Automatic Resource Bound Analysis and Linear Optimization

Jan Hoffmann

Carnegie Mellon

... of algorithms

... of algorithms

Resource bound analysis

... of algorithms

Resource bound analysis

... of programs / software

Motivation: Why analyze resource usage of programs?

Resource Usage in Safety-Critical Systems

Memory Usage

Timing

Resource Usage in Safety-Critical Systems

Memory Usage



Home > Automotive Design Center > How To Article

Toyota's killer firmware: Bad design and its consequences



On Thursday October 24, 2013, an Oklahoma court ruled against Toyota in a case of unintended acceleration that lead to the death of one the occupants. Central to the trial was the Engine Control Module's (ECM) firmware.

Unintended acceleration in Toyota cars in the US 2005-2009.

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ICE 3 Velaro D delivery delayed by one year because of software performance issues in 2013.

Performance Bugs are Common and Expensive



The System is down at the moment.

We're working to resolve the issue as soon as possible. Please try again later.

Please include the reference ID below if you wish to contact us at 1-800-318-2596 Error from: https%3A//www.healthcare.gov/marketplace/global/en_US/registration% Reference ID: 0.cdc7c117.1380633115.2739dce8

HealthCare.gov debacle has been mainly caused by performance issues.



Google Apps Developer: "Cannot test for performance bugs with regression test".

Software Security





Algorithmic Complexity Attacks

Side-Channel Attacks

Software Security





Algorithmic Complexity Attacks

Side-Channel Attacks



Space/Time Analysis for Cybersecurity (STAC)

October 2014 \$ 53M program Our team: GRAMMATECH **Carnegie Mellon** Yale **WISCONSIN** UNIVERSITY OF WISCONSIN_MADISO

	Computed Bound	Actual Behavior	Performance	
Quick Sort (Integers)	$12n^2 + 14n + 3$	O(n ²)	0.1 s	
Split and Sort	16n ² + 46n + 9	O(n ²)	2.1 s	

Cancel Connect

Static Resource Bound Analysis

Given: A program P

Question: What is the worst-case resource consumption of P as a function of the size of its inputs?

Static Resource Bound Analysis

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Clock cycles, heap space, power, ...

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Not only asymptotic bounds but concrete constant factors.

Automatic Static Resource Bound Analysis

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Question: What is the worst-case resource consumption of P as a function of the size of its inputs?



Not only asymptotic bounds but concrete constant factors.

Automatic Static Resource Bound Analysis

Undecidable problem

Given: A program P

Clock cycles, heap space, power, ...

Question: What is the worst-case resource consumption of P as a function of the size of its inputs?



Research Challenges

Model and predict resource usage at development time.



Source code

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Model and predict resource usage at development time.







Source code





Research Challenges

Help developers to reason about quantitative properties.

- Computer support: Modeling, specification, verification, automation and user interaction
- Compositionally: Track size changes and specify resource-usage of library code
- Language features: Concurrency, higher-order, data structures, ...

Why is this Related?

1. Beyond worst-case analysis of algorithms

- Automation
- Concrete (non-asymptotic) bounds for specific hardware

2. We face similar challenges in resource-bound analysis

"The worst-case behavior doesn't happen in practice."

3. We reduce bound inference to linear optimization

- Linear programs we get are solvable in linear time in practice
- Theoretical worst-case of the algorithm is exponential (simplex)

Outline

- Motivation
- How does automatic resource bound analysis work?
- How well does automatic resource bound analysis work?
 (implementation and experiments)
- What are the properties of the LP instances that we get?





Bird's Eye View

Type-Based Resource Analysis



















Bird's Eye View

Preside a contract of the second state of the

Source Code

Type-Based Resource Analysis





Clear soundness theorem.

Naturally compositional.

Efficient inference via LP solving.

Bird's Eye View

Type-Based Resource Analysis

Idea: Automate Amortized Analysis

- Assign potential functions to data structures
 - States are mapped to non-negative numbers
- Potential pays the resource consumption and the potential at the following program point
- Initial potential is an upper bound

 $\Phi(before) \ge \Phi(after) + cost$ $\bigvee telescoping \bigvee$ $\Phi(initial \ state) \ge \sum cost$

 $\Phi(state) \geq 0$

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Type systems for automatic analysis

- Fix a format of potential functions
- Develop type rules that manipulate potential functions

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 $\Phi(state) \ge 0$ $\Phi(before) \ge \Phi(after) + cost$ $\clubsuit telescoping \clubsuit$ $\Phi(initial \ state) \ge \sum cost$

Potential is given by types.

Example: Append for Persistent Lists

append(x,y)

Heap-space usage is 2n if

- n is the length of list x
- One list element requires two heap cells (data and pointer)
append(x,y)

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```
f(x,y,z) = {
   t = append(x,y);
   append(t,z)
}
```

Heap usage of f(x,y,z) is 2n + 2(n+m) if

- n is the length of list x
- m is the length of list y

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$$f(x,y,z) = \{ append: (L^{4}(int), L^{2}(int)) \xrightarrow{0/0} L^{2}(int) \\ t = append(x,y); \\ append(t,z) \\ \} \qquad append: (L^{2}(int), L^{0}(int)) \xrightarrow{0/0} L^{0}(int)$$

The most general type of append is specialized at call-sites:

append:
$$(L^{q}(int), L^{p}(int)) \xrightarrow{s/t}{} L^{r}(int) | \phi$$
 Linear constraints.

Polynomial Potential Functions

	Linear Potential Functions
User-defined resource metrics (i.e., by tick(q) in the code)	
Naturally compositional : tracks size changes, types are specifications	
Bound inference by reduction to efficient LP solving	
Type derivations prove bounds with respect to the cost semantics	

Phd Thesis: Polynomial Potential Functions

	Linear Potential Functions	Multivariate Polynomial Potential Functions
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Phd Thesis: Polynomial Potential Functions

	For example m*n ² .	
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Phd Thesis: Polynomial Potential Functions

First automatic, type-based resource analysis for polynomial bounds.

t = append(xs,ys);
quicksort(t)

Computed time bound:

$$12m^2 + 24mn + 12n^2 + 14m + 22n + 11$$

t = append(xs,ys); quicksort(t) Computed time bound: $12m^2 + 24mn + 12n^2 + 14m + 22n + 11$

append :
$$((L(int), L(int)), \begin{pmatrix} 6 & 26 & 24 \\ 34 & 24 \\ 24 \end{pmatrix}) \rightarrow (L(int), (3, 26, 24))$$

t = append(xs,ys); quicksort(t) Computed time bound: $12m^2 + 24mn + 12n^2 + 14m + 22n + 11$

append :
$$((L(int), L(int)), \begin{pmatrix} 6 & 26 & 24 \\ 34 & 24 \end{pmatrix}) \rightarrow (L(int), (3, 26, 24))$$

 $6 + 34n + 26m + 24 \binom{n}{2} + 24nm + 24 \binom{m}{2}$

t = append(xs,ys); quicksort(t) Computed time bound: $12m^2 + 24mn + 12n^2 + 14m + 22n + 11$



t = append(xs,ys); quicksort(t) Computed time bound:

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Multivariate Resource Polynomials [POPL'11]

Map data structures to non-negative rational numbers

$$p:\llbracket A
rbracket o \mathbb{Q}_0^+$$

Are non-negative linear combinations of the following base polynomials:

$$\mathcal{P}(Int) = \{a \mapsto 1\}$$
$$\mathcal{P}(A_1, A_2) = \{(a_1, a_2) \mapsto p_1(a_1) \cdot p_2(a_2) \mid p_i \in \mathcal{P}(A_i)\}$$
$$\mathcal{P}(L(A)) = \{[a_1, \dots, a_n] \mapsto \sum_{1 \le j_1 < \dots < j_k \le n} \prod_{i=1}^k p_i(a_{j_i}) \mid k \in \mathbb{N}, p_i \in \mathcal{P}(A)\}$$

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Resource Polynomials: Examples

$$\mathcal{P}(L(A)) = \{[a_1, \ldots, a_n] \mapsto \sum_{1 \leq j_1 < \cdots < j_k \leq n} \prod_{i=1}^k p_i(a_{j_i}) \mid k \in \mathbb{N}, p_i \in \mathcal{P}(A)\}$$
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$$[a_1, \dots, a_n] \mapsto 36 \binom{n}{3} + 16 \binom{n}{2} + 20n + 3$$

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$$([a_1, \ldots, a_n], [b_1, \ldots, b_m]) \mapsto 39mn + 6m + 21n + 19$$

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$$[[a_1^1, \dots, a_{m_1}^1], \dots, [a_1^n, \dots, a_{m_n}^n]] \mapsto 18\binom{n}{2} + 12n + 3 + \sum_{1 \le i < j \le n} 12m_i$$

$$\mathcal{P}(L(A)) = \{[a_1, \ldots, a_n] \mapsto \sum_{1 \leq j_1 < \cdots < j_k \leq n} \prod_{i=1}^k p_i(a_{j_i}) \mid k \in \mathbb{N}, p_i \in \mathcal{P}(A)\}$$

Automatic Computation of the Bounds

- 1. Fix a maximal degree of resource polynomials
- 2. Annotate each type with (yet unknown) coefficients for resource polynomials

Example for degree 2: $((L(int), L(int)), q_{0,0}, q_{1,0}, q_{2,0}, q_{1,1}, q_{0,1}, q_{0,2})$

General case: index system that enumerates resource polynomials

- 3. Extract linear constraints for the coefficients during type inference
- 4. Solve the constraints with an LP solver

Automatic Computation of the Bounds

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Example for degree 2: $((L(int), L(int)), q_{0,0}, q_{1,0}, q_{2,0}, q_{1,1}, q_{0,1}, q_{0,2})$

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- How does automatic resource bound analysis work?
- How well does automatic resource bound analysis work? (Implementation and experiments)
- What are the properties of the LP instances that we get?

Resource Aware ML

- Based on Inria's OCaml compiler
- ~12,000 lines of code (+ ~29,000 loc form the OCaml compiler)
- Currently we use Coin-Or's CLP C interface
- Features:
 - Higher-order functions and polymorphism
 - User defined inductive types
 - Parallel evaluation
 - Side effects
 - User defined (non-monotone) resource metrics
 - Upper and lower bounds

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Experimental Evaluation

	Computed Bound	Actual Behavior	Performance	
Quick Sort (Integers)	12n ² + 14n + 3	O(n²)	0.1 s	
Split and Sort	16n ² + 46n + 9	O(n²)	2.1 s	
Insertion Sort (Strings)	8n²m + 8n² - 8nm + 4n + 3	O(n²m)	0.91 s	
Duplicate Elimination	6n²m + 9n² - 6nm + 3n + 3	O(n²m)	0.97 s	
Longest Common Subsequence	39nm + 6m + 21n + 19	O(nm)	0.36 s	
Matrix Multiplication	28xmn + 32xm + 2x + 14n + 21	O(xmn)	1.96 s	
Breadth-First Matrix Multiplication	2yz + 15ynmx + 14ynm + 15yn + 104n +	51 O(ynmx)	4.98 s	
Dijkstra's Shortest-Path Algorithm	79.5n ² + 31.5n + 38	O(n²)	2.50 s	
In-Place Quick Sort for Arrays	12.25x ² + 52.75x + 3	O(x²)	0.64 s	
M	icro Benchmarks	Evaluation-Step Bounds		



Quick Sort for Integers



Quick Sort for Integers



Longest Common Subsequence



Longest Common Subsequence





Insertion Sort for Strings





Insertion Sort for Strings

Macro Benchmarks

1) OCaml's standard list library list.ml

- Evaluation-step bounds for 47 of 51 top-level functions
- 428 lines of code; 3.2 seconds on a Macbook Pro

2) CompCert C Compiler

- OCaml code extracted from the Coq specification
- Evaluation-step bounds for 13 topmost modules in the dependency graph
- 138 of 164 functions bounded; 2740 lines of code; 21min

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Problems: Modules and untyped code.

138 of 164 functions bounded; 2740 lines of code; 21min

Metric	#Funs	LOC	Time	#Const	#Lin	#Quad	#Cubic	#Poly	#Fail	Asym. Tight
steps	243	3218	72.10s	16	130	60	28	239	4	225
heap	243	3218	70.36s	41	112	60	22	239	4	225
tick	174	2144	64.68s	19	79	53	19	174	0	160
CompC	ert:									
steps	164	2740	1300.91s	32	99	7	0	138	26	137

Macro Benchmarks

How can we make predictions about compiled code?

Machine Learning Cost Models

How to obtain realistic cost metrics for high-level analysis?

- Treat hardware, compiler, and runtime systems as black box
- Select training programs that cover relevant operations
- Use linear regression to obtain average time and memory costs of operations
- Combine time and memory predictions to get a time model for execution with garbage collection

Bound for List Append on x86

1.6 GHz Intel Core i5-5250U processor



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 (Implementation and experiments)
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Constraints we derive are *almost* network-flow problems

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Network-flow constraints:

$$\sum_{i} x_i - \sum_{j} x_j = b$$

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Network-flow constraints:

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Inflow. Outflow.

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Constraints we derive are *almost* network-flow problems



 $I_i \leq x_i \leq u_i$

Constraints we derive are *almost* network-flow problems



Pay for constant cost

$$q = q' + c$$

Account for size changes

$$q_i^\prime = q_i + q_{i+1}$$

Recursive call

$$q = p$$

Conditional branches

$$q \ge p_1 \qquad q \ge p_2$$

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Flow through an edge is used twice.

Network

constraints.

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Network Pay for constant cost constraints. q = q' + c Account for size changes Flow through an edge $q_i' = q_i + q_{i+1}$ is used twice. Recursive call Account for cost q = precursively. Conditional branches

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 Recursive call 	q = p	Acc	count for cost recursively.	
 Conditional branches 				
	$q\geq p_1$ ($q \ge p_2$	Cover cost i branches (p waste)	in both ossible).
Accounting for Size Change

List types:
$$L^{(q_1,...,q_k)}(A)$$

Potential: $\Phi(\ell : L^{(q_1,...,q_k)}) = \sum_{i=1,...,k} q_i \binom{|\ell|}{i}$
Additive shift: $\triangleleft(q_1,...,q_k) = (q_1 + q_2,...,q_{k-1} + q_k,q_k)$

$$\sum_{i=1,...,k} q_i \binom{n+1}{i} = q_1 + \sum_{i=1,...,k-1} q_{i+1} \binom{n}{i} + \sum_{i=1,...,k} q_i \binom{n}{i}$$

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Generation of Linear Constraints

1. It is easy to pass potential to list tails without loss

$$\Phi((x::xs):L^{\vec{q}})+c=\Phi(xs:L^{\triangleleft(\vec{q})})+(q_1+c)$$

2. Pattern: one recursive call and polynomial spill $\Phi((x::xs):L^{\vec{q}}) - \Phi(xs:L^{\vec{q}}) = \Phi(xs:L^{(q_2,...,q_k,0)}) + q_1$

3. It is easy to share potential when aliasing data

 $\Phi(\ell:L^{\vec{q}+\vec{p}}) = \Phi(\ell:L^{\vec{q}}) + \Phi(\ell:L^{\vec{p}})$

Generation of Linear Constraints

$$\lhd (q_1,\ldots,q_k)=(q_1+q_2,\ldots,q_{k-1}+q_k,q_k)$$

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$$\Phi((x::xs): L^{\vec{q}}) + c = \Phi(xs: L^{\triangleleft(\vec{q})}) + (q_1 + c)$$

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 $\Phi(\ell:L^{\vec{q}+\vec{p}}) = \Phi(\ell:L^{\vec{q}}) + \Phi(\ell:L^{\vec{p}})$

f(x) = g(x,x)

Assume cost of g(x,y) is $10|x| \cdot |y|$

Bound for **f** is given as

$$\sum_{i} q_{i} \begin{pmatrix} x \\ i \end{pmatrix}$$

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Need to covert $q|x|^2$ to $\sum_i q_i \begin{pmatrix} x \\ i \end{pmatrix}$

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Constraints:

$$q_1 = 1 \cdot q$$
 $q_2 = 2 \cdot q$ $q_k = 0 \cdot q$ for $k > 2$

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Assume cost of g(x,y) is $10|x| \cdot |y|$

Bound for **f** is given as

$$\sum_{i} q_{i} \begin{pmatrix} x \\ i \end{pmatrix}$$

Need to covert $q|x|^2$ to $\sum_{i} q_i \begin{pmatrix} x \\ i \end{pmatrix}$

Constraints:

$$q_1 = 1 \cdot q$$
 $q_2 = 2 \cdot q$

Coefficients for change of basis.

$$q_k = 0 \cdot q \text{ for } k > 2$$

Constraint Solving in Practice

- LP solving of our constraints is linear in practice
- CLP and CPLEX are similar; Ip_solve is slow (non-linear)
- Large programs (with high degree search space) have around 1 million constraints
- Solving 1 million constraints takes about 1 minute with CLP
- Generating the constraints takes about as much time as solving them

Automatic Amortized Resource Analysis

- Precise: bounds are multivariate resource polynomials
- Efficient: inference via linear programming
- Reliable: formal soundness proof of the bounds
- Verifiable: type derivation is a certificate

Current and future research:

- Non-polynomial bounds
- Garbage collection
- Concurrency
- Better hardware models

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Web interface at <u>http://raml.co</u>