Differential Privacy and Verification

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Given a program P, is it differentially private?





Given a differentially private program P, does it maintain its accuracy promises? Given a differentially private program P that maintains its accuracy promises, can we guarantee that it is also efficient?

An algorithm

Algorithm 2 DualQuery

Input: Database $D \in \mathbb{R}^{|\mathcal{X}|}$ (normalized) and linear queries $q_1, \ldots, q_k \in \{0, 1\}^{|\mathcal{X}|}$. **Initialize:** Let $\mathcal{Q} = \bigcup_{j=1}^k q_j \cup \overline{q_j}$, Q^1 uniform distribution on \mathcal{Q} ,

$$T = \frac{16\log|\mathcal{Q}|}{\alpha^2}, \qquad \eta = \frac{\alpha}{4}, \qquad s = \frac{48\log\left(\frac{2|\mathcal{X}|T}{\beta}\right)}{\alpha^2}$$

For t = 1, ..., T: Sample *s* queries $\{q_i\}$ from Q according to Q^t . Let $\overline{q} := \frac{1}{s} \sum_i q_i$. Find x^t with $\langle \overline{q}, x^t \rangle \ge \max_x \langle \overline{q}, x \rangle - \alpha/4$. Update: For each $q \in Q$: $Q_q^{t+1} := \exp(-\eta \langle q, x^t - D \rangle) \cdot Q_q^t$. Normalize Q^{t+1} . Output synthetic database $\widehat{D} := \bigcup_{t=1}^T x^t$.



https://github.com/ejgallego/dualquery/

Some issues

- Are the algorithms bug-free?
- Do the implementations respect their specifications?
- Is the system architecture bug-free?
- Is the code efficient?
- Do the optimization preserve privacy and accuracy?
- Is the actual machine code correct?
- Is the full stack attack-resistant?

Outline

- Few more words on program verification,
- Challenges in the verification of differential privacy,
- Few verification methods developed so far,
- Looking forward.





Knight Capital Group







Algorithm 1 An instantiation of the SVT proposed in this paper.	Algorithm 2 SVT in Dwork and Roth 2014 [8].
Input: $D, Q, \Delta, \mathbf{T} = T_1, T_2, \cdots, c.$	Input: D, Q, Δ, T, c .
1: $\epsilon_1 = \epsilon/2$, $\rho = Lap(\Delta/\epsilon_1)$	1: $\epsilon_1 = \epsilon/2, \ \ ho = Lap\left(c\Delta/\epsilon_1 ight)$
2: $\epsilon_2 = \epsilon - \epsilon_1$, count = 0	2: $\epsilon_2 = \epsilon - \epsilon_1$, count = 0
3: for each query $q_i \in Q$ do	3: for each query $q_i \in Q$ do
4: $\nu_i = Lap\left(2c\Delta/\epsilon_2\right)$	4: $ u_i = \text{Lap}\left(2c\Delta/\epsilon_1\right) $
5: if $q_i(D) + \nu_i \ge T_i + \rho$ then	5: if $q_i(D) + \nu_i \ge T + \rho$ then
6: Output $a_i = \top$	6: Output $a_i = \top$, $\rho = \text{Lap}(c\Delta/\epsilon_2)$
7: $\operatorname{count} = \operatorname{count} + 1$, Abort if $\operatorname{count} \ge c$.	7: $\operatorname{count} = \operatorname{count} + 1$, Abort if $\operatorname{count} \ge c$.
8: else	8: else
9: Output $a_i = \bot$	9: Output $a_i = \bot$

Algorithm 3 SVT in Roth's 2011 Lecture Notes [15].	Algorithm 4 SVT in Lee and Clifton 2014 [13].
Input: D, Q, Δ, T, c .	Input: D, Q, Δ, T, c .
1: $\epsilon_1 = \epsilon/2, \ \rho = Lap(\Delta/\epsilon_1),$	1: $\epsilon_1 = \epsilon/4, \ \rho = Lap\left(\Delta/\epsilon_1\right)$
2: $\epsilon_2 = \epsilon - \epsilon_1$, count = 0	2: $\epsilon_2 = \epsilon - \epsilon_1$, count = 0
3: for each query $q_i \in Q$ do	3: for each query $q_i \in Q$ do
4: $\nu_i = Lap\left(c\Delta/\epsilon_2\right)$	4: $ u_i = Lap\left(\Delta/\epsilon_2\right)$
5: if $q_i(D) + \nu_i \ge T + \rho$ then	5: if $q_i(D) + \nu_i \ge T + \rho$ then
6: Output $a_i = q_i(D) + \nu_i$	6: Output $a_i = \top$
7: $\operatorname{count} = \operatorname{count} + 1$, Abort if $\operatorname{count} \ge c$.	7: $\operatorname{count} = \operatorname{count} + 1$, Abort if $\operatorname{count} \ge c$.
8: else	8: else
9: Output $a_i = \bot$	9: Output $a_i = \bot$

Algorithm 5 SVT in Stoddard et al. 2014 [18]	Algorithm 6 SVT in Chen et al. 2015 [1]
Algorithm 5 5 v 1 m Stoduard et al. 2014 [16].	Algorithm 0.5 v T in Chen et al. 2015 [1].
Input: D, Q, Δ, T .	Input: $D, Q, \Delta, \mathbf{T} = T_1, T_2, \cdots$.
1: $\epsilon_1 = \epsilon/2$, $\rho = Lap(\Delta/\epsilon_1)$	1: $\epsilon_1 = \epsilon/2, \ \rho = Lap\left(\Delta/\epsilon_1\right)$
2: $\epsilon_2 = \epsilon - \epsilon_1$	2: $\epsilon_2 = \epsilon - \epsilon_1$
3: for each query $q_i \in Q$ do	3: for each query $q_i \in Q$ do
4: $\nu_i = 0$	4: $ u_i = Lap\left(\Delta/\epsilon_2\right)$
5: if $q_i(D) + \nu_i \ge T + \rho$ then	5: if $q_i(D) + \nu_i \ge T_i + \rho$ then
6: Output $a_i = \top$	6: Output $a_i = \top$
7:	7:
8: else	8: else
9: Output $a_i = \bot$	9: Output $a_i = \bot$

	Alg. 1	Alg. 2	Alg. 3	Alg. 4	Alg. 5	Alg. 6
ϵ_1	$\epsilon/2$	$\epsilon/2$	$\epsilon/2$	$\epsilon/4$	$\epsilon/2$	$\epsilon/2$
Scale of threshold noise ρ	Δ/ϵ_1	$c\Delta/\epsilon_1$	Δ/ϵ_1	Δ/ϵ_1	Δ/ϵ_1	Δ/ϵ_1
Reset ρ after each output of \top (unnecessary)		Yes				
Scale of query noise ν_i	$2c\Delta/\epsilon_2$	$2c\Delta/\epsilon_2$	$c\Delta/\epsilon_1$	Δ/ϵ_2	0	Δ/ϵ_2
Outputting $q_i + \nu_i$ instead of \top (not private)			Yes			
Outputting unbounded \top 's (not private)					Yes	Yes
Privacy Property	ϵ -DP	ϵ -DP	∞ -DP	$\left(\frac{1+6c}{4}\epsilon\right)$ -DP	∞ -DP	∞ -DP

Some successful stories - I

- CompCert a fully verified C compiler,
- Sel4, CertiKOS formal verification of OS kernel
- A formal proof of the Odd order theorem,
- A formal proof of Kepler conjecture (lead by T. Hales).

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Years of work from very specialized researchers!

Some successful stories - II

- Automated verification for Integrated Circuit Design.
- Automated verification for Floating point computations,
- Automated verification of Boeing flight control -Astree,
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The years of work go in the design of the techniques!

Verification trade-offs



What program verification isn't...

- Algorithm design,
- Trial and error,
- Program testing,
- System engineering,
- A certification process.

What program verification can help with...

- Designing languages for non-experts,
- Guaranteeing the correctness of algorithms,
- Guaranteeing the correctness of code,
- Designing automated techniques for guaranteeing differential privacy,
- Help providing tools for certification process.

The challenges of differential privacy

Given $\varepsilon, \delta \ge 0$, a mechanism M: db $\rightarrow O$ is (ε, δ)-differentially private iff $\forall b_1, b_2$: db at distance one and for every S $\subseteq O$: $Pr[M(b_1) \in S] \le exp(\varepsilon) \cdot Pr[M(b_2) \in S] + \delta$

- Relational reasoning,
- Probabilistic reasoning,
- Quantitative reasoning

A 10 thousand ft view on program verification



Work-flow



VCs = Verification Conditions

Semi-decision procedures

- Require a good decomposition of the problem,
- Handle well logical formulas, numerical formulas and their combination,
- Limited support for probabilistic reasoning (usually through decision procedures for counting).

Compositional Reasoning about the privacy budget

Sequential Composition Let M_i be ϵ_i -differentially private $(1 \le i \le k)$. Then $M(x) = (M_1(x), \dots, M_k(x))$ is $\sum_{i=0}^k \epsilon_i$.

- We can reason about DP programs by monitoring the privacy budget,
- If we have basic components for privacy we can just focus on counting,
- It requires a limited reasoning about probabilities,
- This way of reasoning adapt to other compositions.

Iterated - CDF

CDF(X) = number of records with value $\leq X$.

Joe	29	19144	diabets
Bob	48	19146	tumor
Jim	25	34505	flue
Alice	62	19144	diabets
Bill	39	16544	anemia
Sam	61	19144	diabets
•••			





<u>it-CDF</u> (raw : data) (budget : R) (buckets : list) (E: R) : list

{

var agent = new PINQAgentBudget(budget); var db = new PINQueryable<data>(rawdata, agent); foreach (var b in buckets)

b = db.where(y ⇒ y.val ≤ b).noisyCount(E);
yield return b;

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foreach (var b in buckets)

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 $b = db.where(y \Rightarrow y.val \le b).noisyCount(\mathcal{E});$ yield return b;

agent is responsible for the budget

<u>it-CDF</u> (raw : data) (budget : R) (buckets : list) (E: R) : list

var agent = new PINQAgentBudget(budget); var db = new PINQueryable<data>(rawdata, agent); foreach (var b in buckets) b = db.where(y => y.val ≤ b).noisyCount(E); yield return b;

{

raw data are accessed through a PINQueryable

<u>it-CDF</u> (raw : data) (budget : R) (buckets : list) (E: R) : list

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 var agent = new PINQAgentBudget(budget);
 var db = new PINQueryable<data>(rawdata, agent);
 foreach (var b in buckets)

$$b = db.where(y \Rightarrow y.val \leq b).noisyCount(\varepsilon);$$

yield return b;

we have transformations (scaling factor)

<u>it-CDF</u> (raw : data) (budget : R) (buckets : list) (E: R) : list

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 var agent = new PINQAgentBudget(budget);
 var db = new PINQueryable<data>(rawdata, agent);
 foreach (var b in buckets)

$$b = db.where(y \Rightarrow y.val \leq b).noisyCount(\varepsilon);$$

yield return b;

we have transformations (scaling factor) aggregate operations (actual budget consumption)

Enough budget?

<u>it-CDF</u> (raw : data) (budget : R) (buckets : list) (E: R) : list

var agent = new PINQAgentBudget(budget); var db = new PINQueryable<data>(rawdata, agent); foreach (var b in buckets)

{

 $b = db.where(y \Rightarrow y.val \leq b).noisyCount(E);$ yield return b;

We can check local vs global budget Compositional reasoning about sensitivity

$$GS(f) = \max_{v \sim v'} |f(v) - f(v')|$$

- It allows to decompose the analysis/construction of a DP program,
- A metric property of the function (DMNS06),
- It requires a limited reasoning about probabilities,
- Similar worst case reasoning as basic composition.



```
it-CDF (b :[??] data) (buckets : list) : list
{
    case buckets of
    |nil => nil
    |x::xs => size (filter (fun y => y ≤ x) b)))
        :    it-CDF xs b
}
Let's assume |- size : [1]data --o R
```









Reasoning about DP via probabilistic coupling - BGGHS

For two (sub)-distributions $\mu_1, \mu_2 \in \text{Dist}(A)$ we have an **approximate coupling** $\mu_1 C_{\epsilon,\delta}(R) \mu_2$ iff there exists $\mu \in \text{Dist}(A \times A)$ s.t.

• $\mathrm{supp}\mu\subseteq R$

•
$$\pi_i \mu \leq \mu_i$$

•
$$\max_A(\pi_i\mu - e^{\epsilon}\mu_i, \mu_i - e^{\epsilon}\pi_i\mu) \le \delta$$

- Generalize indistinguishability to other relations allowing more general relational reasoning,
- More involved reasoning about probability distances and divergences,
- Preserving the ability to use semi-decision logical and numerical procedures.

pRHL-like languages

CDF example similar to the previous ones

$$b \sim b' \Rightarrow (\underline{\mathsf{itcdf}} \, b \, l \, \epsilon) \, \mathcal{C}_{\epsilon,0}(=) \, (\underline{\mathsf{itcdf}} \, b' \, l \, \epsilon)$$

pRHL-like languages

CDF example similar to the previous ones

Having two copies of the program allows to compare different parts of the same program.

It allows to internalize better the properties of Laplace

$$\left(\underline{\operatorname{Lap}}\left(1/\epsilon\right)v_{1}\right)\,\mathcal{C}_{|k+v_{1}-v_{2}|\epsilon,0}(x_{1}+k=x_{2})\,\left(\underline{\operatorname{Lap}}\left(1/\epsilon\right)v_{2}\right)$$

can be used to assert symbolically several facts about probabilities.

$$\left(\underline{\mathsf{Lap}}\left(1/\epsilon\right)v_{1}\right)\,\mathcal{C}_{|v_{1}-v_{2}|\epsilon,0}(x_{1}=x_{2})\,\left(\underline{\mathsf{Lap}}\left(1/\epsilon\right)v_{2}\right)$$

expresses

$$\left|\log\left(\frac{\Pr(\underline{\mathsf{Lap}}\left(1/\epsilon\right)v_{1}=r)}{\Pr(\underline{\mathsf{Lap}}\left(1/\epsilon\right)v_{2}=r)}\right)\right| \leq |v_{1}-v_{2}|\epsilon$$

 $|v_1 - v_2| \le k \Rightarrow (\underline{\mathsf{Lap}}(1/\epsilon) v_1) \ \mathcal{C}_{2k\epsilon,0}(x_1 + k = x_2) \ (\underline{\mathsf{Lap}}(1/\epsilon) v_2)$

expresses

$$|v_1 - v_2| \le k \Rightarrow \left| \log \left(\frac{\Pr(\underline{\operatorname{Lap}}(1/\epsilon) v_1 = r + k)}{\Pr(\underline{\operatorname{Lap}}(1/\epsilon) v_2 = r)} \right) \right| \le 2k\epsilon$$

 $\left(\underline{\mathsf{Lap}}\left(1/\epsilon\right)v_{1}\right)\,\mathcal{C}_{0,0}(x_{1}-x_{2}=v_{1}-v_{2})\,\left(\underline{\mathsf{Lap}}\left(1/\epsilon\right)v_{2}\right)$

expresses

$$\log\left(\frac{\Pr(\operatorname{Lap}\left(1/\epsilon\right)v_2 + k = r + k)}{\Pr(\operatorname{Lap}\left(1/\epsilon\right)v_2 = r)}\right) \le 0$$

Other works

- Bisimulation based methods (Tschantz&al Xu&al)
- Fuzz with distributed code (Eigner&Maffei)
- Satisfiability modulo counting (Friedrikson&Jha)
- Bayesian Inference (BFGGHS)
- Adaptive Fuzz (Penn)
- Accuracy bounds (BGGHS)
- Continuous models (Sato)
- Lightweight verification injective function argument (Zhang&Kifer)
- Relational symbolic execution for R generating DP counterexamples (Chong&Farina&Gaboardi)
- Formalizing the local model (Ebadi&Sands)
- zCDP (BGHS)

Challenges

• All of these tools are research projects and most of them are usable only by experts.

Can we use them to certify correct a library of basic mechanism?

Which non-expert we should aim for?

Other Challenges

- Are there other fundamental principles that we can use?
- How can we extend them to verify accuracy and efficiency?
- There are several works on the verification of randomness, floating points, SMC, etc. Can we combine the different approaches?
- How can we internalize more involved data models assumptions?
- From benchmarks to certification?