

Lower Bounds for Problems Parameterized by Clique-width

Petr A. Golovach¹

¹Department of Informatics, University of Bergen

Satisfiability Lower Bounds and Tight Results for
Parameterized and Exponential-Time Algorithms
Berkeley, November 6, 2015

The talk is based on the following papers:

- 1 F. V. Fomin, P. A. Golovach, D. Lokshtanov, and S. Saurabh, Almost Optimal Lower Bounds for Problems Parameterized by Clique-Width. *SIAM J. Comput.* 43(5): 1541-1563 (2014)
- 2 H. Broersma, P. A. Golovach, and V. Patel, Tight complexity bounds for FPT subgraph problems parameterized by the clique-width. *Theor. Comput. Sci.* 485: 69-84 (2013)

Outline

- 1 **Introduction**
 - Clique-width
 - Our results
- 2 **Upper bounds**
- 3 **Lower bounds**
- 4 **Edge Dominating Set**
- 5 **Double parameterization**
- 6 **Conclusion and open problems**

Clique-width

Let G be a graph, and let t be a positive integer.

Clique-width

Let G be a graph, and let t be a positive integer.

A t -graph is a graph whose vertices are labeled by integers from $\{1, 2, \dots, t\}$.

Clique-width

Let G be a graph, and let t be a positive integer.

A **t -graph** is a graph whose vertices are labeled by integers from $\{1, 2, \dots, t\}$.

We call the t -graph consisting of exactly one vertex v labeled by some integer i from $\{1, 2, \dots, t\}$ an **initial t -graph**.

Clique-width

The **clique-width** $\text{cwd}(G)$ is the smallest integer t such that G can be constructed by means of repeated application of the following four operations:

Clique-width

The **clique-width** $\text{cwd}(G)$ is the smallest integer t such that G can be constructed by means of repeated application of the following four operations:

- construction of an initial t -graph with vertex v labeled by i (denoted by $i(v)$),

Clique-width

The **clique-width** $\text{cwd}(G)$ is the smallest integer t such that G can be constructed by means of repeated application of the following four operations:

- construction of an initial t -graph with vertex v labeled by i (denoted by $i(v)$),
- disjoint union (denoted by \oplus),

Clique-width

The **clique-width** $\text{cwd}(G)$ is the smallest integer t such that G can be constructed by means of repeated application of the following four operations:

- construction of an initial t -graph with vertex v labeled by i (denoted by $i(v)$),
- disjoint union (denoted by \oplus),
- relabel: changing the labels of each vertex labeled i to j (denoted by $\rho_{i \rightarrow j}$), and

Clique-width

The **clique-width** $\text{cwd}(G)$ is the smallest integer t such that G can be constructed by means of repeated application of the following four operations:

- construction of an initial t -graph with vertex v labeled by i (denoted by $i(v)$),
- disjoint union (denoted by \oplus),
- relabel: changing the labels of each vertex labeled i to j (denoted by $\rho_{i \rightarrow j}$), and
- join: connecting all vertices labeled by i with all vertices labeled by j by edges (denoted by $\eta_{i,j}$).

Clique-width

An **expression tree** of a graph G is a rooted tree T :

Clique-width

An **expression tree** of a graph G is a rooted tree T :

- the nodes of T are of four types: i , \oplus , η and ρ ;

Clique-width

An **expression tree** of a graph G is a rooted tree T :

- the nodes of T are of four types: i , \oplus , η and ρ ;
- **introduce** nodes $i(v)$ are leaves of T for initial t -graphs with vertices v , which are labeled i ;

Clique-width

An **expression tree** of a graph G is a rooted tree T :

- the nodes of T are of four types: i , \oplus , η and ρ ;
- **introduce** nodes $i(v)$ are leaves of T for initial t -graphs with vertices v , which are labeled i ;
- a **union** node \oplus stands for a disjoint union of graphs associated with its children;

Clique-width

An **expression tree** of a graph G is a rooted tree T :

- the nodes of T are of four types: i , \oplus , η and ρ ;
- **introduce** nodes $i(v)$ are leaves of T for initial t -graphs with vertices v , which are labeled i ;
- a **union** node \oplus stands for a disjoint union of graphs associated with its children;
- a **relabel** node $\rho_{i \rightarrow j}$ for the t -graph resulting from the relabeling operation $\rho_{i \rightarrow j}$ applied to the child;

Clique-width

An **expression tree** of a graph G is a rooted tree T :

- the nodes of T are of four types: i , \oplus , η and ρ ;
- **introduce** nodes $i(v)$ are leaves of T for initial t -graphs with vertices v , which are labeled i ;
- a **union** node \oplus stands for a disjoint union of graphs associated with its children;
- a **relabel** node $\rho_{i \rightarrow j}$ for the t -graph resulting from the relabeling operation $\rho_{i \rightarrow j}$ applied to the child;
- a **join** node $\eta_{i,j}$ for the t -graph resulting from the join operation $\eta_{i,j}$ applied to the child;

Clique-width

An **expression tree** of a graph G is a rooted tree T :

- the nodes of T are of four types: i , \oplus , η and ρ ;
- **introduce** nodes $i(v)$ are leaves of T for initial t -graphs with vertices v , which are labeled i ;
- a **union** node \oplus stands for a disjoint union of graphs associated with its children;
- a **relabel** node $\rho_{i \rightarrow j}$ for the t -graph resulting from the relabeling operation $\rho_{i \rightarrow j}$ applied to the child;
- a **join** node $\eta_{i,j}$ for the t -graph resulting from the join operation $\eta_{i,j}$ applied to the child;
- the graph G is isomorphic to the graph associated with the root of T (with all labels removed).

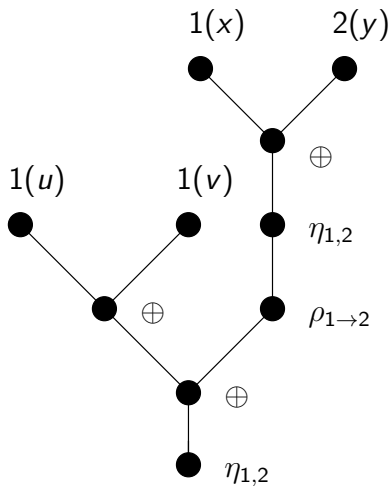
Clique-width

An **expression tree** of a graph G is a rooted tree T :

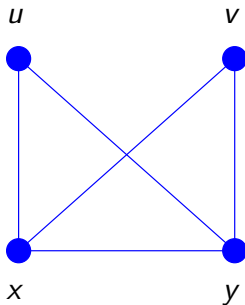
- the nodes of T are of four types: i , \oplus , η and ρ ;
- **introduce** nodes $i(v)$ are leaves of T for initial t -graphs with vertices v , which are labeled i ;
- a **union** node \oplus stands for a disjoint union of graphs associated with its children;
- a **relabel** node $\rho_{i \rightarrow j}$ for the t -graph resulting from the relabeling operation $\rho_{i \rightarrow j}$ applied to the child;
- a **join** node $\eta_{i,j}$ for the t -graph resulting from the join operation $\eta_{i,j}$ applied to the child;
- the graph G is isomorphic to the graph associated with the root of T (with all labels removed).

The **width** of the tree T is the number of different labels appearing in T .

Clique-width



Expression tree



Clique-width

Theorem (Courcelle, Makowsky, and Rotics, 2000)

*All problems expressible in MSO_1 -logic are **fixed parameter tractable** (FPT), when parameterized by the clique-width of the input graph. Or in other words, any problem expressible in MSO_1 -logic can be solved, for graphs of clique-width at most t , in time $f(t) \cdot |I|^{O(1)}$, where $|I|$ is the size of the input and f is a computable function depending on the parameter t only.*

Our results

We obtain the asymptotically tight bounds for **MAX-CUT** and **EDGE DOMINATING SET** by showing that both problems

Our results

We obtain the asymptotically tight bounds for **MAX-CUT** and **EDGE DOMINATING SET** by showing that both problems

- cannot be solved in time $f(t)n^{o(t)}$, unless ETH collapses; and

Our results

We obtain the asymptotically tight bounds for **MAX-CUT** and **EDGE DOMINATING SET** by showing that both problems

- cannot be solved in time $f(t)n^{o(t)}$, unless ETH collapses; and
- can be solved in time $n^{O(t)}$,

where f is an arbitrary function of t , on input of size n and clique-width at most t .

Our results

We obtain the asymptotically tight bounds for **MAX-CUT** and **EDGE DOMINATING SET** by showing that both problems

- cannot be solved in time $f(t)n^{o(t)}$, unless ETH collapses; and
- can be solved in time $n^{O(t)}$,

where f is an arbitrary function of t , on input of size n and clique-width at most t .

Similar results can be obtained for some variants of these problems, e.g., for **MAXIMUM (MINIMUM) BISECTION**.

Our results

We give tight algorithmic lower and upper bounds for some double-parameterized graph problems when the clique-width of the input graph is one of the parameters. We prove the following for n -vertex graphs G of clique-width at most t ,

Our results

We give tight algorithmic lower and upper bounds for some double-parameterized graph problems when the clique-width of the input graph is one of the parameters. We prove the following for n -vertex graphs G of clique-width at most t ,

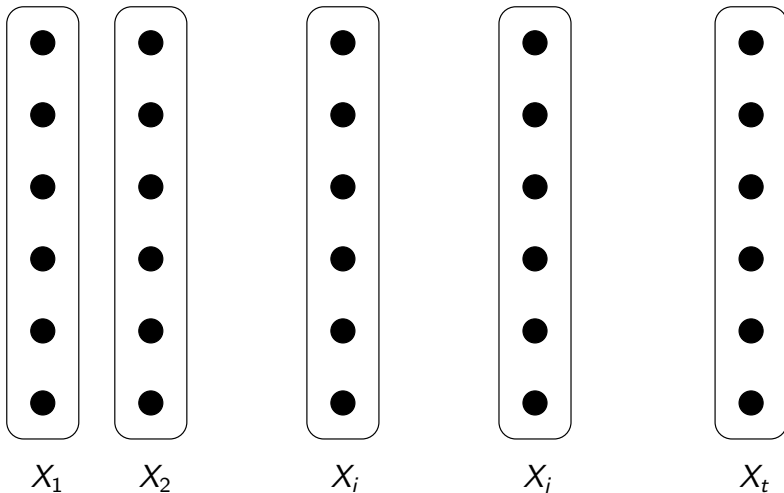
- The **DENSE (SPARSE) k -SUBGRAPH** problem, can be solved in time $k^{O(t)} \cdot n$, but it cannot be solved in time $2^{o(t \log k)} \cdot n^{O(1)}$ unless ETH fails.

Our results

We give tight algorithmic lower and upper bounds for some double-parameterized graph problems when the clique-width of the input graph is one of the parameters. We prove the following for n -vertex graphs G of clique-width at most t ,

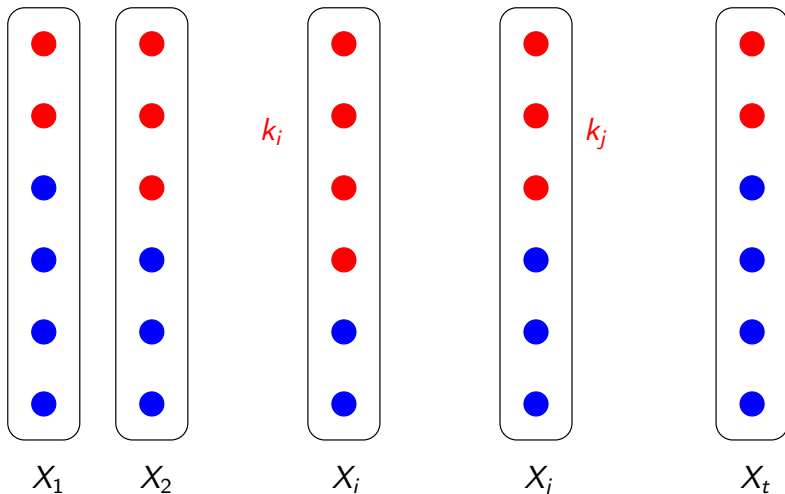
- The **DENSE (SPARSE) k -SUBGRAPH** problem, can be solved in time $k^{O(t)} \cdot n$, but it cannot be solved in time $2^{o(t \log k)} \cdot n^{O(1)}$ unless ETH fails.
- The **d -Regular Induced Subgraph** problem, can be solved in time $d^{O(t)} \cdot n$, but it cannot be solved in time $2^{o(t \log d)} \cdot n^{O(1)}$ unless ETH fails.

Algorithmic upper bound for Max-Cut



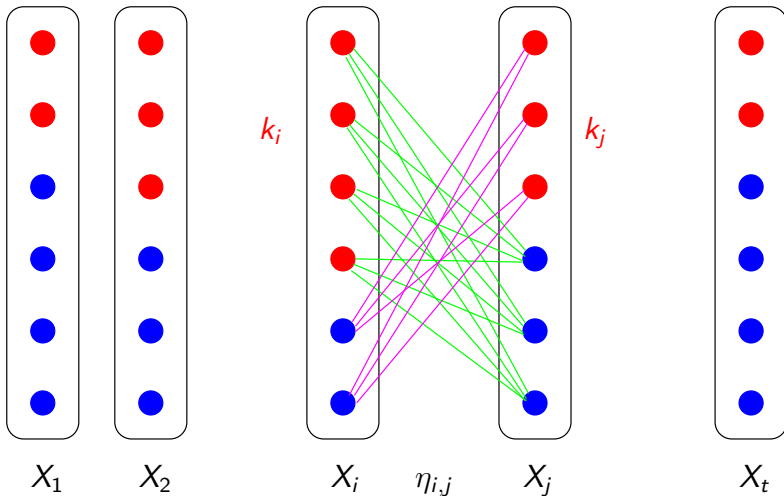
Partial solution for a node of the expression tree

Algorithmic upper bounds for Max-Cut



Partial solution for a node of the expression tree

Algorithmic upper bounds for Max-Cut



Partial solution for a node of the expression tree

Algorithmic lower bounds

Theorem (Cai and Juedes 2001, Downey et al. 2003, Chen et al. 2006)

There is no algorithm for k -CLIQUE (finding a clique of size k) running in time $f(k)n^{o(k)}$ unless ETH fails.

Algorithmic lower bounds

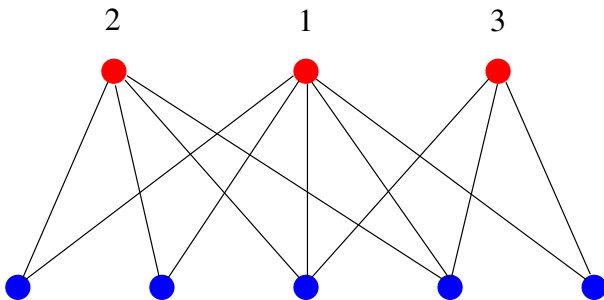
Theorem (Cai and Juedes 2001, Downey et al. 2003, Chen et al. 2006)

*There is no algorithm for **k -CLIQUE** (finding a clique of size k) running in time $f(k)n^{o(k)}$ unless ETH fails.*

Corollary

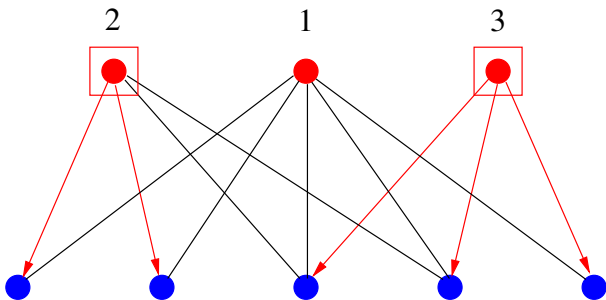
*There is no algorithm for **MULTICOLORED k -CLIQUE** (finding a clique of size k in a k -partite graph) running in time $f(k)n^{o(k)}$ unless ETH fails.*

Capacitated Domination



Red-blue Capacitated Dominating Set

Capacitated Domination



Red-blue Capacitated Dominating Set

Capacitated Domination

Problem (Red-Blue CDS)

Input: *A graph G with a partition (R, B) of $V(G)$, a capacity function $c: R \rightarrow \mathbb{N}$ and a positive integer k .*

Question: *Is there a capacitated dominating set $S \subseteq R$ of size at most k ?*

Capacitated Domination

Problem (Red-Blue CDS)

Input: *A graph G with a partition (R, B) of $V(G)$, a capacity function $c: R \rightarrow \mathbb{N}$ and a positive integer k .*

Question: *Is there a capacitated dominating set $S \subseteq R$ of size at most k ?*

RED-BLUE SATURATED CDS: each vertex $v \in S$ is assigned exactly $c(v)$ neighbors to dominate.

Capacitated Domination

Problem (Red-Blue CDS)

Input: *A graph G with a partition (R, B) of $V(G)$, a capacity function $c: R \rightarrow \mathbb{N}$ and a positive integer k .*

Question: *Is there a capacitated dominating set $S \subseteq R$ of size at most k ?*

RED-BLUE SATURATED CDS: each vertex $v \in S$ is assigned exactly $c(v)$ neighbors to dominate.

RED-BLUE EXACT SATURATED CDS: a variant of **Red-Blue Saturated CDS**, where $|S| = k$.

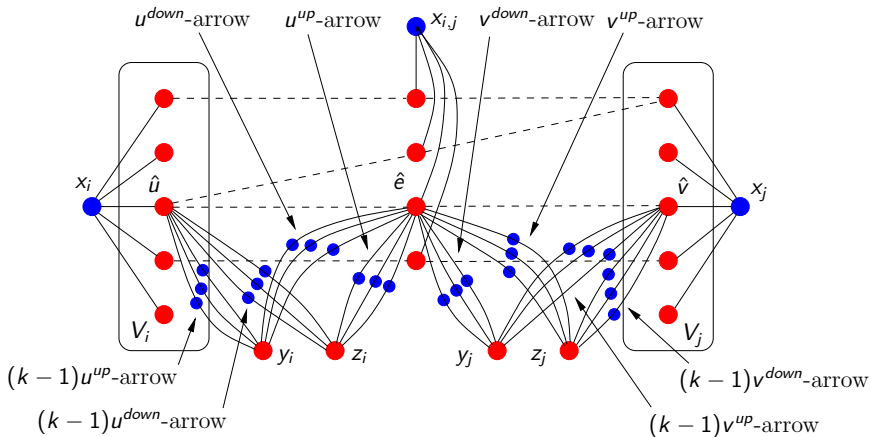
Algorithmic lower bounds

Theorem

There is no algorithm for RED-BLUE CDS (RED-BLUE SATURATED CDS, RED-BLUE EXACT SATURATED CDS) running in time $f(t)n^{o(t)}$ unless ETH fails, where t is the feedback vertex number of an input graph even if the input restricted to graphs G such that

- *every minimum feedback vertex set X is independent, and*
- *only leaves of the forest $G - X$ are adjacent to X and each leaf is adjacent to exactly one vertex of X .*

Algorithmic lower bounds



Reduction for RED-BLUE CDS

Algorithmic lower bounds

Corollary

There is no algorithm for RED-BLUE CDS (RED-BLUE SATURATED CDS, RED-BLUE EXACT SATURATED CDS) running in time $f(t)n^{o(t)}$ unless ETH fails, where t is the clique-width of an input graph/clique-width of the incidence graph of an input graph, even if an expression tree (clique-decomposition) of width at most t is given.

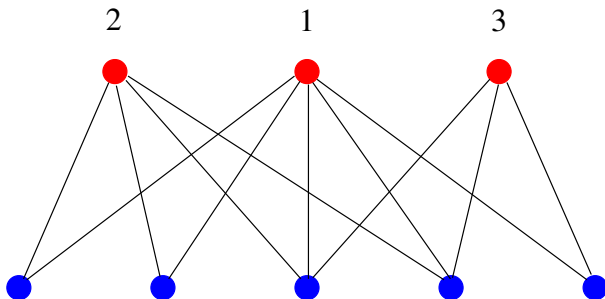
Lower bound for Edge Dominating Set

Theorem

EDGE DOMINATING SET cannot be solved in time $f(t) \cdot n^{o(t)}$ unless the ETH fails even if an expression tree (clique-decomposition) of width at most t is given.

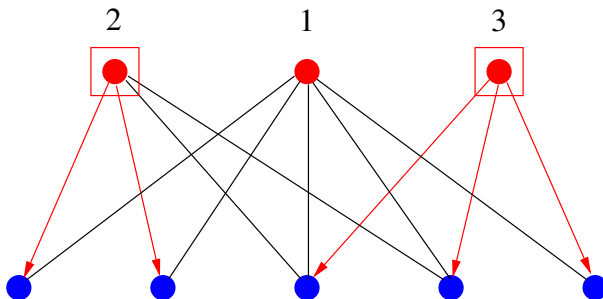
The idea of reduction

Consider an instance of RED-BLUE EXACT SATURATED CDS.



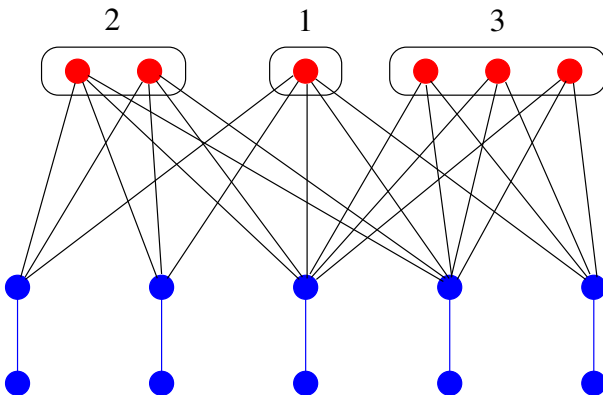
The idea of reduction

Consider an instance of **RED-BLUE EXACT SATURATED CDS**.



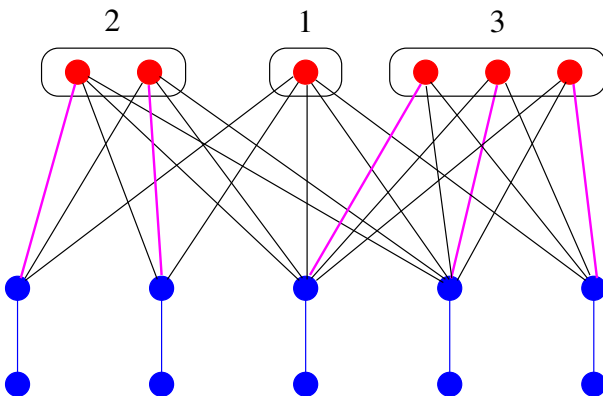
The idea of reduction

Consider an instance of **RED-BLUE EXACT SATURATED CDS**.

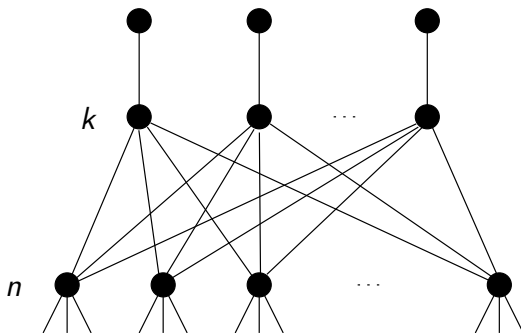


The idea of reduction

Consider an instance of RED-BLUE EXACT SATURATED CDS.

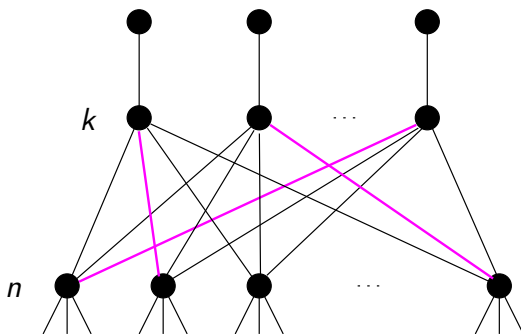


The idea of reduction



Selection gadget

The idea of reduction



Selection gadget

Double parameterization

Theorem (Lokshtanov, Marx, and Saurabh, 2011)

The $k \times k$ -CLIQUE problem (the variant of MULTICOLORED k -CLIQUE where all sets of the k -partition have size k) cannot be solved in time $2^{o(k \log k)} \cdot n^{O(1)}$, where n is the number of vertices of the input graph G , unless ETH fails.

Double parameterization

Theorem (Lokshtanov, Marx, and Saurabh, 2011)

The $k \times k$ -CLIQUE problem (the variant of MULTICOLORED k -CLIQUE where all sets of the k -partition have size k) cannot be solved in time $2^{o(k \log k)} \cdot n^{O(1)}$, where n is the number of vertices of the input graph G , unless ETH fails.

Theorem

The DENSE (SPARSE) k -SUBGRAPH problem, can be solved in time $k^{O(t)} \cdot n$, but it cannot be solved in time $2^{o(t \log k)} \cdot n^{O(1)}$ unless ETH fails.

Open problems

- Is it possible to obtain tight bounds for the aforementioned problems parameterized by the **rank-width** of an input graph?

Open problems

- Is it possible to obtain tight bounds for the aforementioned problems parameterized by the **rank-width** of an input graph?
- Is it possible to give tight algorithmic upper and lower bounds for **HAMILTONIAN CYCLE** when parameterized by the clique-width of the input graph?

Open problems

- Is it possible to obtain tight bounds for the aforementioned problems parameterized by the **rank-width** of an input graph?
- Is it possible to give tight algorithmic upper and lower bounds for **HAMILTONIAN CYCLE** when parameterized by the clique-width of the input graph?
- Is it possible to give tight algorithmic upper and lower bounds for **d -REGULAR INDUCED SUBGRAPH** when parameterized by the tree-width of the input graph?

Thank You!