# A structure theorem for Boolean functions with small total influences

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# Influences

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- The influence of the j-th variable on f is

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•  $I_f = \sum_{i=1}^n I_j(f)$  is called the total influence of f.



#### Example

- Let  $X = (\{0,1\}, \mu)$  be the uniform distribution on  $\{0,1\}$ .
- Let  $f: \{0,1\}^n \to \{0,1\}$  be parity

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• Total influence of f is n/2.



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• Total influence  $I_f \leq 2(n-1)/n \approx 2$ .

#### Main Question

What can we say about the structure of functions  $f: X^n \to \{0,1\}$  with  $I_f = O(1)$ ?

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  - 3-SAT exhibits a sharp threshold.
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- Bourgain 2000: Partially extended this to general setting f: X<sup>n</sup> → {0, 1}.



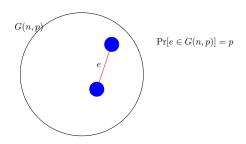
# **Phase Transitions**

## Erdös-Rényi graph

 In early sixties Erdös and Rényi invented the notion of a random graph G(n, p):

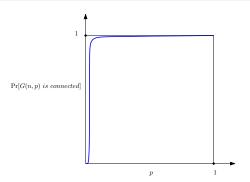
## Erdös-Rényi graph

- In early sixties Erdös and Rényi invented the notion of a random graph G(n, p):
- Every edge is present independently with probability p.



#### **Thresholds**

They observed that some fundamental graph properties such as connectivity exhibit a threshold as *p* increases.



## sharpness of threshold

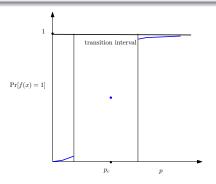
One of the main questions that arises in studying phase transitions is:

• "How sharp is the threshold?"

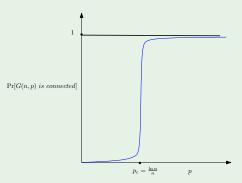
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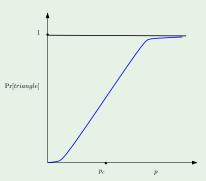
- "How sharp is the threshold?"
- That is how short is the interval in which the transition occurs.



#### Connectivity exhibits a sharp threshold.



Containing a triangle does not exhibit a sharp threshold.



What about more complicated properties such as

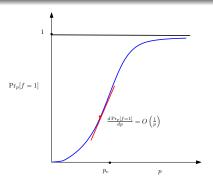
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Is there a general approach to such questions?

#### Observation

If  $f:\{0,1\}^n \to \{0,1\}$  does not exhibit a sharp threshold, then  $\frac{d\Pr_p[f(x)=1]}{dp} = O\left(\frac{1}{p}\right)$ , for some p in the transition interval.



#### Question [Coarse Threshold]

Which functions  $f: \{0,1\}^n \to \{0,1\}$  satisfy  $\frac{d \Pr_p[f(x)=1]}{dp} = O\left(\frac{1}{p}\right)$ ?

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#### Russo-Margulis Lemma

The sharpness of the threshold is controlled by the total influence of the indicator function of the property:

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#### **Question Rephrased**

Which functions  $f:(\{0,1\}^n,\mu_p)\to\{0,1\}$  satisfy  $I_f=O(1)$ ?



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## More general question

What is the structure of the functions  $f: X^n \to \{0, 1\}$  with bounded total influence?

# **Bounded Total Influence**

# Functions with Small Total Influence **Juntas**

The value of  $f(x_1,...,x_n)$  depends on a small set of variables  $\{x_{i_1},...,x_{i_k}\}$ :

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- Juntas have total influence O(1).

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## Theorem (More precisely)

Let  $f: \{0,1\}^n \to \{0,1\}$  have total influence O(1). Then for every  $\epsilon > 0$ , there exists a  $O_{\epsilon}(1)$ -junta  $g: \{0,1\}^n \to \{0,1\}$  such that

$$\Pr[f(x) \neq g(x)] \leq \epsilon$$
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- For the applications in phase transition, the range  $p \lesssim n^{-c}$  is the most interesting case.
  - connectivity
  - satisfiability of 3-SAT
  - 3-colorability of graphs....

# Pseudo-Juntas

$$f: X^n \to \{0, 1\}$$

• Let  $\mathcal{J} = \{J_{\mathcal{S}}\}_{\mathcal{S} \subseteq [n]}$  be a collection of constraints;  $J_{\mathcal{S}} : X^n \to \{0,1\}$  depends on coordinates in  $\mathcal{S}$ .

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 $\mathcal{F}_{\mathcal{J}}$ : Put *x* and *y* in the same part if:

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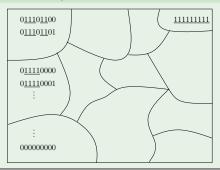
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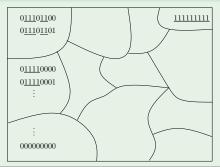
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## Definition (Pseudo-junta)

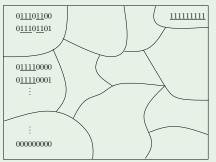
If  $f: X^n \to \{0,1\}$  is measurable w.r.t.  $\mathcal{F}_{\mathcal{J}}$ , then f is called a k-pseudo-junta provided that

 $\mathbb{E}[\text{number of active coordiates of } x] \leq k.$ 



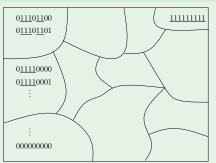
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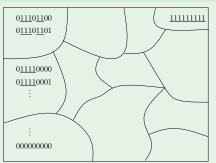
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- Suppose x and y differ only in one coordinate j.
- E.g.  $(\underline{1}, \overline{1}, \overline{1}, 0, 1, 0, 0, \underline{1}, \underline{1})$   $(\underline{1}, \overline{1}, \overline{1}, 0, 0, 0, 0, \underline{1}, \underline{1}).$



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- $j \notin J_{\mathcal{J}}(x) \cup J_{\mathcal{J}}(y) \Leftrightarrow x$  and y are atom-mates.



## Theorem (Direct Theorem)

Let  $f: X^n \to \{0,1\}$  be a k-pseudo-junta. Then  $I_f \leq 2k$ .

$$I_{f} = \sum_{j \in [n]} \Pr[f(x_{1}, \dots, x_{j}, \dots, x_{n}) \neq f(x_{1}, \dots, y_{j}, \dots, x_{n})]$$

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$$\leq \sum_{j \in [n]} \Pr\left[j \in J_{\mathcal{J}}(x_1, \dots, x_j, \dots, x_n)\right] + \Pr\left[j \in J_{\mathcal{J}}(x_1, \dots, y_j, \dots, x_n)\right]$$

$$\leq 2\sum_{j\in [n]}\Pr[j\in J_{\mathcal{J}}(x)]\leq 2\mathbb{E}|J_{\mathcal{J}}(x)|\leq 2k.$$

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# Theorem (Friedgut 2000 - Inverse Theorem for graphs)

If the total influence of a graph property f is O(1) on G(n, p), then f is essentially a pseudo-junta.

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## **Shortcomings**

- It is about graph properties, and the proof heavily relies on symmetries.
- It is only applicable to p-biased distribution.

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Partially extended Friedgut's proof to general  $f: X^n \to \{0,1\}$ .

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- does not tell anything about the global structure of f.

# Main Theorem

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#### Theorem (More precisely:)

Let  $f: X^n \to \{0,1\}$  and  $\epsilon > 0$ 

• There exists a  $\exp(10^{15}\epsilon^{-3}\lceil I_f\rceil^3)$ -pseudo-junta  $h:X^n\to\{0,1\}$  such that

$$\Pr[f(x) \neq h(x)] \leq \epsilon.$$

# **Proof Sketch**

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- $\int F_S dx_i = 0$  for  $i \in S$ .

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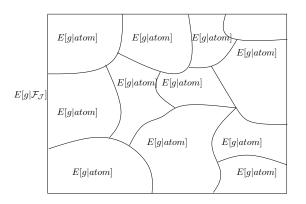
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So

$$f \approx \sum_{S:|S| < k} F_S =: g.$$



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- For  $|S| \le k$ :

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- But we want

$$\int |f - \mathbb{E}[f|\mathcal{F}_{\mathcal{J}}]|^2 = \int \left| \sum (F_{\mathcal{S}} - \mathbb{E}[F_{\mathcal{S}}|\mathcal{F}_{\mathcal{J}}]) \right|^2 \approx 0.$$



Note bounding  $\mathbb{E}[|J_{\mathcal{J}}|]$  is easy:

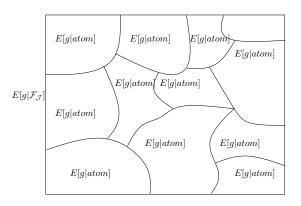
$$\mathbb{E}[|J_{\mathcal{J}}(x)|] \leq \sum |S| \times \Pr[J_{\mathcal{S}}(x) = 1]$$

$$\leq k \sum \int J_{\mathcal{S}}(x)$$

$$\leq k \sum \int \epsilon_1^{-1} |F_{\mathcal{S}}|^2 \leq \epsilon_1^{-1} k = O(1).$$

• We approximated f with  $g := \sum_{|S| \le k} F_S$ .

- We approximated f with  $g := \sum_{|S| < k} F_S$ .
- We need to show  $\|g \mathbb{E}[g|\mathcal{F}_{\mathcal{J}}]\|_2$  is small.



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- We have  $\mathbb{E}[g|\mathcal{F}_{\mathcal{J}}] = \sum_{|S| < k} \mathbb{E}[F_{S}|\mathcal{F}_{\mathcal{J}}].$
- Since  $\mathcal{F}_{\mathcal{J}}$  depends on all coordinates, so does  $\mathbb{E}[F_{\mathcal{S}}|\mathcal{F}_{\mathcal{J}}]$ .
- To remedy this we define some auxiliary  $\sigma$ -algebras  $\mathcal{F}_{\mathcal{S}}$  (activate coordinates only if  $x_{\mathcal{S}}$  activates them, E.g.

$$(\underbrace{1,1,0,1}_{S},1,0,0)$$
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- F<sub>S</sub> depends only on coordinates in S.
- $\mathcal{F}_{\mathcal{S}}$  is coarser than  $\mathcal{F}_{\mathcal{J}}$ .

• Since  $\mathcal{F}_{\mathcal{S}}$  is coarser than  $\mathcal{F}_{\mathcal{J}}$ :

$$\|g - \mathbb{E}[g|\mathcal{F}_{\mathcal{J}}]\|_2^2 \leq \left\|g - \sum \mathbb{E}[F_{\mathcal{S}}|\mathcal{F}_{\mathcal{S}}]\right\|_2^2.$$

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• Since  $\mathcal{F}_{\mathcal{S}}$  depends only on coordinates in  $\mathcal{S}$ :

$$\int \mathbb{E}[F_{\mathcal{S}_1}|\mathcal{F}_{\mathcal{S}_1}]\mathbb{E}[F_{\mathcal{S}_2}|\mathcal{F}_{\mathcal{S}_2}] = 0,$$

if  $S_1 \cap S_2 = \emptyset$ .

## Step IV: Bounding the error

• Since  $\mathcal{F}_{\mathcal{S}}$  is coarser than  $\mathcal{F}_{\mathcal{J}}$ :

$$\|g - \mathbb{E}[g|\mathcal{F}_{\mathcal{J}}]\|_2^2 \le \|g - \sum \mathbb{E}[\mathcal{F}_{\mathcal{S}}|\mathcal{F}_{\mathcal{S}}]\|_2^2.$$

• Since  $\mathcal{F}_{\mathcal{S}}$  depends only on coordinates in  $\mathcal{S}$ :

$$\int \mathbb{E}[F_{S_1}|\mathcal{F}_{S_1}]\mathbb{E}[F_{S_2}|\mathcal{F}_{S_2}] = 0,$$

if  $S_1 \cap S_2 = \emptyset$ .

We get

$$\begin{split} \|g - \mathbb{E}[g|\mathcal{F}_{\mathcal{J}}]\|_2^2 &\lesssim \int \sum |F_S - \mathbb{E}[F_S|\mathcal{F}_S]|^2 \\ &+ \sum_{\substack{S_1, S_2 \in \mathcal{S} \\ S_1 \cap S_2 \neq \emptyset \ S_1 \neq S_2}} \left| \int \mathbb{E}[F_{S_1}|\mathcal{F}_{S_1}] \mathbb{E}[F_{S_2}|\mathcal{F}_{S_2}] \right|. \end{split}$$



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First sum is small by Bourgain's inequality.

$$\begin{split} \|g - \mathbb{E}[g|\mathcal{F}_{\mathcal{J}}]\|_2^2 &\lesssim \int \sum |F_S - \mathbb{E}[F_S|\mathcal{F}_S]|^2 \\ &+ \sum_{\substack{S_1, S_2 \in \mathcal{S} \\ S_1 \cap S_2 \neq \emptyset, S_1 \neq S_2}} \left| \int \mathbb{E}[F_{S_1}|\mathcal{F}_{S_1}] \mathbb{E}[F_{S_2}|\mathcal{F}_{S_2}] \right|. \end{split}$$

- First sum is small by Bourgain's inequality.
- Second term is analyzed by considering  $T := S_1 \cap S_2$ :

$$\begin{split} &\int \mathbb{E}[F_{\mathcal{S}_1}(x_T,\cdot)|\mathcal{F}_{\mathcal{S}_1}]\mathbb{E}[F_{\mathcal{S}_2}(x_T,\cdot)|\mathcal{F}_{\mathcal{S}_2}] = \\ &\int \mathbb{E}[F_{\mathcal{S}_1}(x_T,\cdot)|\mathcal{F}_{\mathcal{S}_1}] \times \int \mathbb{E}[F_{\mathcal{S}_2}(x_T,\cdot)|\mathcal{F}_{\mathcal{S}_2}]. \end{split}$$

$$J_T(y) := \left\{ \begin{array}{ll} 1 & \max_{R \subseteq T} \delta_0^{-2|T \setminus R|} \int \xi_T(y_R, x_{T \setminus R}) dx_{T \setminus R} \geq 1, \\ 0 & \text{otherwise}. \end{array} \right.$$

where

$$\xi_{\mathcal{T}}(y) := \left\{ \begin{array}{ll} 1 & \sum_{R \subseteq \mathcal{T}} \sum_{S \in \mathcal{S}: S \supseteq \mathcal{T}} \int a_S(y_R, x_{S \setminus R}) dx_{S \setminus R} > \epsilon_2, \\ \text{otherwise}. \end{array} \right.$$

where

$$a_{\mathcal{S}}(y) := 2^{3k} \delta^{-2k} \sum_{T \subseteq \mathcal{S}} \int 1_{[|F_{\mathcal{S}}(y_{\mathcal{S}\setminus T}, x_{\mathcal{T}})| > \epsilon_1]} dx_{\mathcal{T}}.$$



Furthermore in the case of general *X*:

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  - $\blacktriangleright \sum \|F_S G_S\|_2^2 \text{ is small.}$
  - $\sum_{|S|\leq k} \|G_S\|_1 = O(1).$

## **Increasing Functions**

### Friedgut 2000

For an increasing graph property f, if  $I_f = O(1)$ , then there exists a small set of coordinates J such that

$$\mathbb{E}[f(x)|x_J=\vec{1}]\geq 1-\epsilon.$$

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If  $I_f = O(1)$  for an increasing  $f: (\{0,1\}^n, \mu_p) \to \{0,1\}$ , then  $\exists \delta > 0$  and a small J such that

$$\mathbb{E}[f(x)|x_J=\vec{1}] \geq \mathbb{E}[f(x)] + \delta.$$

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#### H 2011

Under the above assumptions

$$\mathbb{E}[f(x)|x_J=\vec{1}]\geq 1-\epsilon.$$



## Open problem

### Conjecture[Friedgut]

If  $I_f = O(1)$  for an increasing  $f: (\{0,1\}^n, \mu_p) \to \{0,1\}$ , then

$$f \approx O(1)$$
 – Monotone DNF.

### Conjecture

If  $f: [0,1]^n \to \{0,1\}$  is increasing, and  $I_f = O(1)$ , then there is  $|J| = O_{\epsilon}(1)$  such that either

$$\mathbb{E}[f(x)|x_J=\vec{1}]\geq 1-\epsilon,$$

or

$$\mathbb{E}[f(x)|x_J=\vec{0}]\leq \epsilon.$$



# Thank you!