## Uniform Convergence for Learning Binary

## Classifcation

- Given a concept class $\mathcal{C}$, and a training set sampled from $\mathcal{D}$, $\left\{\left(x_{i}, c\left(x_{i}\right)\right) \mid i=1, \ldots, m\right\}$.
- For any $h \in \mathcal{C}$, let $\Delta(c, h)$ be the set of items on which the two classifiers differ: $\Delta(c, h)=\{x \in U \mid h(x) \neq c(x)\}$
- For the realizable case we need a training set (sample) that with probability $1-\delta$ intersects every set in

$$
\{\Delta(c, h) \mid \operatorname{Pr}(\Delta(c, h)) \geq \epsilon\} \quad(\epsilon \text {-net })
$$

- For the unrealizable case we need a training set that with probability $1-\delta$ estimates, within additive error $\epsilon$, every set in

$$
\Delta(c, h)=\{x \in U \mid h(x) \neq c(x)\} \quad(\epsilon \text {-sample }) .
$$

- Under what conditions can a finite sample achieve these requirements?
- What sample size is needed?


## Uniform Convergence Sets

Given a collection $R$ of sets in a universe $X$, under what conditions a finite sample $N$ from an arbitrary distribution $\mathcal{D}$ over $X$, satisfies with probability $1-\delta$,
(1)

$$
\forall r \in R, \quad \underset{\mathcal{D}}{\operatorname{Pr}}(r) \geq \epsilon \Rightarrow r \cap N \neq \emptyset \quad(\epsilon \text {-net })
$$

(2) for any $r \in R$,

$$
\left|\underset{\mathcal{D}}{\operatorname{Pr}}(r)-\frac{|N \cap r|}{|N|}\right| \leq \varepsilon \quad(\epsilon \text {-sample })
$$

## Vapnik-Chervonenkis (VC) - Dimension

$(X, R)$ is called a "range space":

- $X=$ finite or infinite set (the set of objects to learn)
- $R$ is a family of subsets of $X, R \subseteq 2^{X}$.
- For a finite set $S \subseteq X,|S|=m$, define the projection of $R$ on S,

$$
\Pi_{R}(S)=\{r \cap S \mid r \in R\} .
$$

- If $\left|\Pi_{R}(S)\right|=2^{m}$ we say that $R$ shatters $S$.
- The VC-dimension of $(X, R)$ is the maximum size of $S \subseteq X$ that is shattered by $R$. If there is no maximum, the VC-dimension is $\infty$.


## The VC-Dimension of a Collection of Intervals

$C=$ collections of intervals in $[A, B]-$ can shatter 2 point but not 3 . No interval includes only the two red points


The VC-dimension of $C$ is 2

## Collection of Half Spaces in the Plane

$C$ - all half space partitions in the plane. Any 3 points can be shattered:


- Cannot partition the red from the blue points
- The VC-dimension of half spaces on the plane is 3
- The VC-dimension of half spaces in d-dimension space is $\mathrm{d}+1$


## Axis-parallel rectangles on the plane



4 points that define a convex hull can be shattered.
No five points can be shattered since one of the points must be in the convex hull of the other four.

## Convex Bodies in the Plane

- $C$ - all convex bodies on the plane


Any subset of the point can be included in a convex body. The VC-dimension of $C$ is $\infty$

## A Few Examples

- $\mathcal{C}=$ set of intervals on the line. Any two points can be shattered, no three points can be shattered.
- $\mathcal{C}=$ set of linear half spaces in the plane. Any three points can be shattered but no set of 4 points. If the 4 points define a convex hull let one diagonal be 0 and the other diagonal be 1. If one point is in the convex hull of the other three, let the interior point be 1 and the remaining 3 points be 0 .
- $\mathcal{C}=$ set of axis-parallel rectangles on the plane. 4 points that define a convex hull can be shattered. No five points can be shattered since one of the points must be in the convex hull of the other four.
- $\mathcal{C}=$ all convex sets in $R^{2}$. Let $S$ be a set of $n$ points on a boundary of a cycle. Any subset $Y \subset S$ defines a convex set that doesn't include $S \backslash Y$.


## Estimating Probabilities - $\varepsilon$-sample

## Definition

An $\varepsilon$-sample for a range space $(X, R)$, with respect to a probability distribution $\mathcal{D}$ defined on $X$, is a subset $N \subseteq X$ such that, for any $r \in R$,

$$
\left\lvert\, \underset{\mathcal{D}}{\left.\operatorname{Pr}(r)-\frac{|N \cap r|}{|N|} \right\rvert\, \leq \varepsilon .}\right.
$$

## Theorem

Let $(X, \mathcal{R})$ be a range space with VC dimension $d$ and let $\mathcal{D}$ be a probability distribution on $X$. For any $0<\epsilon, \delta<1 / 2$, there is an

$$
m=O\left(\frac{d}{\epsilon^{2}} \ln \frac{d}{\epsilon}+\frac{1}{\epsilon^{2}} \ln \frac{1}{\delta}\right)
$$

such that a random sample from $\mathcal{D}$ of size greater than or equal to $m$ is an $\epsilon$-sample for $X$ with with probability at least $1-\delta$.

## Sauer's Lemma

For a finite set $S \subseteq X, s=|S|$, define the projection of $R$ on $S$,

$$
\Pi_{R}(S)=\{r \cap S \mid r \in R\} .
$$

## Theorem

Let $(X, R)$ be a range space with VC-dimension $d$, for $S \subseteq X$, such that $|S|=m$,

$$
\left|\Pi_{R}(S)\right| \leq \sum_{i=0}^{d}\binom{m}{i}
$$

For $m=d,\left|\Pi_{R}(S)\right|=2^{d}$, and for $m>d \geq 2,\left|\Pi_{R}(S)\right| \leq m^{d}$.

## Proof

- By induction on $d$ and (for each $d$ ) on $n$, obvious for $d=0,1$ with any $n$.
- Assume that the claim holds for all $\left|S^{\prime}\right| \leq n-1$ and $d^{\prime} \leq d-1$ and let $|S|=n$.
- Fix $x \in S$ and let $S^{\prime}=S-\{x\}$.

$$
\begin{aligned}
\left|\Pi_{R}(S)\right| & =|\{r \cap S \mid r \in R\}| \\
\left|\Pi_{R}\left(S^{\prime}\right)\right| & =\left|\left\{r \cap S^{\prime} \mid r \in R\right\}\right| \\
\left|\Pi_{R(x)}\left(S^{\prime}\right)\right| & =\mid\left\{r \cap S^{\prime} \mid r \in R \text { and } x \notin r \text { and } r \cup\{x\} \in R\right\} \mid
\end{aligned}
$$

- For $r_{1} \cap S \neq r_{2} \cap S$ we have $r_{1} \cap S^{\prime}=r_{2} \cap S^{\prime}$ iff $r_{1}=r_{2} \cup\{x\}$, or $r_{2}=r_{1} \cup\{x\}$. Thus,

$$
\left|\Pi_{R}(S)\right|=\left|\Pi_{R}\left(S^{\prime}\right)\right|+\left|\Pi_{R(x)}\left(S^{\prime}\right)\right|
$$

Fix $x \in S$ and let $S^{\prime}=S-\{x\}$.

$$
\begin{aligned}
\left|\Pi_{R}(S)\right| & =|\{r \cap S \mid r \in R\}| \\
\left|\Pi_{R}\left(S^{\prime}\right)\right| & =\left|\left\{r \cap S^{\prime} \mid r \in R\right\}\right| \\
\left|\Pi_{R(x)}\left(S^{\prime}\right)\right| & =\mid\left\{r \cap S^{\prime} \mid r \in R \text { and } x \notin r \text { and } r \cup\{x\} \in R\right\} \mid
\end{aligned}
$$

- The VC-dimension of $\left(S, \Pi_{R}(S)\right)$ is no more than the VC-dimension of $(X, R)$, which is $d$.
- The VC-dimension of the range space $\left(S^{\prime}, \Pi_{R}\left(S^{\prime}\right)\right)$ is no more than the VC-dimension of $\left(S, \Pi_{R}(S)\right)$ and $\left|S^{\prime}\right|=n-1$, thus by the induction hypothesis $\left|\Pi_{R}\left(S^{\prime}\right)\right| \leq \sum_{i=0}^{d}\binom{n-1}{i}$.
- For each $r \in \Pi_{R(x)}\left(S^{\prime}\right)$ the range set $\Pi_{S}(R)$ has two sets: $r$ and $r \cup\{x\}$. If $B$ is shattered by $\left(S^{\prime}, \Pi_{R(x)}\left(S^{\prime}\right)\right)$ then $B \cup\{x\}$ is shattered by $(X, R)$, thus $\left(S^{\prime}, \Pi_{R(x)}\left(S^{\prime}\right)\right)$ has VC-dimension bounded by $d-1$, and $\left|\Pi_{R(x)}\left(S^{\prime}\right)\right| \leq \sum_{i=0}^{d-1}\binom{n-1}{i}$.

$$
\left|\Pi_{R}(S)\right|=\left|\Pi_{R}\left(S^{\prime}\right)\right|+\left|\Pi_{R(x)}\left(S^{\prime}\right)\right|
$$

$$
\begin{aligned}
\left|\Pi_{R}(S)\right| & \leq \sum_{i=0}^{d}\binom{n-1}{i}+\sum_{i=0}^{d-1}\binom{n-1}{i} \\
& =1+\sum_{i=1}^{d}\left(\binom{n-1}{i}+\binom{n-1}{i-1}\right) \\
& =\sum_{i=0}^{d}\binom{n}{i} \leq \sum_{i=0}^{d} \frac{n^{i}}{i!} \leq n^{d}
\end{aligned}
$$

[We use $\binom{n-1}{i-1}+\binom{n-1}{i}=\frac{(n-1)!}{(i-1)!(n-i-1)!}\left(\frac{1}{n-i}+\frac{1}{i}\right)=\binom{n}{i}$ ]
The number of distinct concepts on $n$ elements grows polynomially in the VC-dimension!

## $\varepsilon$-sample

## Definition

An $\varepsilon$-sample for a range space $(X, R)$, with respect to a probability distribution $\mathcal{D}$ defined on $X$, is a subset $N \subseteq X$ such that, for any $r \in R$,

$$
\left\lvert\, \underset{\mathcal{D}}{\left.\operatorname{Pr}(r)-\frac{|N \cap r|}{|N|} \right\rvert\, \leq \varepsilon .}\right.
$$

## Theorem

Let $(X, \mathcal{R})$ be a range space with VC dimension $d$ and let $\mathcal{D}$ be a probability distribution on $X$. For any $0<\epsilon, \delta<1 / 2$, there is an

$$
m=O\left(\frac{d}{\epsilon^{2}} \ln \frac{d}{\epsilon}+\frac{1}{\epsilon^{2}} \ln \frac{1}{\delta}\right)
$$

such that a random sample from $\mathcal{D}$ of size greater than or equal to $m$ is an $\epsilon$-sample for $X$ with with probability at least $1-\delta$.

## Proof of the $\varepsilon$-Sample Theorem

Let $N$ be a set of $m$ independent samples from $X$ according to $\mathcal{D}$.
Let

$$
E_{1}=\left\{\exists r \in R \text { s.t. }\left|\frac{|N \cap r|}{m}-\operatorname{Pr}(r)\right|>\varepsilon\right\} .
$$

We want to show that $\operatorname{Pr}\left(E_{1}\right) \leq \delta$.
Choose another set $T$ of $m$ independent samples from $X$ according to $\mathcal{D}$. Let

$$
E_{2}=\left\{\exists r \in R \text { s.t. }\left|\frac{|N \cap r|}{m}-\operatorname{Pr}(r)\right|>\varepsilon \wedge\left|\operatorname{Pr}(r)-\frac{|T \cap r|}{m}\right| \leq \varepsilon / 2\right\}
$$

Lemma

$$
\operatorname{Pr}\left(E_{2}\right) \leq \operatorname{Pr}\left(E_{1}\right) \leq 2 \operatorname{Pr}\left(E_{2}\right)
$$

$\operatorname{Pr}\left(E_{2}\right) \leq \operatorname{Pr}\left(E_{1}\right) \leq 2 \operatorname{Pr}\left(E_{2}\right)$.

$$
E_{1}=\left\{\exists r \in R \text { s.t. }\left|\frac{|N \cap r|}{m}-\operatorname{Pr}(r)\right|>\varepsilon\right\}
$$

$E_{2}=\left\{\exists r \in R\right.$ s.t. $\left.\left|\frac{|N \cap r|}{m}-\operatorname{Pr}(r)\right|>\varepsilon \wedge\left|\frac{|T \cap r|}{m}-\operatorname{Pr}(r)\right| \leq \varepsilon / 2\right\}$

For $m \geq \frac{24}{\varepsilon}$,

$$
\begin{aligned}
\frac{\operatorname{Pr}\left(E_{2}\right)}{\operatorname{Pr}\left(E_{1}\right)} & =\frac{\operatorname{Pr}\left(E_{1} \cap E_{2}\right)}{\operatorname{Pr}\left(E_{1}\right)}=\operatorname{Pr}\left(E_{2} \mid E_{1}\right) \geq \operatorname{Pr}\left(\left|\frac{|T \cap r|}{m}-\operatorname{Pr}(r)\right| \leq \varepsilon / 2\right) \\
& \geq 1-2 e^{-\varepsilon m / 12} \geq 1 / 2
\end{aligned}
$$

Instead of bounding the probability of

$$
E_{2}=\left\{\exists r \in R \text { s.t. }\left|\frac{|N \cap r|}{m}-\operatorname{Pr}(r)\right|>\varepsilon \wedge\left|\frac{|T \cap r|}{m}-\operatorname{Pr}(r)\right| \leq \varepsilon / 2\right\}
$$

we bound the probability of

$$
E_{2}^{\prime}=\left\{\exists r \in R\left|\|r \cap N|-| r \cap T\| \geq \frac{\epsilon}{2} m\right\}\right.
$$

Since

$$
\left||r \cap N|-\left|r \cap T \| \geq||r \cap N|-m \underset{\mathcal{D}}{\operatorname{Pr}}(r)|-||r \cap T|-m \underset{\mathcal{D}}{\operatorname{Pr}}(r)| \geq \frac{\epsilon}{2} m .\right.\right.
$$

$$
\operatorname{Pr}\left(E_{1}\right) \leq 2 \operatorname{Pr}\left(E_{2}\right) \leq 2 \operatorname{Pr}\left(E_{2}^{\prime}\right) \leq 2(2 m)^{d} e^{-\epsilon^{2} m / 8}
$$

- Since $N$ and $T$ are random samples, we can first choose a random sample of $2 m$ elements $Z=z_{1}, \ldots, z_{2 m}$ and then partition it randomly into two sets of size $m$ each.
- Since $Z$ is a random sample, any partition that is independent of the actual values of the elements generates two random samples.
- We will use the following partition: for each pair of sampled items $z_{2 i-1}$ and $z_{2 i}, i=1, \ldots, m$, with probability $1 / 2$ (independent of other choices) we place $z_{2 i-1}$ in $T$ and $z_{2 i}$ in $N$, otherwise we place $z_{2 i-1}$ in $N$ and $z_{2 i}$ in $T$.

For $r \in R$, let $B_{r}$ be the event

$$
B_{r}=\left\{\|r \cap N|-| r \cap T\| \geq \frac{\varepsilon}{2} m\right\} . \quad E_{2}^{\prime}=\bigcup_{r \in R} B_{r}
$$

The event $B_{r}$ depends only on the random partition of $Z$ into $N$ and $T$. Its doesn't depend on the selection of $Z$.

- If $z_{2 i-1}, z_{2 i} \in r$ or $z_{2 i-1}, z_{2 i} \notin r$ they don't contribute to the value of $\| r \cap N|-|r \cap T||$.
- If just one of the pair $z_{2 i-1}$ and $z_{2 i}$ is in $r$ then their contribution is +1 or -1 with equal probabilities.
- There are at least $\epsilon m / 2$ pairs that contribute +1 or -1 with equal probabilities. Applying the Chernoff bound we have

$$
\operatorname{Pr}\left(E_{r}\right) \leq e^{-\epsilon^{2} m / 8}
$$

$$
\operatorname{Pr}\left(E_{r}\right) \leq e^{-\epsilon^{2} m / 8}
$$

$E_{2}^{\prime}=\left\{\exists r \in R\left|\|r \cap N|-| r \cap T\| \geq \frac{\epsilon}{2} m\right\}=\bigcup_{r \in R} B_{r}\right.$.
Since the projection of $R$ on $T \cup N$ has no more than $(2 m)^{d}$ different ranges, we have

$$
\operatorname{Pr}\left(E_{1}\right) \leq 2 \operatorname{Pr}\left(E_{2}^{\prime}\right) \leq 2(2 m)^{d} e^{-\epsilon^{2} m / 8}
$$

To complete the proof we need to show that for

$$
m \geq \frac{32 d}{\epsilon^{2}} \ln \frac{64 d}{\epsilon^{2}}+\frac{16}{\epsilon^{2}} \ln \frac{1}{\delta}
$$

we have

$$
(2 m)^{d} e^{-\epsilon^{2} m / 8} \leq \delta
$$

To complete the proof we show that for

$$
m \geq \frac{32 d}{\epsilon^{2}} \ln \frac{64 d}{\epsilon^{2}}+\frac{16}{\epsilon^{2}} \ln \frac{1}{\delta}
$$

we have

$$
(2 m)^{d} e^{-\epsilon^{2} m / 8} \leq \delta .
$$

Equivalently, we require

$$
\epsilon^{2} m / 8 \geq \ln (1 / \delta)+d \ln (2 m)
$$

Clearly $\epsilon^{2} m / 16 \geq \ln (1 / \delta)$, since $m>\frac{16}{\epsilon^{2}} \ln \frac{1}{\delta}$.
To show that $\epsilon^{2} m / 16 \geq d \ln (2 m)$ we use:

## Lemma

If $y \geq x \ln x>e$, then $\frac{2 y}{\ln y} \geq x$.

## Proof.

For $y=x \ln x$ we have $\ln y=\ln x+\ln \ln x \leq 2 \ln x$. Thus

$$
\frac{2 y}{\ln y} \geq \frac{2 x \ln x}{2 \ln x}=x
$$

Differentiating $f(y)=\frac{\ln y}{2 y}$ we find that $f(y)$ is monotonically decreasing when $y \geq x \ln x \geq e$, and hence $\frac{2 y}{\ln y}$ is monotonically increasing on the same interval, proving the lemma.

Let $y=2 m \geq \frac{64 d}{\epsilon^{2}} \ln \frac{64 d}{\epsilon^{2}}$ and $x=\frac{64 d}{\epsilon^{2}}$, we have $\frac{4 m}{\ln (2 m)} \geq \frac{64 d}{\epsilon^{2}}$, so $\frac{\epsilon^{2} m}{16} \geq d \ln (2 m)$ as required.

Application: Unrealizable (Agnostic) Learning

- We are given a training set $\left\{\left(x_{1}, c\left(x_{1}\right)\right), \ldots,\left(x_{m}, c\left(x_{m}\right)\right)\right\}$, and a concept class $\mathcal{C}$
- No hypothesis in the concept class $\mathcal{C}$ is consistent with all the training set $(c \notin \mathcal{C})$.
- Relaxed goal: Let $c$ be the correct concept. Find $c^{\prime} \in \mathcal{C}$ such that

$$
\operatorname{Pr}_{\mathcal{D}}\left(c^{\prime}(x) \neq c(x)\right) \leq \inf _{h \in \mathcal{C}} \operatorname{Pr}(h(x) \neq c(x))+\epsilon .
$$

- An $\epsilon / 2$-sample of the range space $\left(X, \Delta\left(c, c^{\prime}\right)\right)$ gives enough information to identify an hypothesis that is within $\epsilon$ of the best hypothesis in the concept class.
- The range spaces $(X, \mathcal{C})$ and $\left(X, \Delta\left(c, c^{\prime}\right)\right)$ have the same VC-dimension.


## Uniform Convergence

## Definition

A range space $(X, \mathcal{R})$ has the uniform convergence property if for every $\epsilon, \delta>0$ there is a sample size $m=m(\epsilon, \delta)$ such that for every distribution $\mathcal{D}$ over $X$, if $S$ is a random sample from $\mathcal{D}$ of size $m$ then, with probability at least $1-\delta, S$ is an $\epsilon$-sample for $X$ with respect to $\mathcal{D}$.

## Theorem

The following three conditions are equivalent:
(1) A concept class $\mathcal{C}$ over a domain $X$ is agnostic PAC learnable.
(2) The range space $(X, \mathcal{C})$ has the uniform convergence property.
(3) The range space $(X, \mathcal{C})$ has a finite VC dimension.

## Is VC-Dimension "Just a Theory"?

Two issues:

- Hard to prove an efficient bound on VC-dimension
- VC-dimension is a "worst case" bound

A quick example:

- Very easy to compute bound on VC-dimension
- Better than union bound
- Not a machine learning problem


## Frequent Itemsets Mining (FIM)

Frequent Itemsets Mining: classic data mining problem with many applications. Settings:

Dataset $\mathcal{D}$
bread, milk bread milk, eggs bread, milk, apple bread, milk, eggs

Each line is a transaction, made of items from an alphabet $\mathcal{I}$
An itemset is a subset of $\mathcal{I}$. E.g., the itemset \{bread,milk\}
The frequency $f_{\mathcal{D}}(A)$ of $A \subseteq \mathcal{I}$ in $\mathcal{D}$ is the fraction of transactions of $\mathcal{D}$ that $A$ is a subset of.
E.g., $f_{\mathcal{D}}(\{$ bread, milk $\})=3 / 5=0.6$

Problem: Frequent Itemsets Mining (FIM)
Given $\theta \in[0,1]$ find (i.e., mine) all itemsets $A \subseteq \mathcal{I}$ with $f_{\mathcal{D}}(A) \geq \theta$
I.e., compute the set $\operatorname{FI}(\mathcal{D}, \theta)=\left\{A \subseteq \mathcal{I}: f_{\mathcal{D}}(A) \geq \theta\right\}$

FI mining algorithms (Apriori, FP-Growth, ...) require significant computation time and space ( $\geq$ quadratic in number of transactions). What can be done with a sample?

## What can we get with a Union Bound?

For any itemset $A$, the number of transactions that include $A$ is distributed

$$
|\mathcal{S}| f_{\mathcal{S}}(A) \sim \operatorname{Binomial}\left(|\mathcal{S}|, f_{\mathcal{D}}(A)\right)
$$

Applying Chernoff bound

$$
\operatorname{Pr}\left(\left|f_{\mathcal{S}}(A)-f_{\mathcal{D}}(A)\right|>\varepsilon / 2\right) \leq 2 e^{-|\mathcal{S}| \varepsilon^{2} / 12}
$$

We then apply the union bound over all the itemsets to obtain uniform convergence

There are $2^{|\mathcal{I}|}$ itemsets, a priori. We need

$$
2 e^{-|\mathcal{S}| \varepsilon^{2} / 12} \leq \delta / 2^{|\mathcal{I}|}
$$

Thus

$$
|\mathcal{S}| \geq \frac{12}{\varepsilon^{2}}\left(|\mathcal{I}|+\ln 2+\ln \frac{1}{\delta}\right)
$$

Assume that we have a bound $\ell$ on the maximum transaction size.

There are $\sum_{i \leq \ell}\binom{|\mathcal{I}|}{i} \leq|\mathcal{I}|^{\ell}$ possible itemsets. We need

$$
2 e^{-|\mathcal{S}| \varepsilon^{2} / 12} \leq \delta /|\mathcal{I}|^{\ell}
$$

Thus,

$$
|\mathcal{S}| \geq \frac{12}{\varepsilon^{2}}\left(\ell \log |\mathcal{I}|+\ln 2+\ln \frac{1}{\delta}\right)
$$

The sample size still depends on $|\mathcal{I}|$, which can be very large - all products sold by Amazon, all the pages on the Web, ...

Can we have a smaller sample size?

## How do we get a smaller sample size?

[Riondato and U. 2014, 2015]: Let's use VC-dimension!

- The domain is the dataset $\mathcal{D}$ (set of transactions)
- For each itemset $A \subseteq 2^{\mathcal{I}}$ we have the set of transactions that contain A

$$
\mathcal{T}_{A}=\{\tau \in \mathcal{D}: A \subseteq \tau\}
$$

- We we need to estimate the probabilities (sizes) of all ranges in the range space

$$
\left(\mathcal{D},\left\{\mathcal{T}_{A}, A \subseteq 2^{\mathcal{I}}\right\}\right)
$$

We need an efficient-to-compute upper bound to the VC-dimension

## How do we bound the VC-dimension?

## Definition

The $d$-index of a dataset $\mathcal{D}$ is the maximum integer $d$ such that $\mathcal{D}$ contains at least $d$ different transactions with at least $d$ items

Example: The following dataset has d-index 3

| bread | beer | milk | coffee |
| :--- | :--- | :--- | :--- |
| chips | coke | pasta |  |
| bread | coke | chips |  |
| milk | coffee |  |  |
| pasta | milk |  |  |

It can be computed easily with a single scan of the dataset

## Theorem

The VC-dimension of $\mathcal{D}$ is bounded by the $d$-index of $\mathcal{D}$

## How do we prove the bound?

Theorem: The VC-dimension is less or equal to the d -index $d$ of $\mathcal{D}$
Proof:

- Let $\ell>d$ and assume it is possible shatter a set $T \subseteq \mathcal{D}$ with $|T|=\ell$.
- Then any $\tau \in T$ appears in at least $2^{\ell-1}$ ranges $\mathcal{T}_{A}$ (there are $2^{\ell-1}$ subsets of $T$ containing $\tau$ )
- But any $\tau$ only appears in the ranges $\mathcal{T}_{A}$ such that $A \subseteq \tau$. So it appears in $2^{|\tau|}-1$ ranges
- From the definition of $d, T$ must contain a transaction $\tau^{*}$ of length $\left|\tau^{*}\right|<\ell$
- This implies $2^{\left|\tau^{*}\right|}-1<2^{\ell-1}$, so $\tau^{*}$ can not appear in $2^{\ell-1}$ ranges
- Then $T$ can not be shattered.


## How good is the bound?

## Definition

The $d$-index of a dataset $\mathcal{D}$ is the maximum integer $d$ such that $\mathcal{D}$ contains at least $d$ different transactions with at least $d$ items

If all transactions have exactly $\ell$ elements, then $d=\ell$.

If we have $n$ transactions, the largest transaction has $\ell$ elements, and the number of elements in a transaction follows a power law distribution

$$
\operatorname{Pr}(X \geq x) \sim c x^{-\alpha}, \quad \text { for } \alpha>1
$$

then $d$ satisfies $\operatorname{Pr}(X \geq d) \sim \frac{d}{n}$, and $\ell$ satisfies $\operatorname{Pr}(X \geq \ell) \sim \frac{1}{n}$, which gives,

$$
d \sim \ell^{\frac{\alpha}{1+\alpha}}
$$

## Frequent Itemset Estimation Using VC-dimension

The VC-dimension is bounded by the maximum $d$ such that $\mathcal{D}$ contains at least $d$ different transactions with at least $d$ items.

Sample size

$$
|S|=O\left(\frac{d}{\epsilon^{2}} \ln \frac{d}{\epsilon}+\frac{1}{\epsilon^{2}} \ln \frac{1}{\delta}\right)
$$



Figure: Frequent itemsets: Sample size based on VC-dimension vs. union bound

