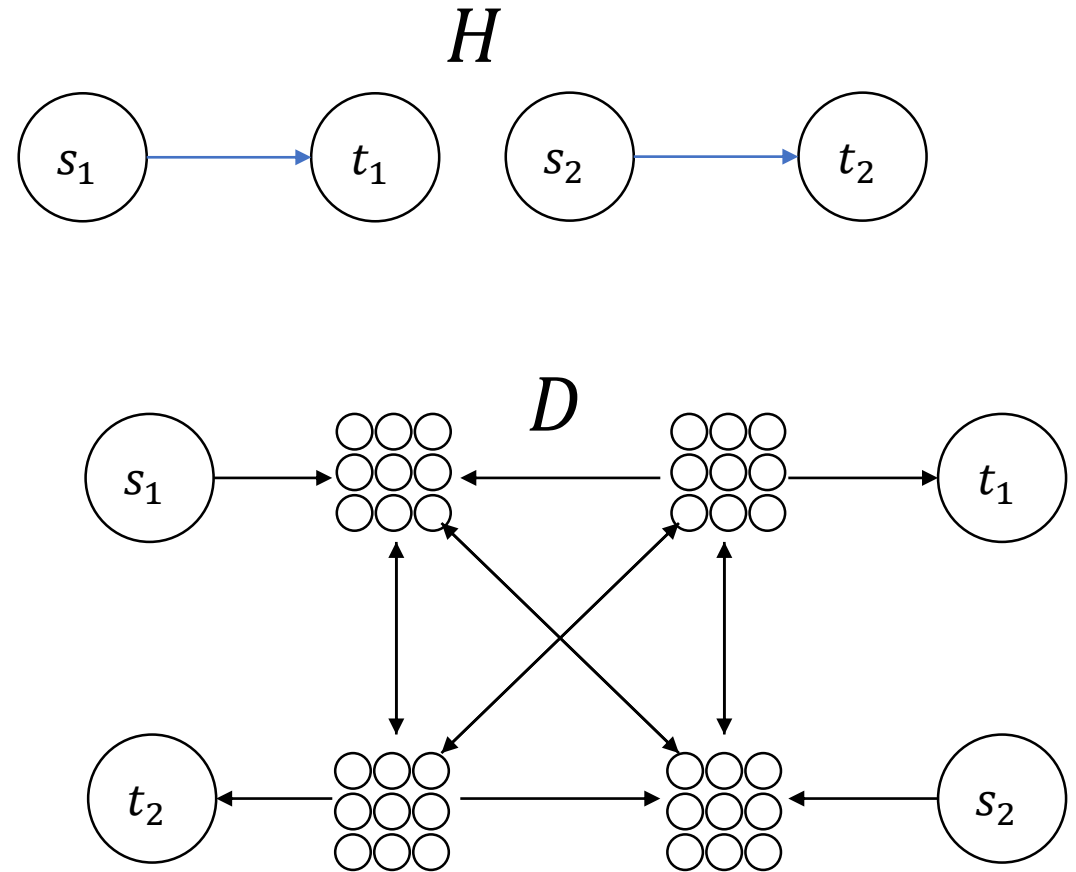
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# Dictator Test

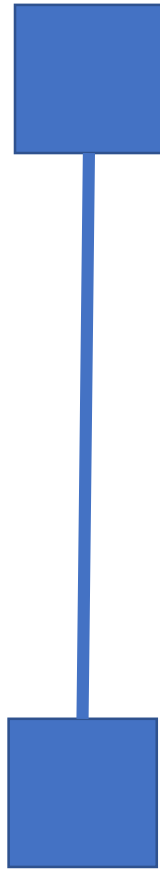
- Just another instance of  $\text{Multicut}(H)$
- Replace every internal vertex by a hypercube  $[\ell]^R$
- Put edges
  - If  $(u, v) \in E_G$ , create some edges between corresponding hypercube “appropriately”.



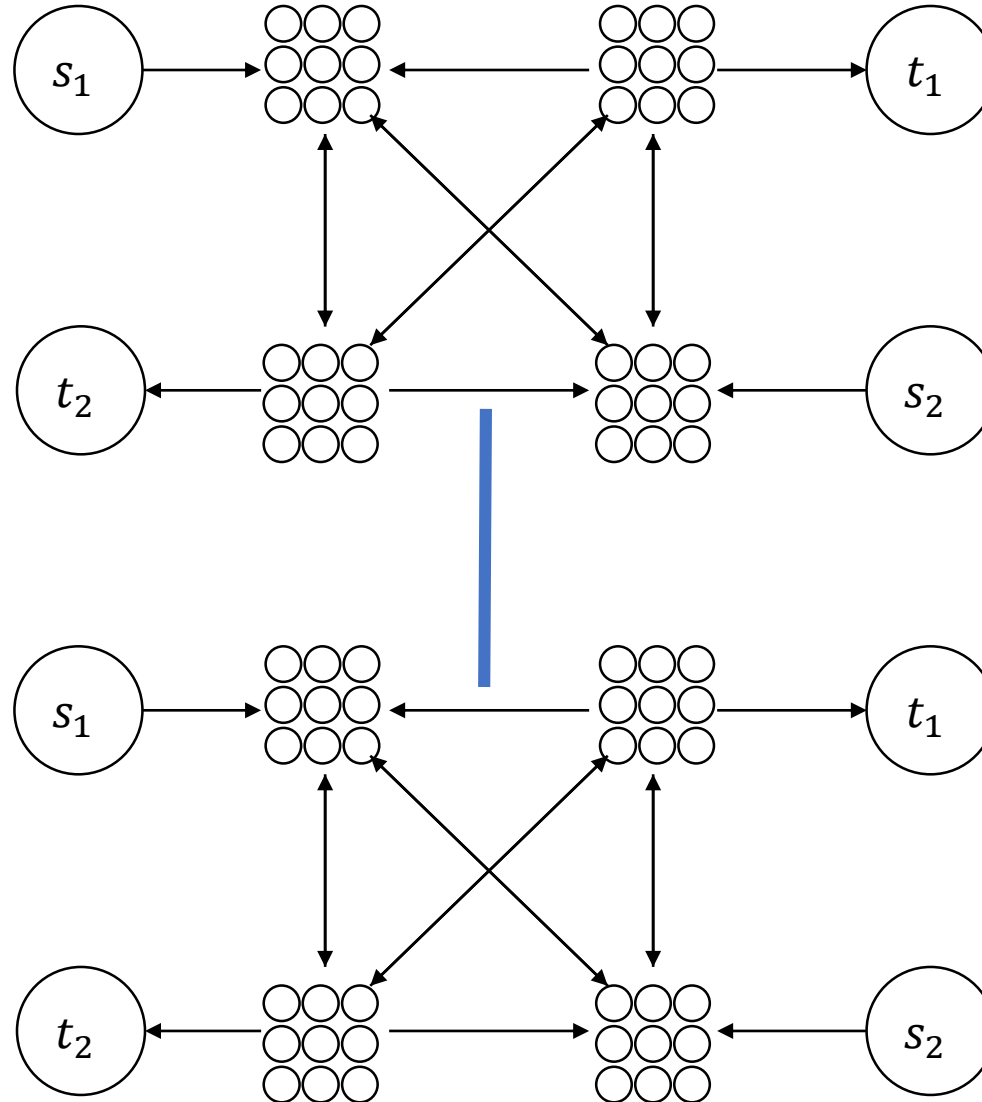


# Reduction from UG

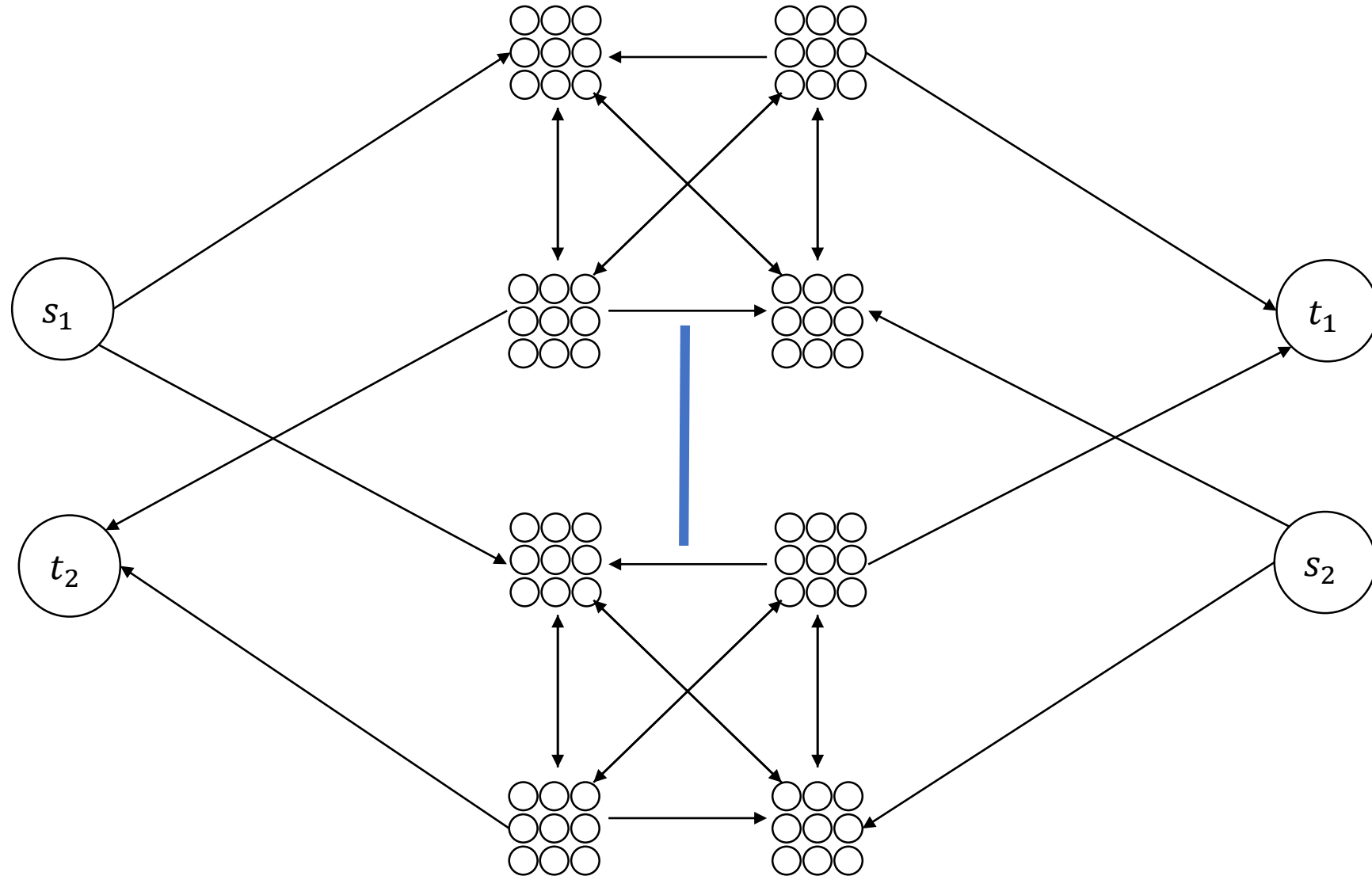
- Instance of Unique Games
  - A graph
  - Each edge is some constraint
- Goal: Give a label to each vertex to
  - Maximize # of “satisfied” edges.



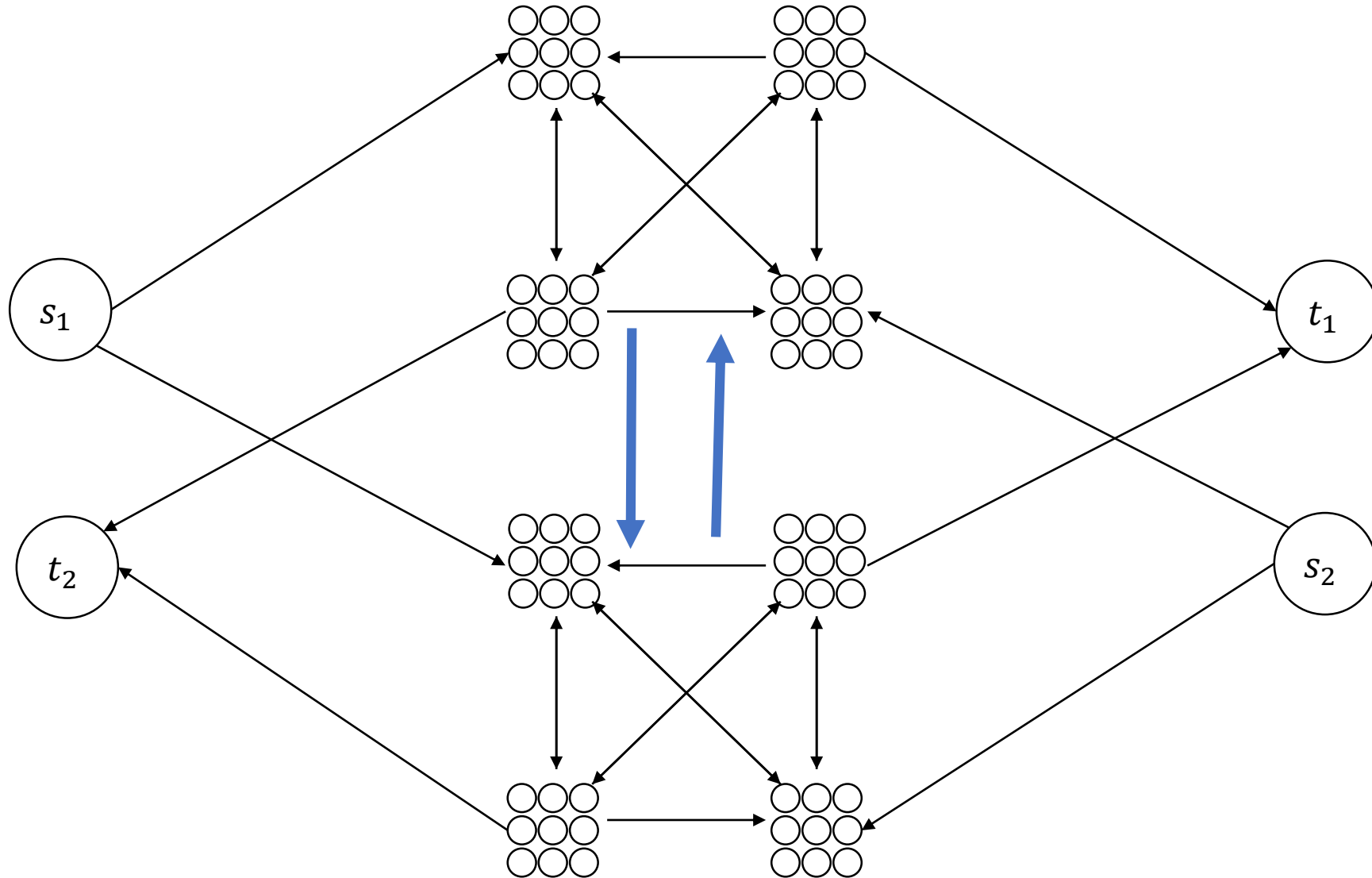
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# Reduction from UG

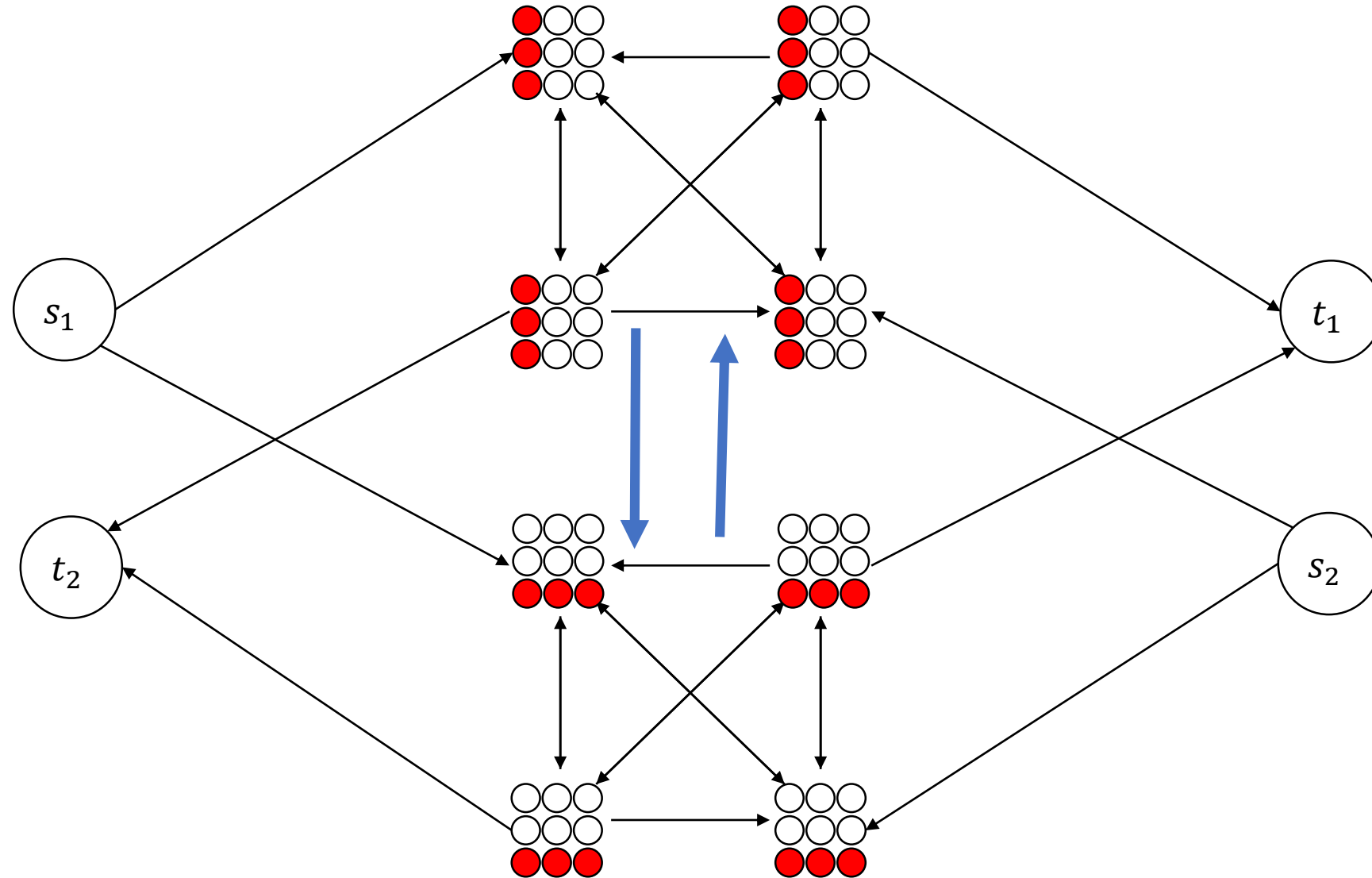


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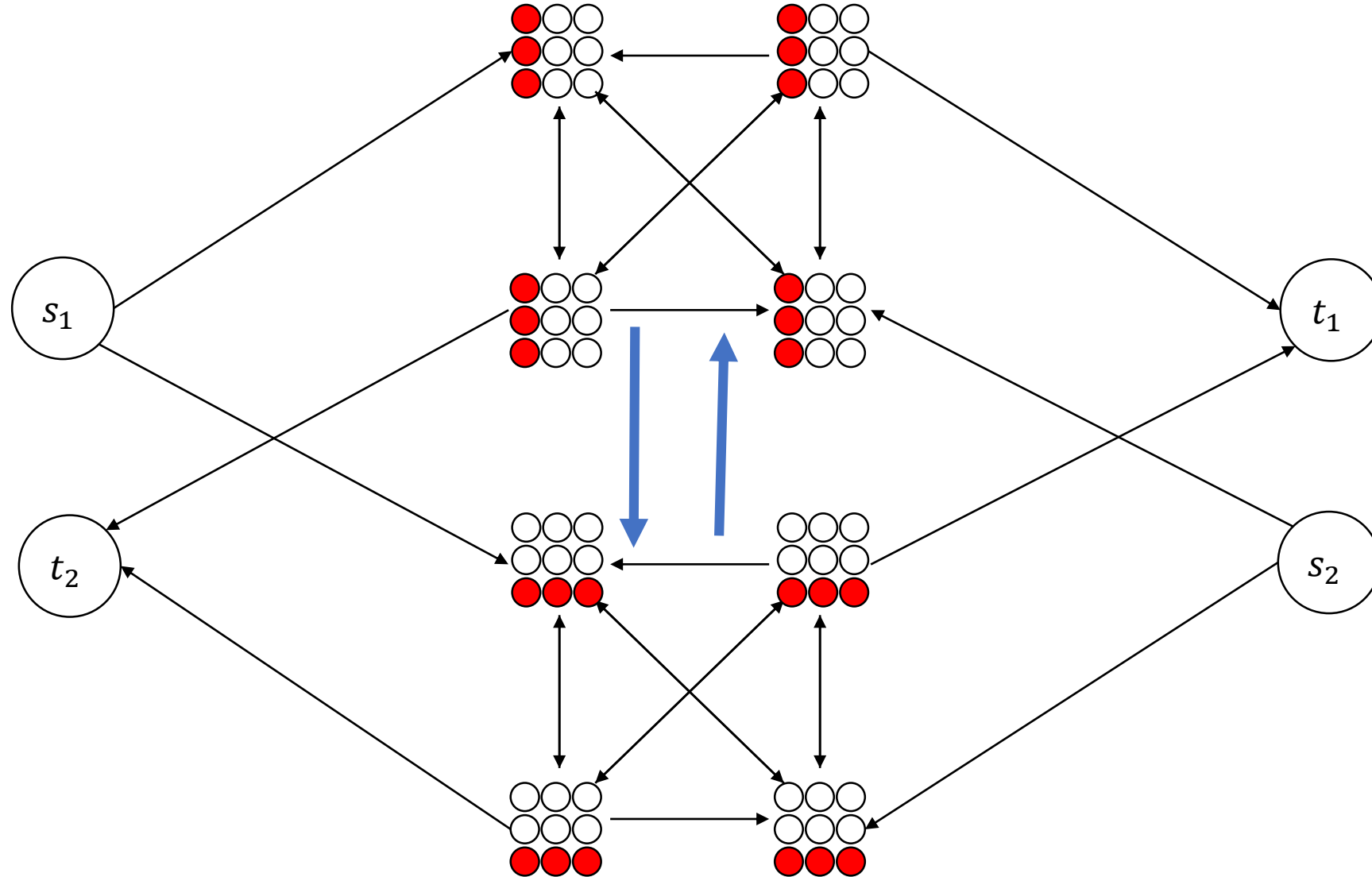
# Reduction from UG

If UG instance **has a good labeling** that satisfies most constraints.



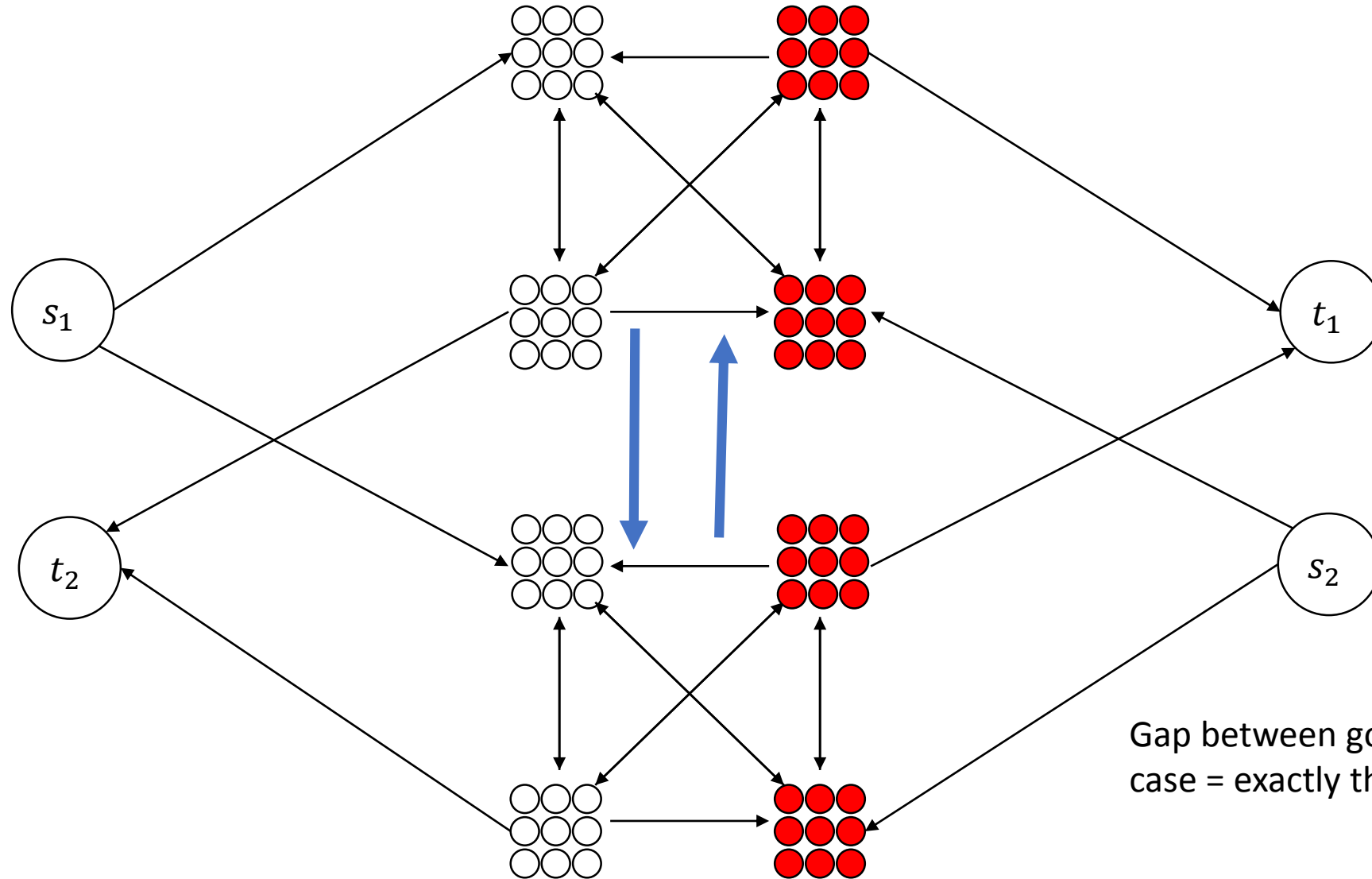
# Reduction from UG

If UG instance **does not** a good labeling



# Reduction from UG

If UG instance **does not** a good labeling



Gap between good case and bad case = exactly the LP gap.

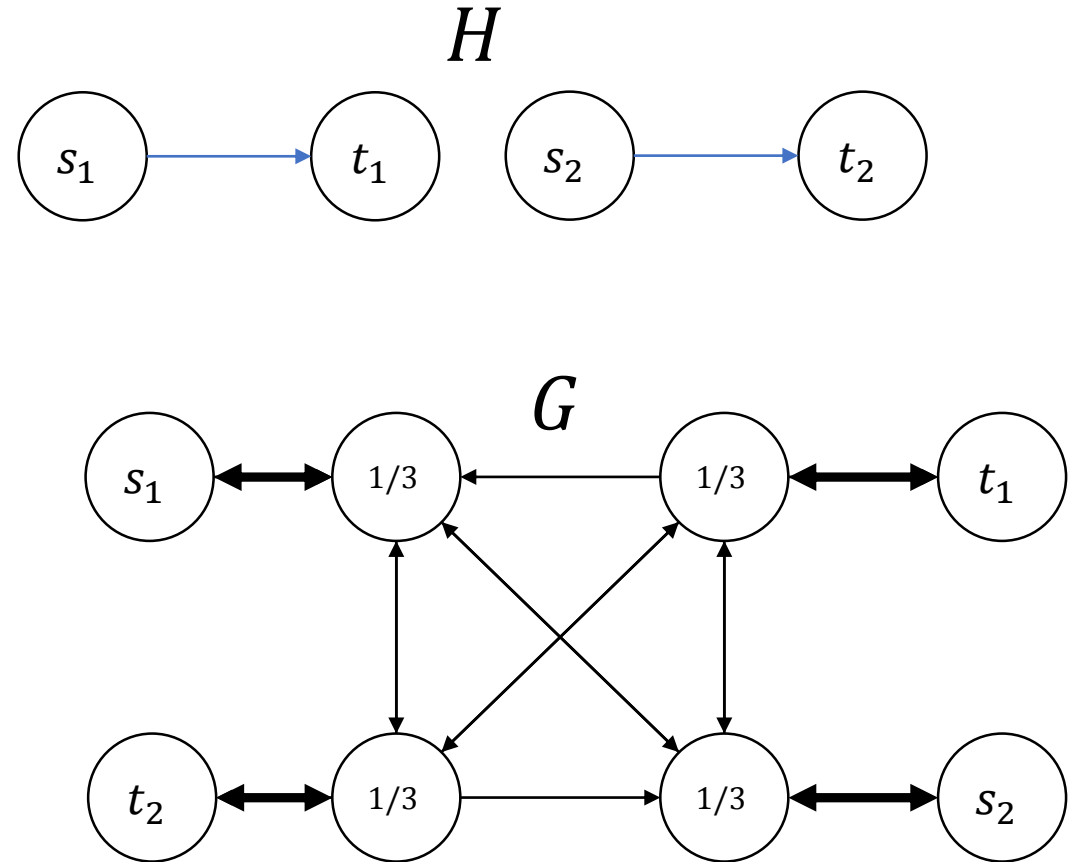
# Multicut( $H$ )

- **[CM 17] When  $H$  is a directed bipartite, Multicut( $H$ ) is UG-hard to approximate better than the worst flow-cut gap.**
- **What is wrong with general  $H$ ?**



# General H

- $x_v = 1/3$  for all  $v \in V \setminus T$ 
  - Still feasible to LP.
  - Reduction does not work.
- $\text{Dist.}(s_1 - t_1) = 1$ , but
  - $\text{Dist.}(s_1 - s_2) = \text{Dist.}(s_2 - t_1) = 2/3$
- **Observation]** In order to cut  $s_1$  from  $t_1$ , we need to either
  - Cut  $s_1$  from  $s_2$  OR
  - Cut  $s_2$  from  $t_1$





# Best (estimation) Algorithm

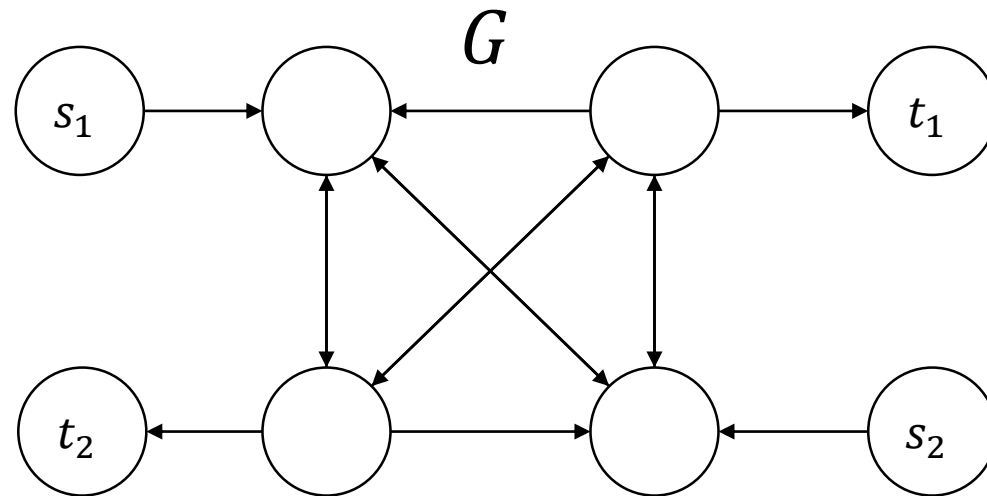
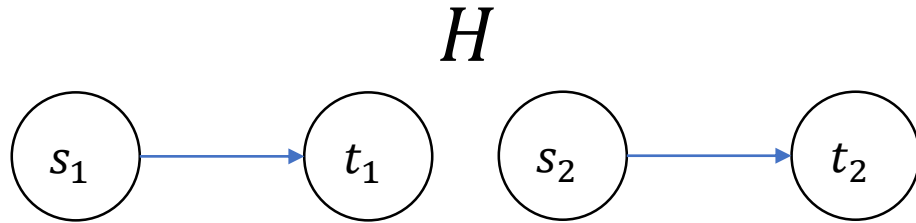
- Say  $F$  “unambiguous” if for every  $(u, v) \in E_F$  and  $w \in V_F$ 
  - Either  $(u, w) \in E_F$  or  $(w, v) \in E_F$
  - “If you cut  $(u, v)$ , then you need to cut either  $(u, w)$  or  $(w, v)$ ”.
  - (Directed) complement of  $F$  is transitive.

- Estimation algorithm for Directed Multicut( $H$ ).
  - Given a supply graph  $G$ ,
  - Try every “unambiguous”  $F = (V_H, E_F)$  s.t.  $E_H \subseteq E_F$ .
    - Compute Flow-cut relaxation value  $LP(F, G)$ .
  - Output the  $\min_F LP(F, G)$ .

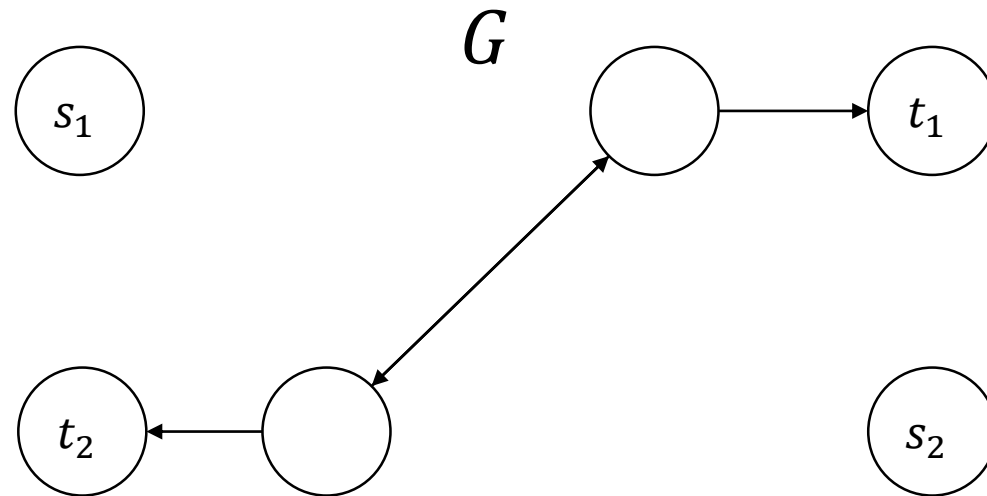
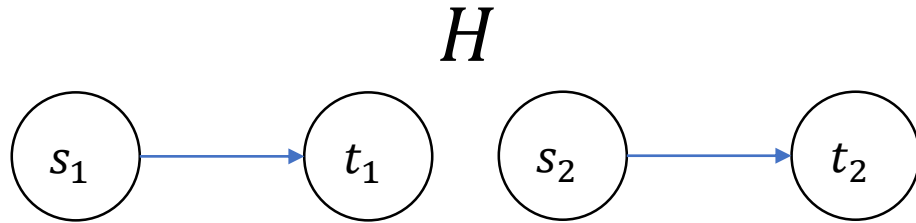
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  - Output the  $\min_F LP(F, G)$ .
- For every  $F$ ,  $LP(H, G) \leq LP(F, G)$ .
- There exists  $F$  such that  $LP(F, G) \leq OPT(F, G) = OPT(H, G)$

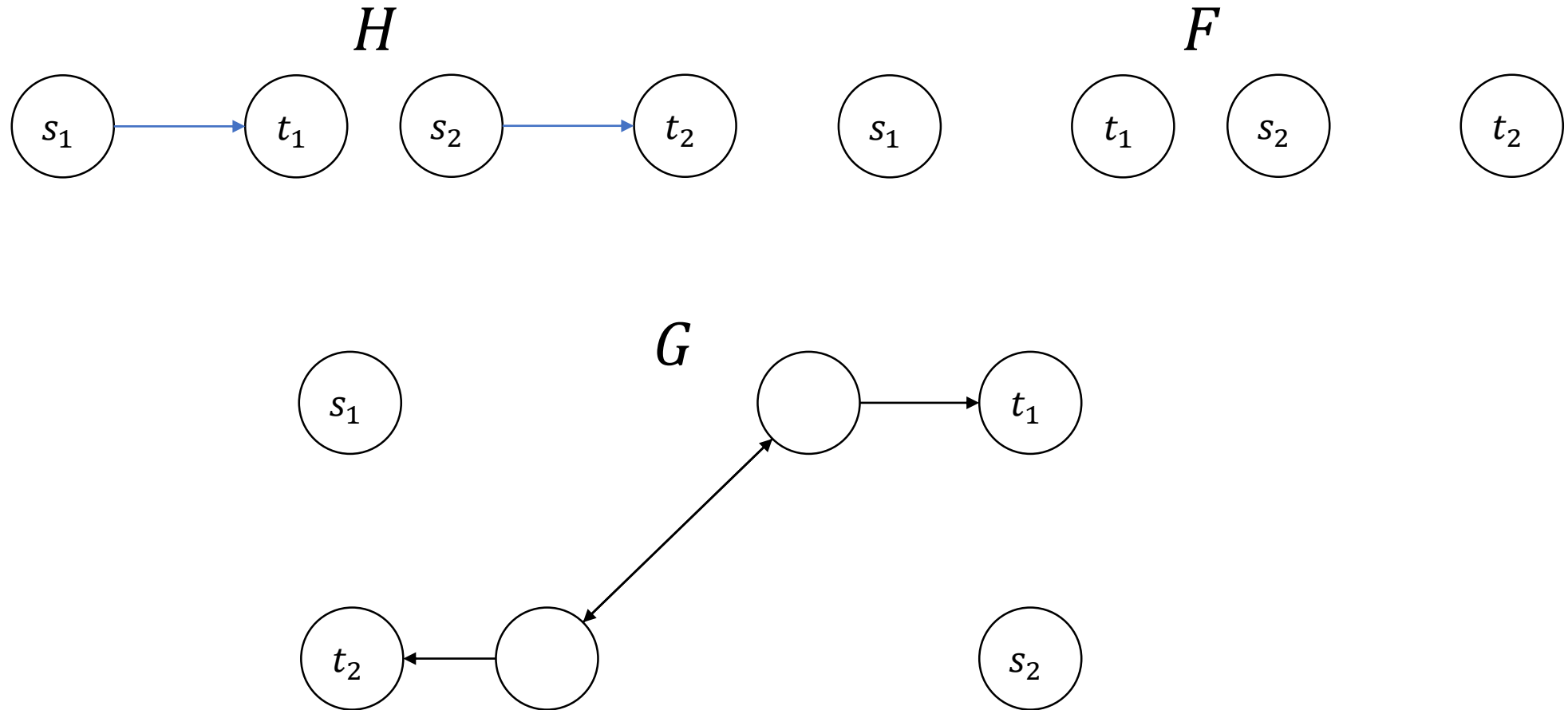
$$\exists F \text{ s.t. } LP(F, G) \leq OPT(F, G) = OPT(H, G)$$



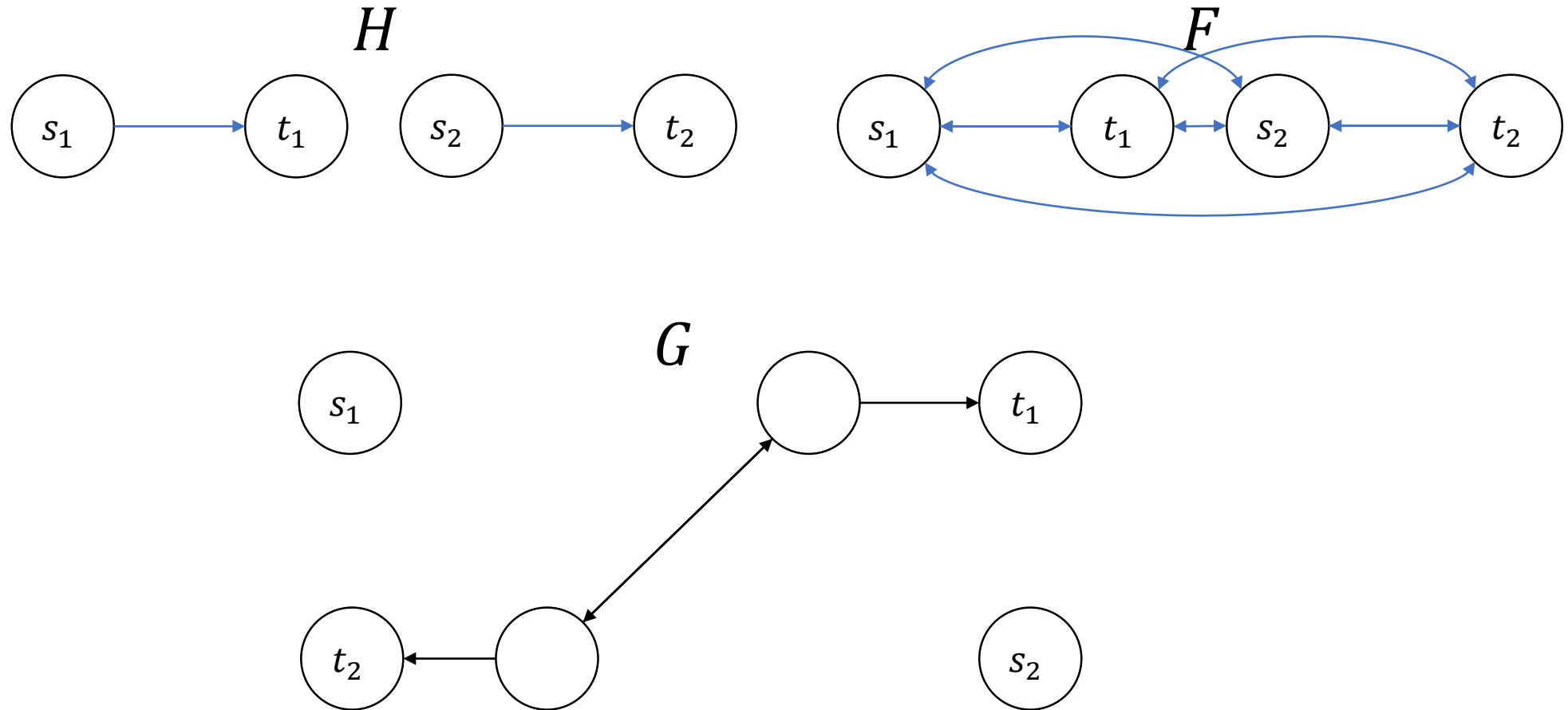
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# Best (estimation) Algorithm

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  - Output the  $\min_F LP(F, G)$ .
- For every  $F$ ,  $LP(H, G) \leq LP(F, G)$ .
- There exists  $F$  such that  $LP(F, G) \leq OPT(F, G) = OPT(H, G)$
- Therefore,  $LP(H, G) \leq ALG(H, G) \leq OPT(H, G)$  for every  $G, H$ .
- Can be captured as a single LP (running a flow-cut LP for every  $F$ ).

# Best (estimation) Algorithm

- Estimation algorithm for Directed Multicut( $H$ ).
  - Given a supply graph  $G$ ,
  - Try every “unambiguous”  $F = (V_H, E_F)$  s.t.  $E_H \subseteq E_F$ .
    - Compute Flow-cut relaxation value  $LP(F, G)$ .
  - Output the  $\min_F LP(F, G)$ .
- What does a gap of this algorithm mean (for fixed  $H$ )?
  - An unambiguous  $F \supseteq H$  and  $G$  s.t.  $LP(F, G) \ll OPT(H, G)$ .
- **[LM ??] For fixed  $H$ , a gap of this algorithm implies the matching UG-hardness.**

# Undirected Analog

- Running time  $2^{O(k^2)}n^{O(1)}$  when  $k = |V_H|$ .
- Undirected Multicut( $H$ ).
  - “Unambiguous”  $F$ : complete  $p$ -partite graph (complement = disjoint cliques).
  - Guess which terminals belong together, and run Multiway Cut
    - Already gives 1.3-approx. [SV13, BSW16] for every  $H$  in time  $2^{O(k \log k)}n^{O(1)}$ .
- Gap instance]
  - Unambiguous  $F \supseteq H$  and  $G$  s.t.  $\text{EarthmoverLP}(F, G) \ll \text{OPT}(H, G)$ .
  - EarthmoverLP is already proved to be optimal for Multiway Cut [MNRS 08]
  - Their proof already proves that the above is best estimation algorithm for Undirected Multicut( $H$ )?

# Undirected Analog



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  - Their proof already proves that the above is best estimation algorithm for Undirected Multicut( $H$ )?

# Global Cut Problems

- [BCKLX 17] Global versions
  - $s$ - $t$  Bicut: Given  $G$  and  $s, t$ , remove min # arcs s.t.  $s \nrightarrow t$  and  $t \nrightarrow s$ .
  - Global Bicut: Given  $G$ , remove min # arcs s.t.  $\exists s, t$  with  $s \nrightarrow t$  and  $t \nrightarrow s$ .
- Undirected Analog
  - 3-way cut: Given  $G$  and  $s, t, u$ , remove min # edges s.t. they are separated.
  - 3-cut : Given  $G$ , remove min # edges s.t.  $\exists s, t, u$  separated.
- 3-way cut: NP-hard. 3-cut: P
- $s$ - $t$  Bicut: 2-hard [CM 17, L 17]. Global Bicut: 1.998-approximation.

# Hardness Framework

- [L 17] First  $\omega(1)$ -hardness for
  - Length-Bounded Cut
  - Shortest Path Interdiction
  - Firefighter (RMFC)
- Length-Control Dictatorship Test
  - Take (some) LP gap instances to UG-hardness.
- More cut problems?
  - General theorem that unifies current results?
  - How to formally unify various cut problems?

# Open Problems

- Flow-Cut LP may be still optimal (save  $2^{O(k^2)}$  time)!
  - $\exists G, H$  s.t.  $LP(H, G) < ALG(H, G)$
  - But maybe  $\max_G \frac{LP(H, G)}{OPT(H, G)} = \max_G \frac{ALG(H, G)}{OPT(H, G)}$  ??
- “Interesting  $H$ ” where we can do much better than  $|E_H|$ -approx.?
  - Multiway Cut, Linear-k-Cut, ???
  - Using the new LP?
- Optimal rounding algorithms?
  - Undirected Multiway Cut [MNRS 08], Min CSP [EVW 13]

Thank you!

