

Electrical Flow Primitive and Fast Graph Algorithms

Aleksander Mądry



These are exciting times for fast graph algorithms

Last several years brought faster algorithms for a number of fundamental graph problems

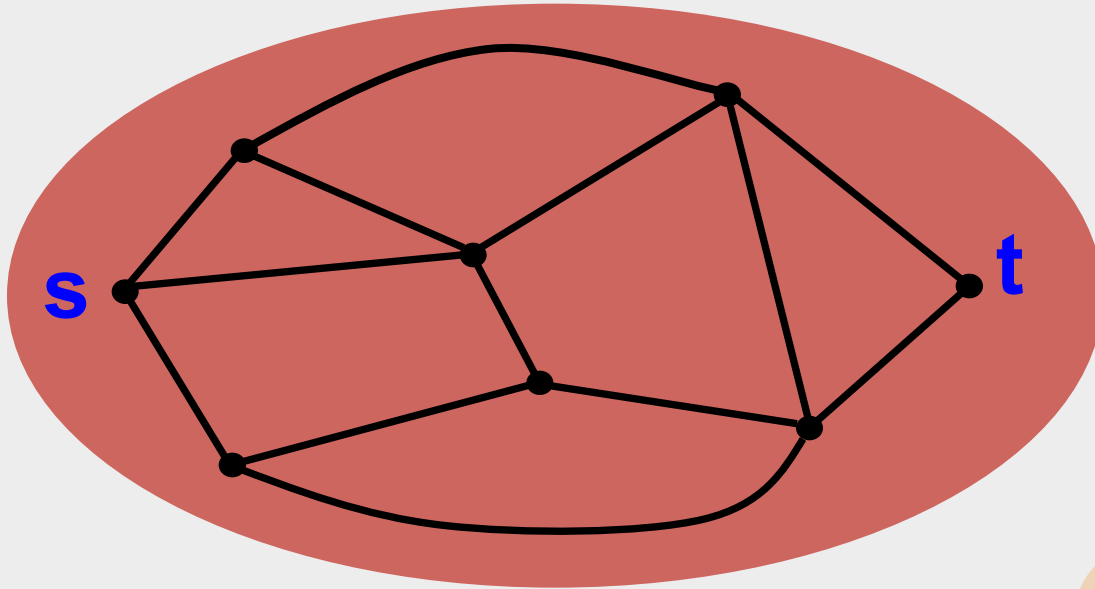
Central notion: **Electrical flows**

This talk: A quick tour through these algorithmic applications and the underlying connections



Electrical flows (Take I)

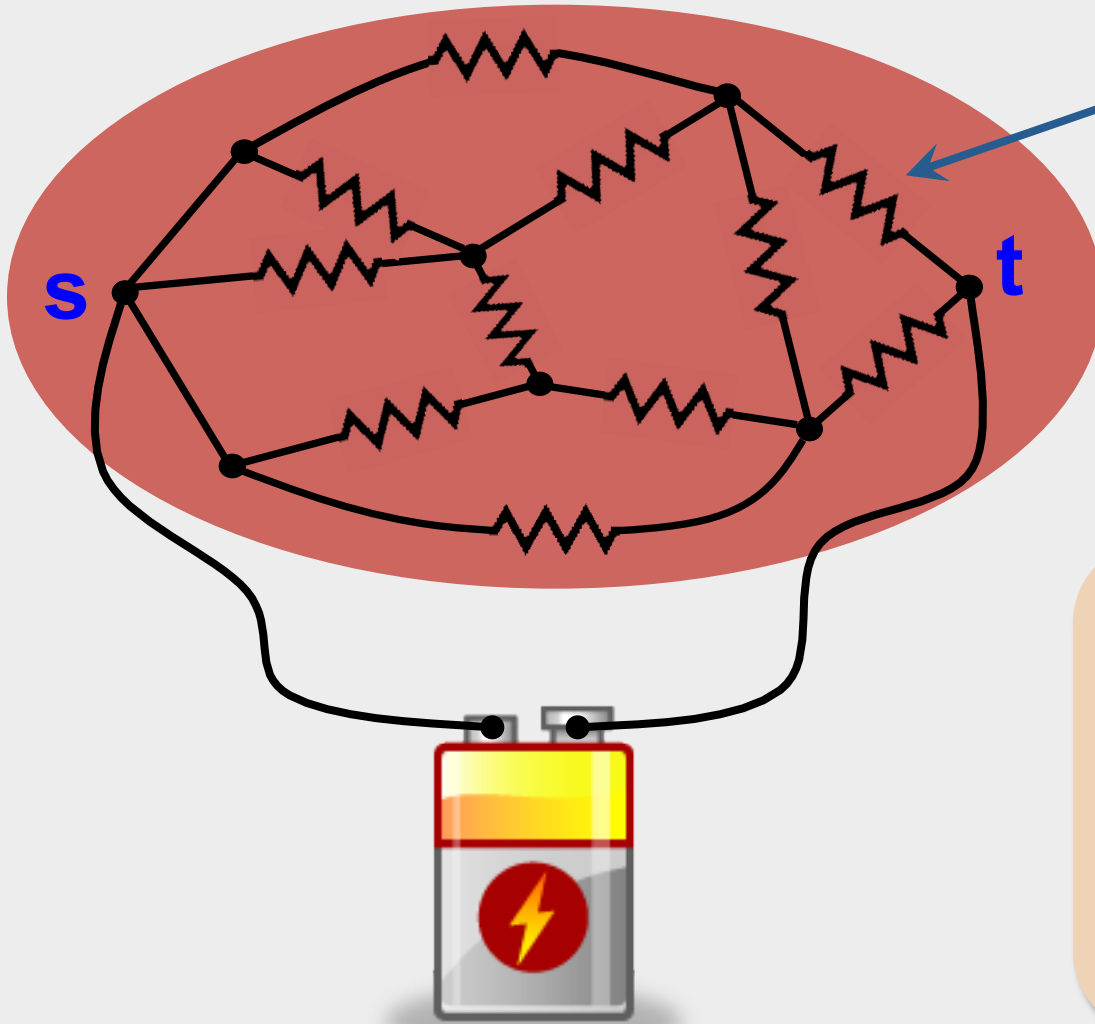
Input: Undirected graph G ,
resistances r_e ,
source s and sink t



Recipe for elec. flow:
1) Treat edges as
resistors

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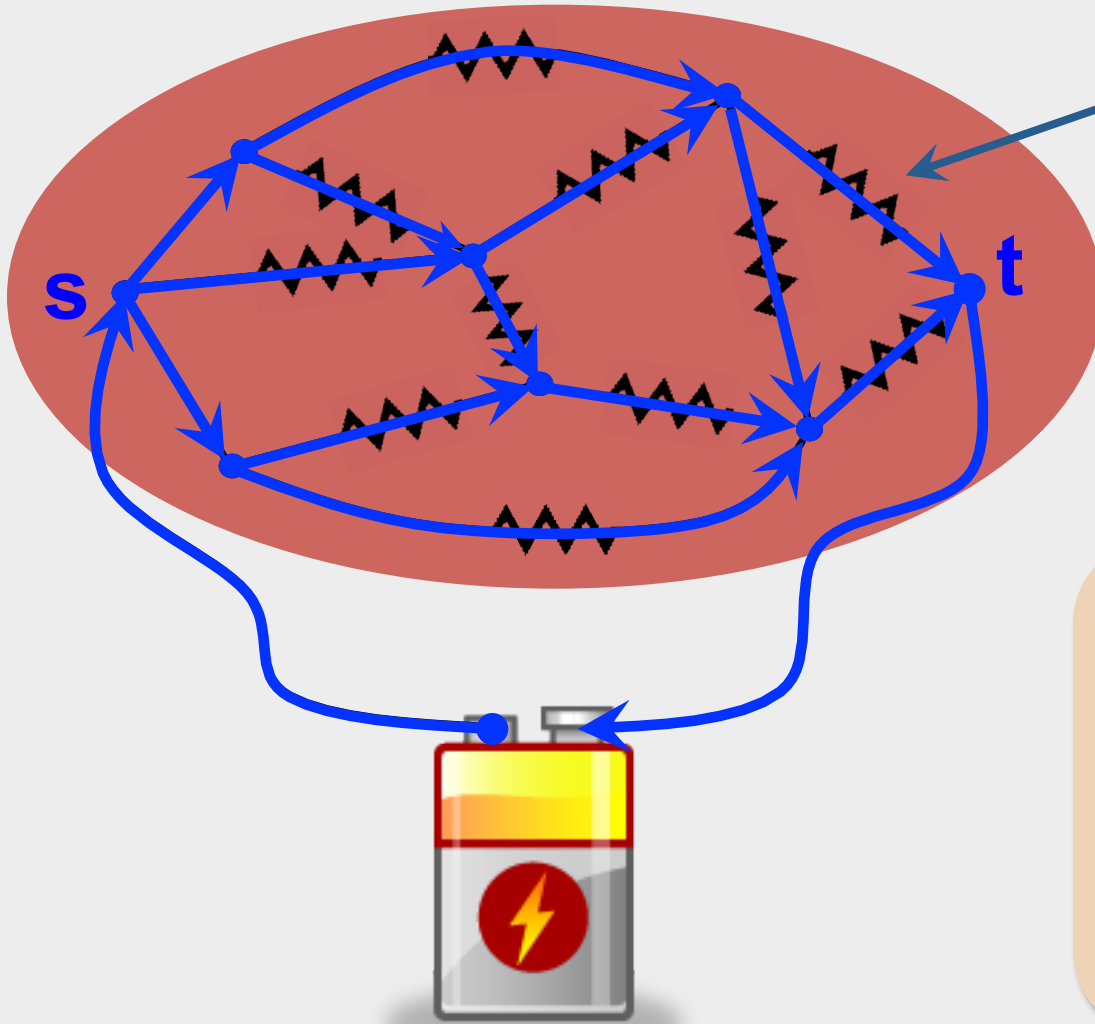
resistance r_e

Recipe for elec. flow:

- 1) Treat edges as resistors
- 2) Connect a **battery** to s and t

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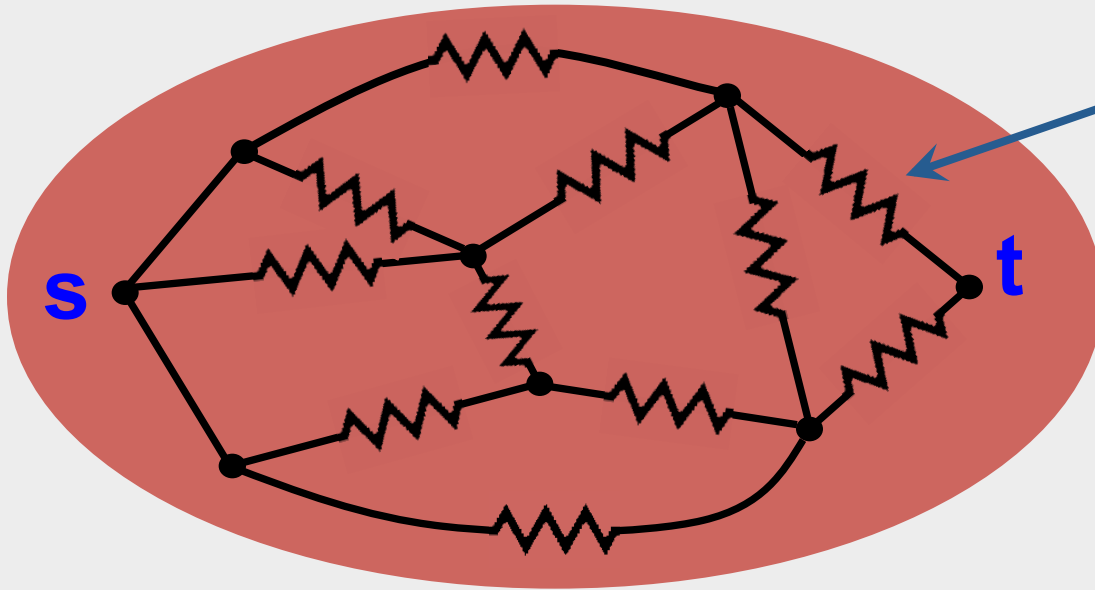
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Recipe for elec. flow:

- 1) Treat edges as **resistors**
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Electrical flows (Take II)

Input: Undirected graph G ,
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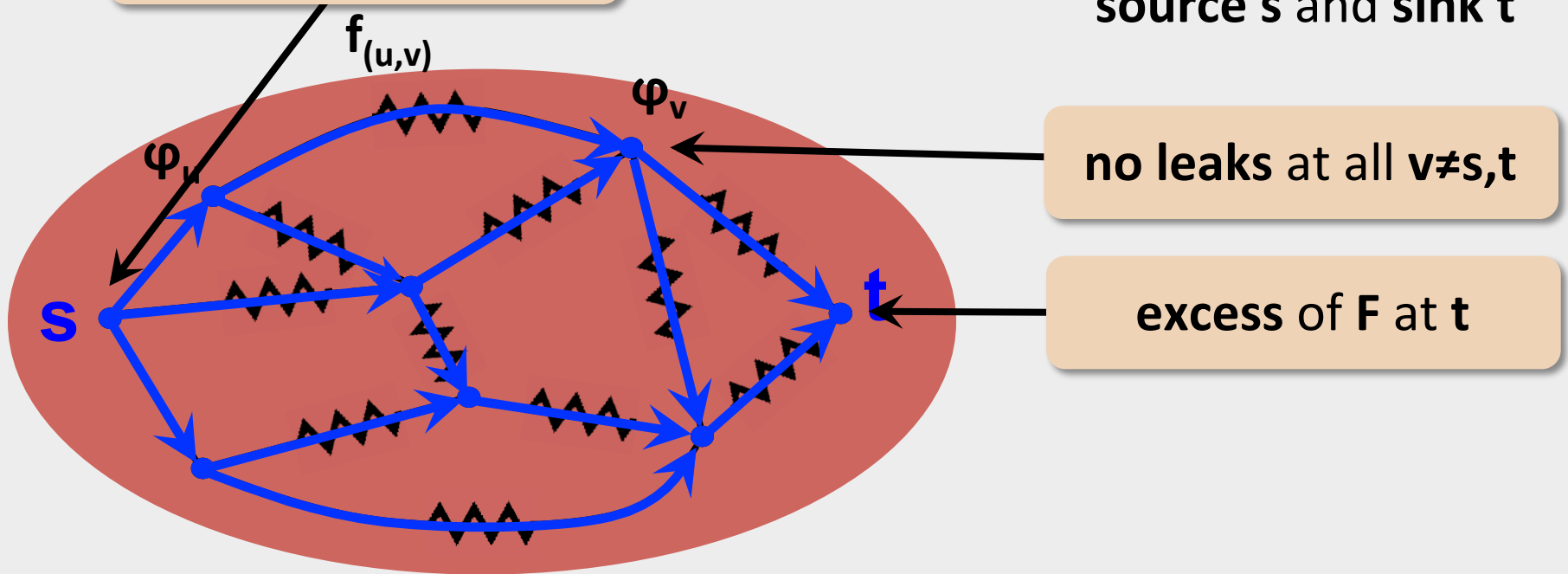


resistance r_e

(Another) recipe for electrical flow (of value F):

Electrical Flow (Take II)

Input: Undirected graph G ,
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(Another) recipe for electrical flow (of value F):

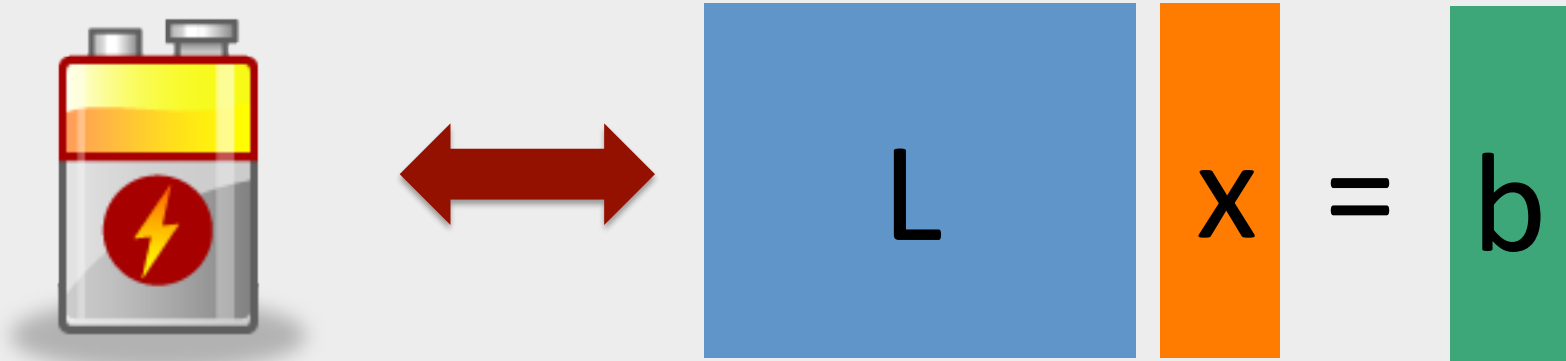
Find **vertex potentials** φ_v such that setting, for all (u,v)

$$f_{(u,v)} \leftarrow (\varphi_v - \varphi_u) / r_{(u,v)} \quad \text{(Ohm's law)}$$

gives a **valid s-t flow of value F**

Crucial connection: Laplacian systems

Computing electrical flows boils down to solving **Laplacian systems**



[ST '04, KMP '10, KMP '11, KOSZ '13, LS '13, CKPPR '14]:
Laplacian systems can be (essentially)
solved in **nearly-linear** time

Key consequence: Electrical flows
become a powerful primitive



Electrical Flows and the Maximum Flow Problem

Connection I: Energy minimization

Principle of least energy:
Electrical flows = ℓ_2 -minimization

Electrical flow of value F :
The unique minimizer of the **energy**

$$\mathbf{E}(\mathbf{f}) = \sum_e r_e f(e)^2$$

among all **s-t** flows \mathbf{f} of value F

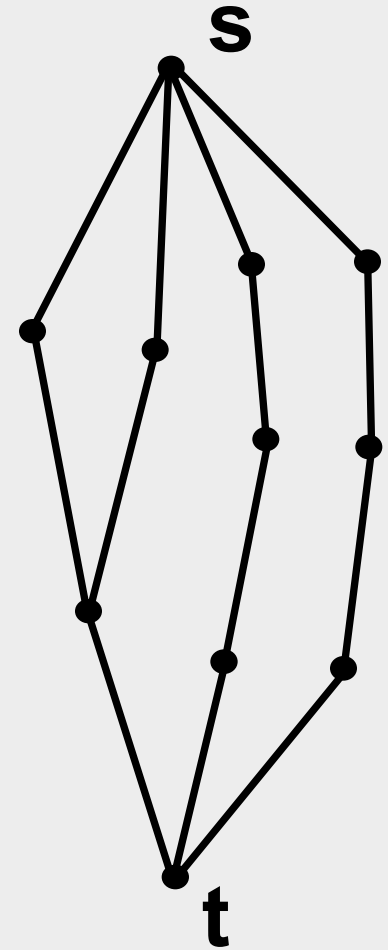
Application:

Turning the fast **electrical flow** computation
into a fast **max flow** approx.

Approx. undirected max flow [Christiano Kelner M. Spielman Teng '11] via electrical flows

Assume: F^* known (via binary search)

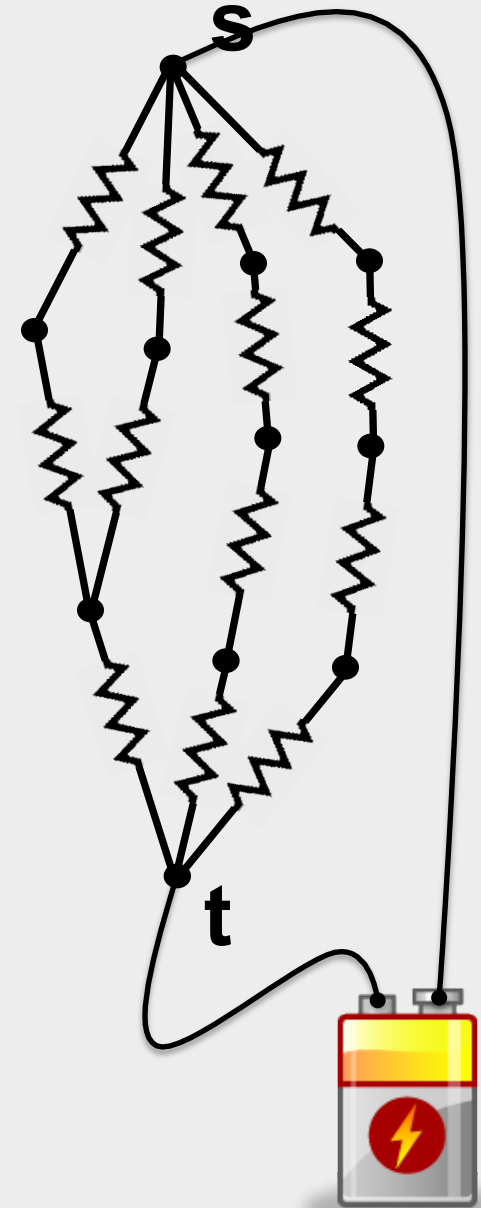
→ Treat edges as resistors of resistance **1**



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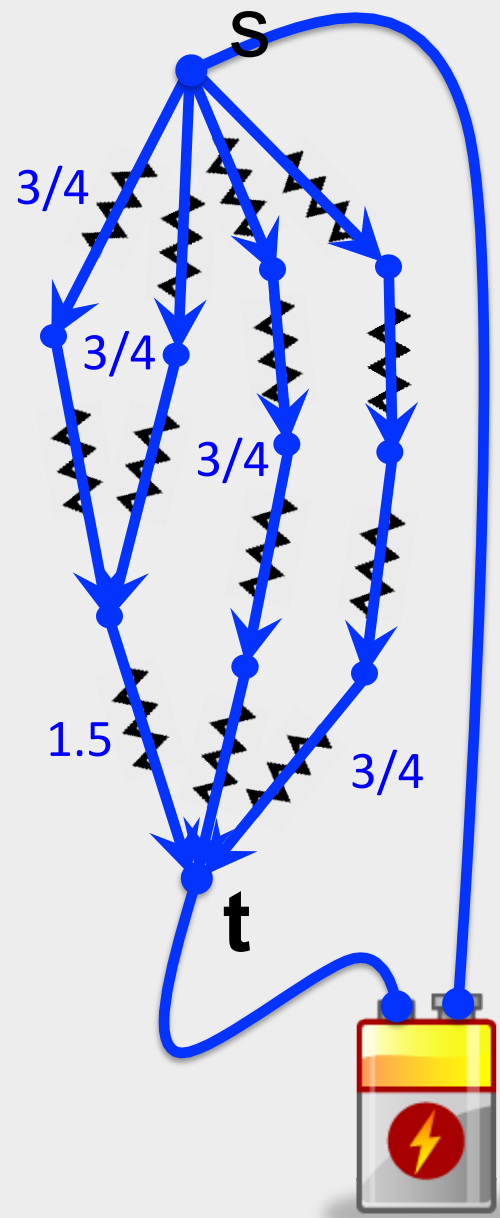
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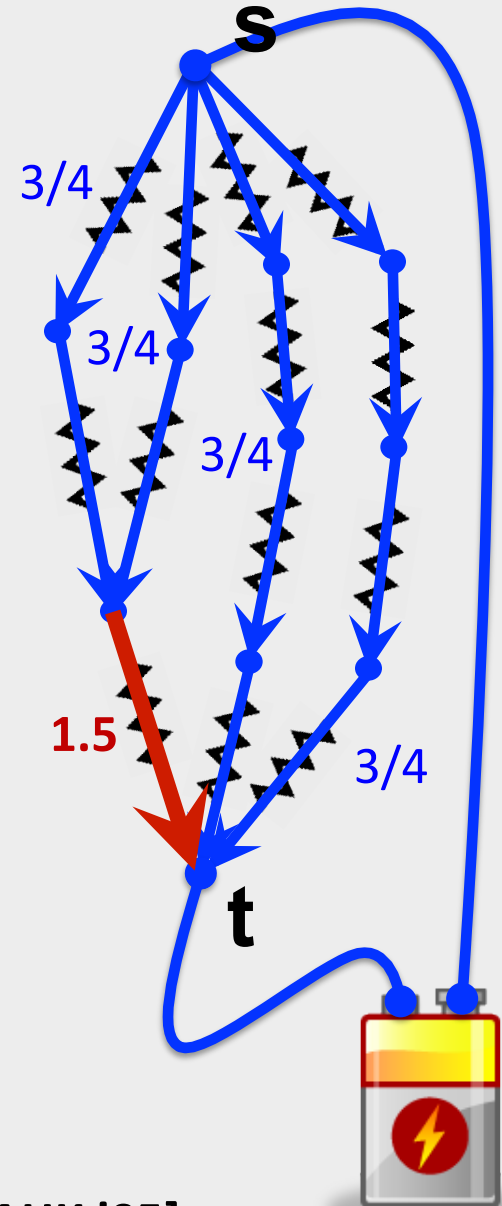
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(This flow has **no leaks**, but **can overflow** some edges)



Approx. undirected max flow [Christiano Kelner M. Spielman Teng '11] via electrical flows

Assume: F^* known (via binary search)

- Treat edges as resistors of resistance **1**
 - Compute electrical flow of value F^*
(This flow has **no leaks**, but can **overflow** some edges)
 - To fix that: **Increase resistances** on the overflowing edges
- Repeat
- **At the end:** Take an **average** of all the flows as the final answer



Evolution of resistances:

Based on Multiplicative Weight Update method

[FS '97, PST '95, AHK '05]

This approach yields an $(1+\epsilon)$ -approx. to undirected max flow in $\tilde{O}(m^{4/3}\epsilon^{-3})$ time algorithm

[Lee Srivastava Rao '13]: A different perspective with a better dependence on ϵ for unit capacity graphs

[Kelner Miller Peng '12]: $(1+\epsilon)$ -approx. to undirected k -commodity flow in $\tilde{O}(m^{4/3} \text{poly}(k, \epsilon^{-1}))$ time

[Sherman '13, Kelner Lee Orecchia Sidford '14]: $(1+\epsilon)$ -approx. to undirected k -commodity flow in $O(m^{1+o(1)} k^2 \epsilon^{-2})$ time

Underlying idea: **j-tree-based** [KLOS '14]

[KLOS '14]

elect. flow still used here

(efficiently computable) oblivious-routing scheme

Regularizer

gradient descent (in ℓ_∞ -norm)

Electrical Flows and the Interior-point Methods

(Path-following) Interior-point method (IPM)

[Dikin '67, Karmarkar '84, Renegar '88,...]

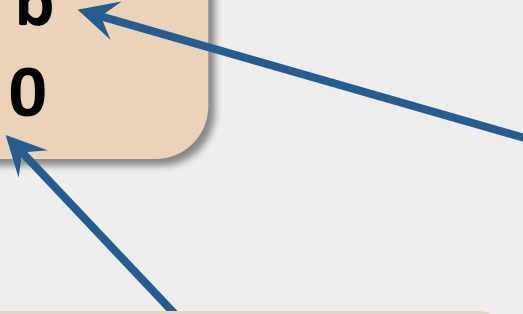
A powerful framework for solving general LPs (and more)

LP: $\min c^T x$
s.t. $Ax = b$
 $x \geq 0$

Idea: Take care of “hard” constraints by adding a “barrier” to the objective

“easy” constraints
(use projection)

“hard” constraints



(Path-following) Interior-point method (IPM)

[Dikin '67, Karmarkar '84, Renegar '88,...]

A powerful framework for solving general LPs (and more)

$$\begin{aligned} \text{LP}(\mu): \quad & \min \mathbf{c}^T \mathbf{x} - \mu \sum_i \log x_i \\ \text{s.t.} \quad & \mathbf{Ax} = \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0} \end{aligned}$$

Idea: Take care of “hard” constraints by adding a “barrier” to the objective

Observe: The barrier term enforces $\mathbf{x} \geq \mathbf{0}$ implicitly

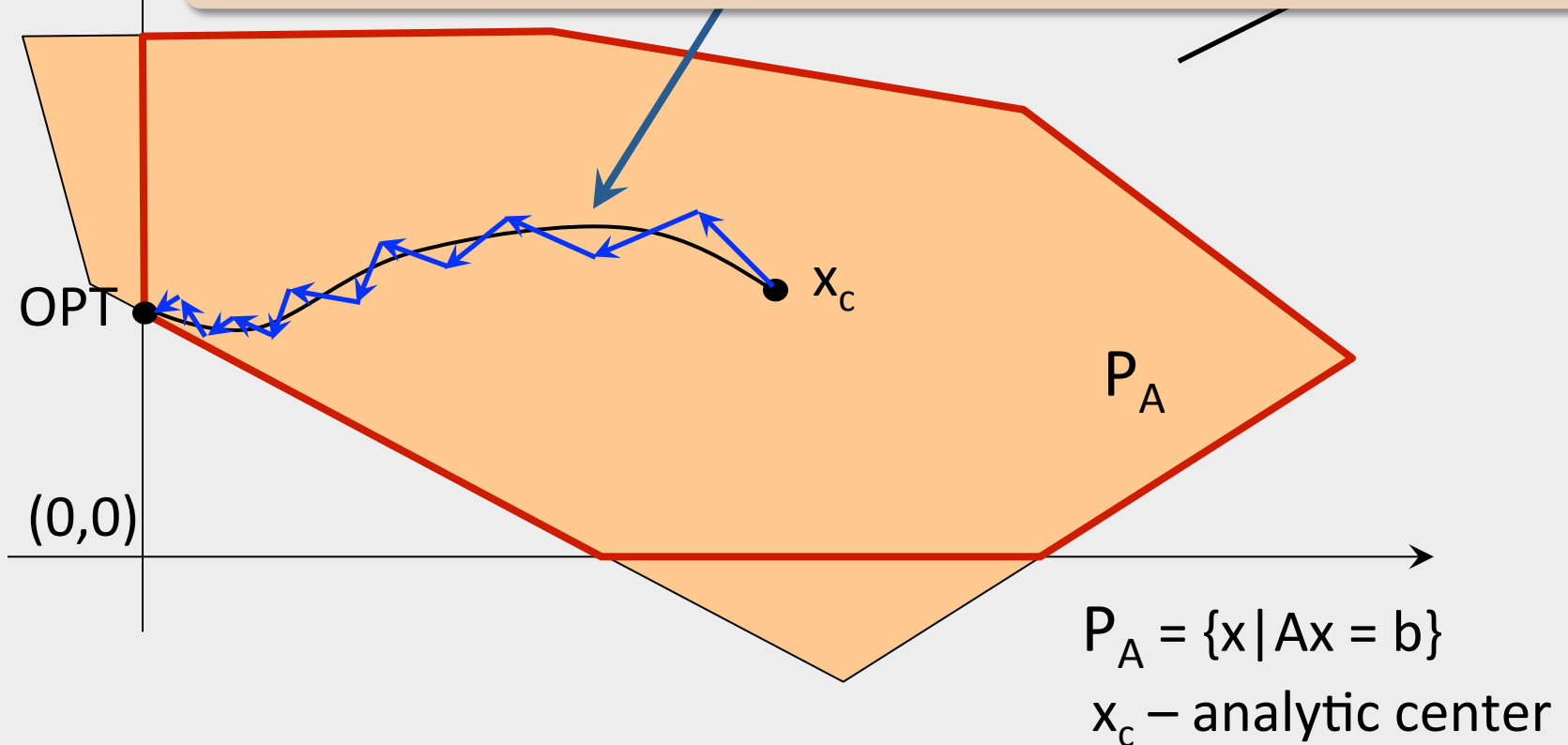
Furthermore: for large μ , $\text{LP}(\mu)$ is easy to solve and

$$\text{LP}(\mu) \rightarrow \text{original LP, as } \mu \rightarrow 0^+$$

Path-following routine:

- Start with (near-)optimal solution $\mathbf{x}(\mu)$ to $\text{LP}(\mu)$ for large $\mu > 0$
- Take an **improvement step** that gradually reduces μ while maintaining the (near-)optimality of $\mathbf{x}(\mu)$ (wrt current μ)

central path = optimal solutions to $LP(\mu)$ for all $\mu > 0$



Path-following routine:

- Start with (near-)optimal solution $x(\mu)$ to $LP(\mu)$ for large $\mu > 0$
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How to guide our improvement steps?

Use electrical flows!

Step 1: Descent (“Predict”)

$$\begin{aligned} \text{Solve: } & \min \sum_i r_i u_i^2 \\ & \text{s.t. } \mathbf{A}\mathbf{u} = \mathbf{b} \end{aligned}$$

$$\begin{aligned} \mathbf{x} &= \text{current solution} \\ & \text{(near-optimal wrt } \mathbf{LP}(\boldsymbol{\mu})\text{)} \\ r_i &= 1/x_i^2 \end{aligned}$$

Effect: Decreasing $\boldsymbol{\mu}$ at the ϵ of optimality (centrality) of

$$\text{Set: } \mathbf{x}' = (1-\delta)\mathbf{x} + \delta\mathbf{u}$$

Formulation of electrical flow problem
if \mathbf{A} = edge-vertex incidence matrix

How to guide our improvement steps?

Use electrical flows!

Step 2: Centering (“Correct”)

\mathbf{x} = current solution
(near-optimal wrt $\mathbf{LP}(\boldsymbol{\mu})$)

$$r_i = \mathbf{1}/x_i^2$$

Set: $x_i' = (1-\delta) x_i + \delta \mathbf{u}$
 $\boldsymbol{\mu}' = (1-\delta) \boldsymbol{\mu}$

How to guide our improvement steps?

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Step 2: Centering (“Correct”)

$$\begin{aligned} \text{Solve: } & \min \sum_i r_i' \hat{u}_i^2 \\ & \text{s.t. } A\hat{u} = b' \end{aligned}$$

x = current solution
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$$r_i = 1/x_i^2 \quad r_i' = 1/(x_i')^2$$

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Effect: x'' is near-optimal (centered) again and μ decreased

$$\begin{aligned} x &= \text{current solution} \\ & \text{(near-optimal wrt } LP(\mu)) \\ r_i &= 1/x_i^2 \quad r_i' = 1/(x_i')^2 \end{aligned}$$

$$\begin{aligned} \text{Set: } \quad x_i' &= (1-\delta) x_i + \delta u \\ \mu' &= (1-\delta) \mu \\ x'' &= (1-\delta) x_i' + \delta \hat{u} \end{aligned}$$

Can show: Setting $\delta \approx m^{-1/2}$ suffices ($m = \#$ of variables)
→ $O(m^{1/2} \log \varepsilon^{-1})$ iterations gives an ε -optimal solution [Renegar '88]

But: Understanding the electrical flow connection brings much more

Beyond the classical analysis of IPMs

Can show: Setting $\delta \approx m^{-1/2}$ suffices ($m = \#$ of variables)
→ $O(m^{1/2} \log \varepsilon^{-1})$ iterations gives an ε -optimal solution [Renegar '88]

1) When solving **flow** problems → each iteration takes $\tilde{O}(m)$ time

[Daitch Spielman '08]: $\tilde{O}(m^{3/2} \log \varepsilon^{-1})$ time alg. for “all” flow problems

2) Optimal setting of δ corresponds to certain ℓ_2 - vs. ℓ_4 -norm interplay

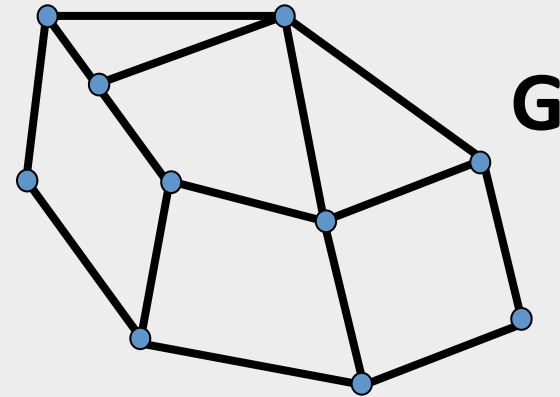
[M. '13]: $\tilde{O}(m^{10/7})$ time alg. for **unit-capacity** max flow
(via perturbation + preconditioning of intermediate sol./central path)

[Lee Sidford '13]: $\tilde{O}(mn^{1/2} \log \varepsilon^{-1})$ time alg. for “all” flow problems
(via a careful choice and reweighting of the barriers)

Electrical Flows, Random Walks, and Random Spanning Tree Generation

Random Spanning Trees

Goal: Output an uniformly random spanning tree

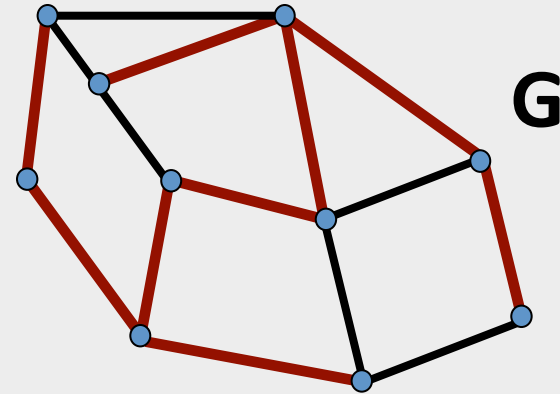


More precisely:

$\mathcal{T}(G)$ = set of all spanning trees of G

Random Spanning Trees

Goal: Output an uniformly random spanning tree



More precisely: $\mathcal{T}(G)$ = set of all spanning trees of G

Task: Output a tree T with prob. $|\mathcal{T}(G)|^{-1}$

Note: $|\mathcal{T}(G)|$ can be as large as n^{n-2}

More generally: Given weight w_e for each edge e

Task: Output a tree T with prob. proportional to $\prod_e w_e$

Connection II: Random Spanning Trees

Key quantity: Effective resistance (between s and t)

$$R_{\text{eff}}(s,t) = \chi_{st}^T \mathbf{L}^+ \chi_{st}$$

Vector with **1** at t , **-1** at s
and **0**s everywhere else

Pseudo-inverse
of the Laplacian

Connection II: Random Spanning Trees

Key quantity: Effective resistance (between s and t)

$$R_{\text{eff}}(s,t) = \chi_{st}^T L^+ \chi_{st}$$

Alternatively: $R_{\text{eff}}(s,t)$ = potential difference $\phi_t - \phi_s$ induced by an electrical flow \mathbf{f} that sends a **unit current** from s to t

Yet differently (when all $r_e=1$ and (s,t) is an edge):

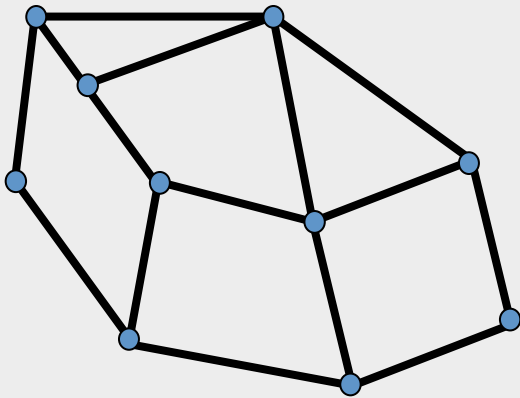
$R_{\text{eff}}(s,t)$ = the amount of flow f_{st} sent directly over the edge (s,t) by the **unit-value** electrical s - t flow \mathbf{f}

Matrix Tree theorem [Kirchoff 1847]

$$\Pr[\mathbf{e} \text{ in a rand. tree}] = w_e R_{\text{eff}}(\mathbf{e}) \quad \text{where } r_e = 1/w_e$$

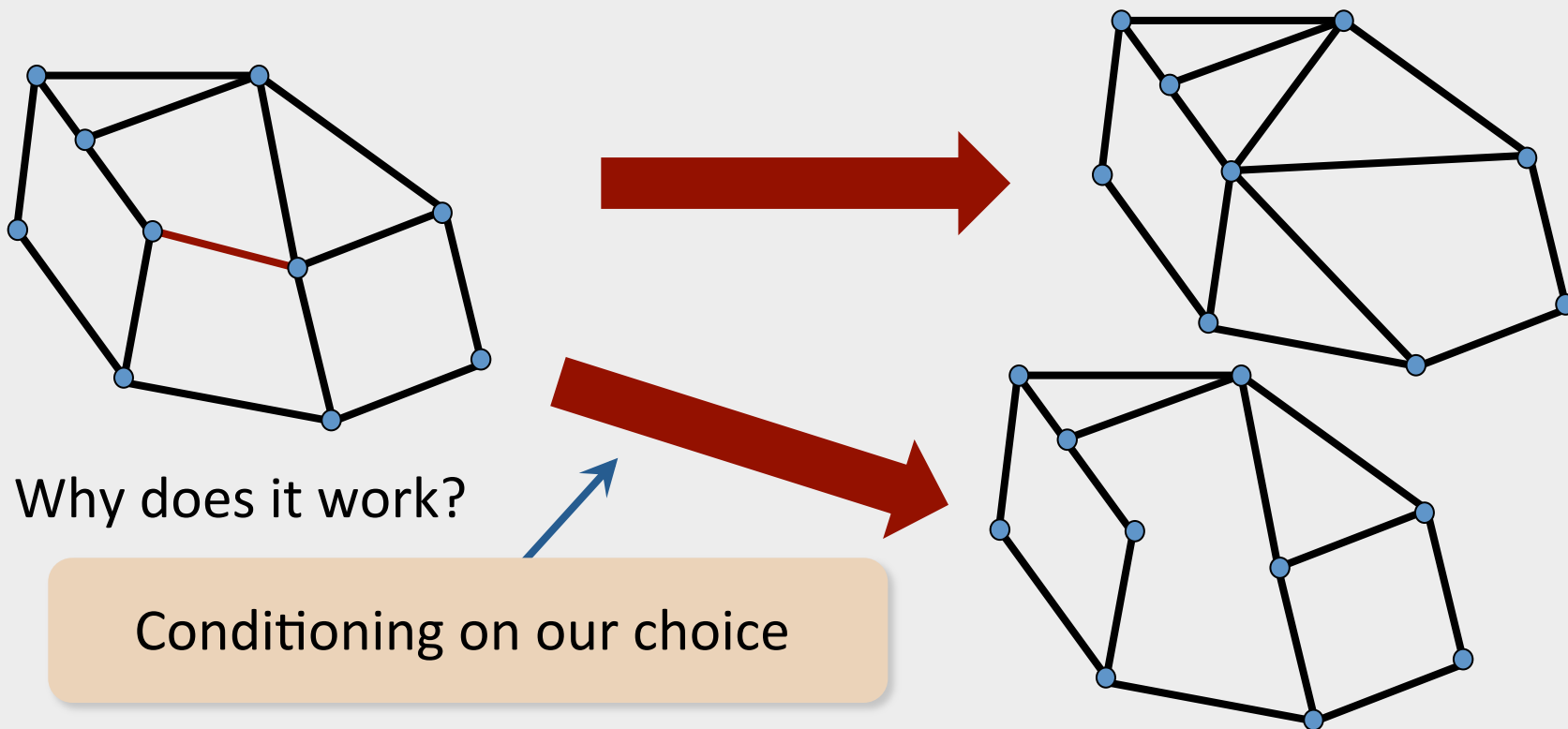
Generating a Random Spanning Tree with Electr. Flows

- Order edges e_1, e_2, \dots, e_m arbitrarily and start with T being empty
- For each e_i :
 - Compute $R_{\text{eff}}(e_i)$ and add e_i to T with that probability
 - Update G by **contracting** e_i if e_i in T and **removing** it o.w.



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Running time?

Bottleneck: Computing $R_{\text{eff}}(e_i)$

But: $R_{\text{eff}}(e) = \chi_e^T L^+ \chi_e \rightarrow$ Use Laplacian solver

Slight difficulty: Need to solve a Laplacian system ~~exactly~~

[Propp '0

Resulting runtime: $\min(m n^\omega, \tilde{O}(m^2))$

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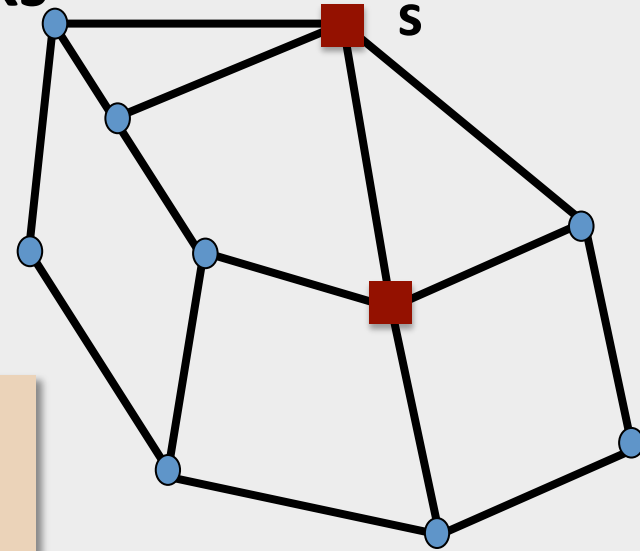
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Can we do better? **Yes!** (At least when the graph is sparse.)

Rand. Spanning Trees and Random Walks

[Broder '89, Aldous '90]: Generate random spanning tree using random walks

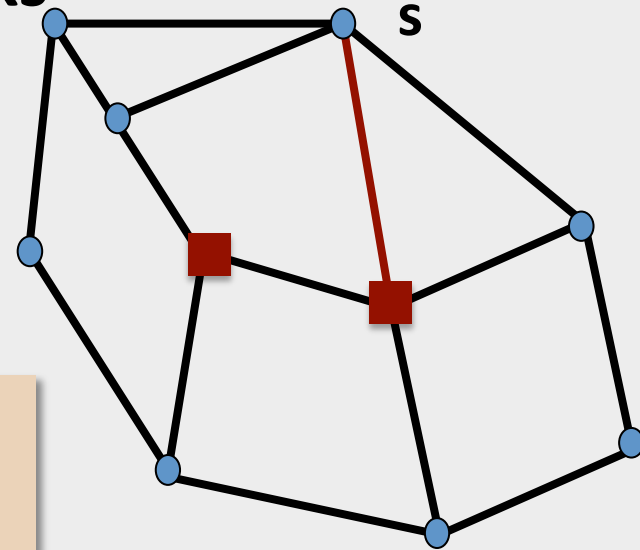
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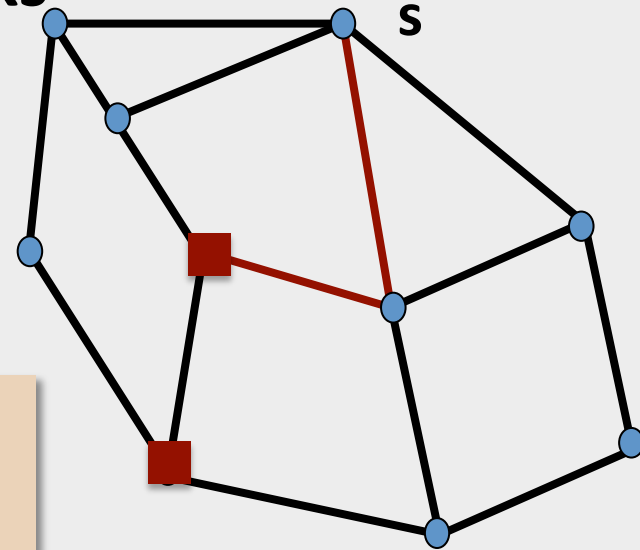
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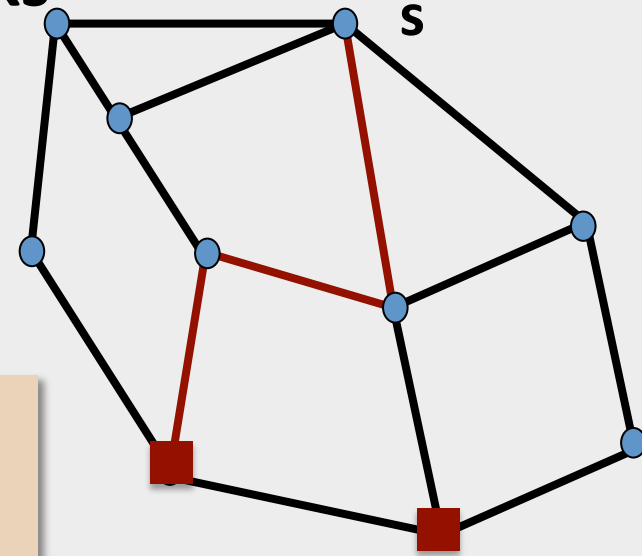
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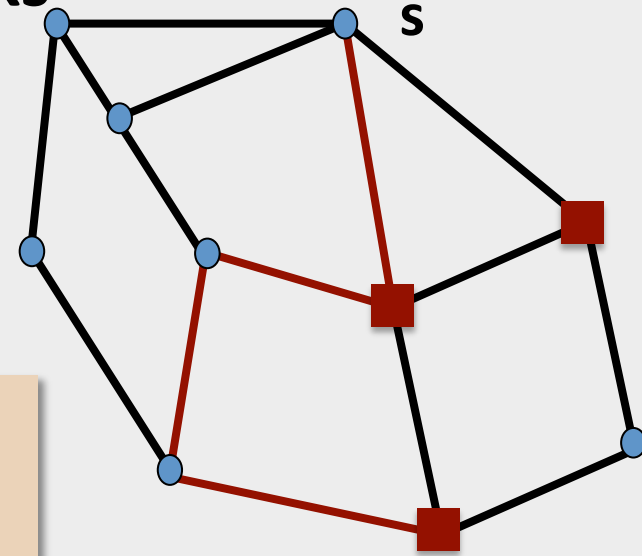
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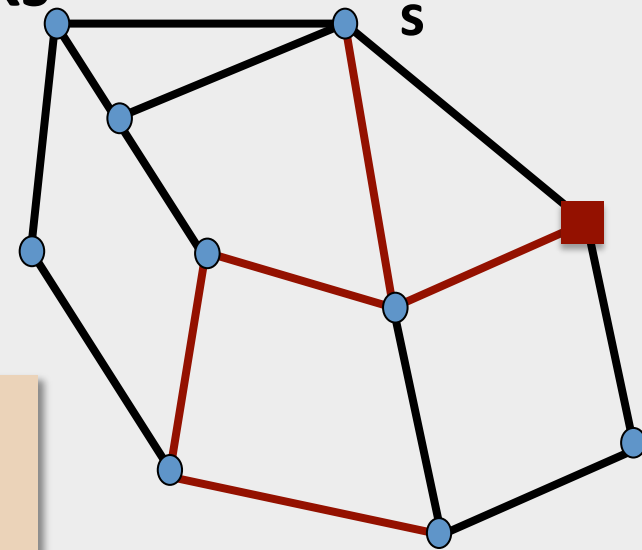
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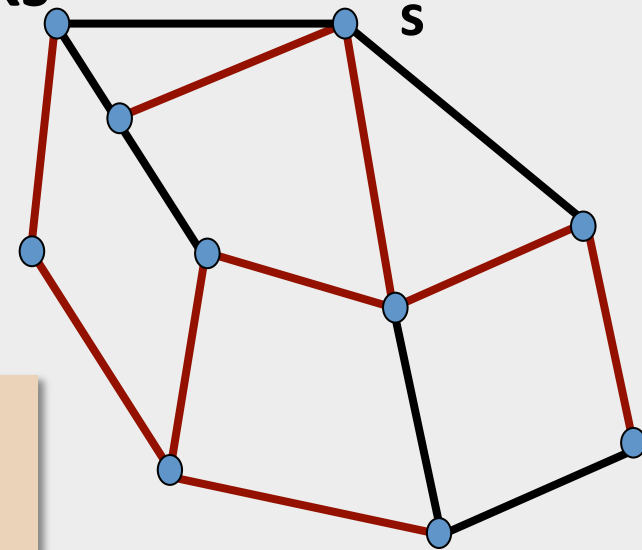
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Why does it work?

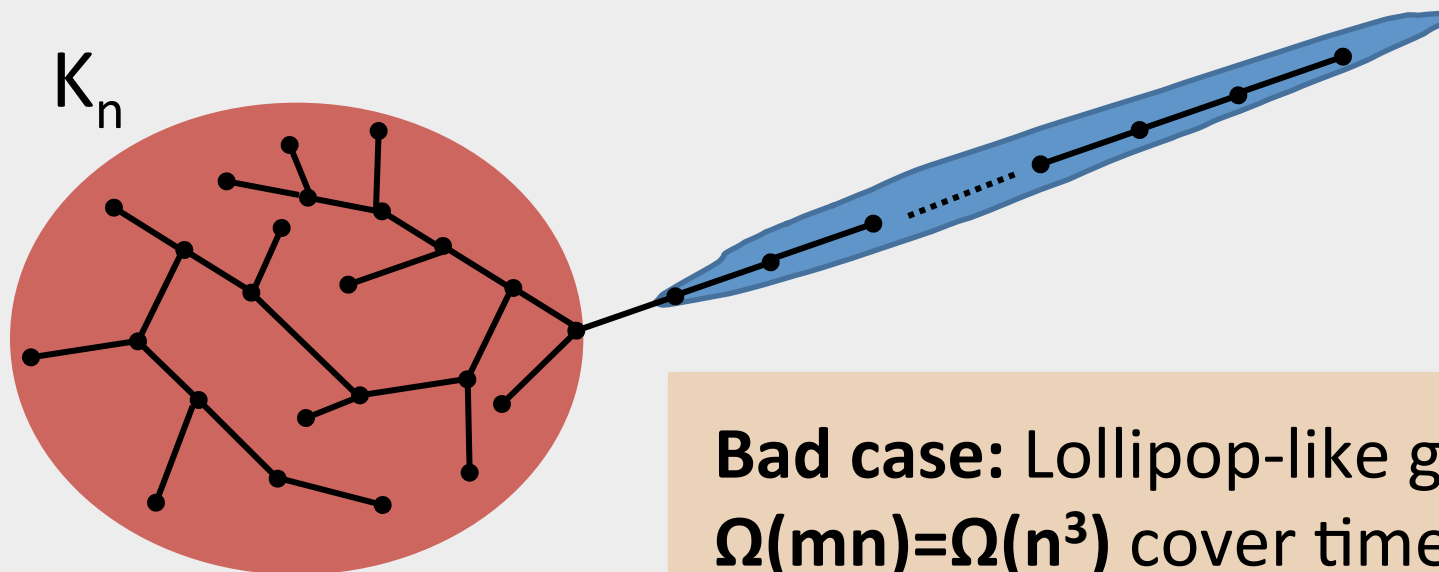
Magic! (aka coupling from the past)

Running time?

$$O(\text{cover time}) = O(mn)$$

[W '96]: Can get $O(\text{mean hitting time})$ but still $O(mn)$ in the worst case

Can we improve upon that?



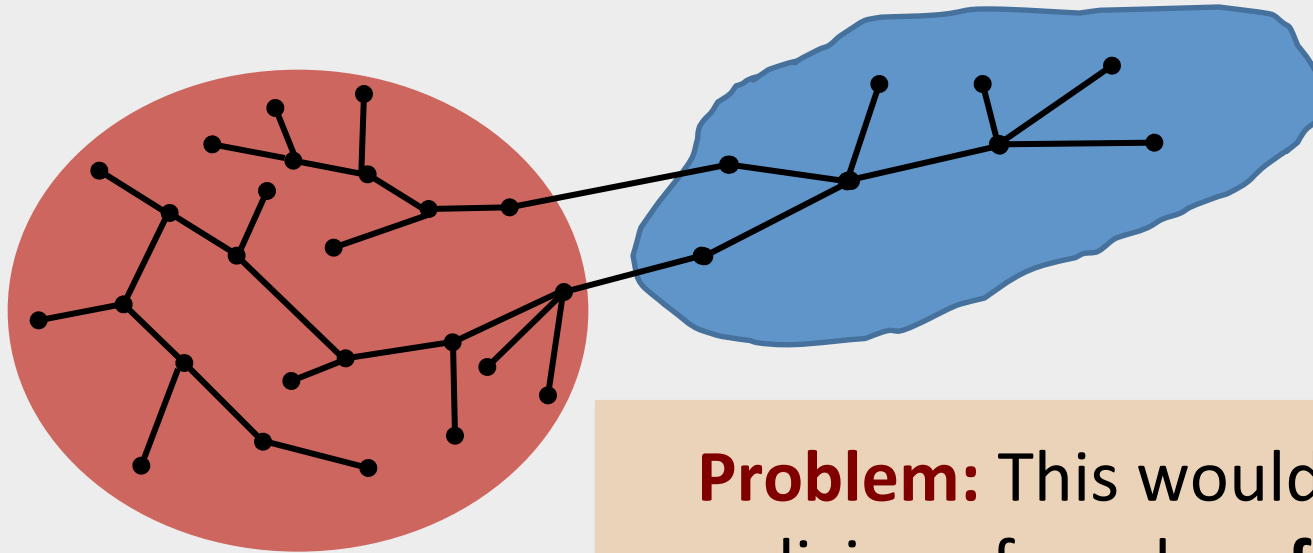
Bad case: Lollipop-like graph
 $\Omega(mn) = \Omega(n^3)$ cover time

What happens: The walk resides mainly in K_n - the path-like part is covered only after a lot of attempts

Observe: We know how the tree looks like in K_n very early on

Idea: Cut the graph into pieces with good cover time and find trees in each piece separately

Can we improve upon that?



Problem: This would require splicing of random **forests**

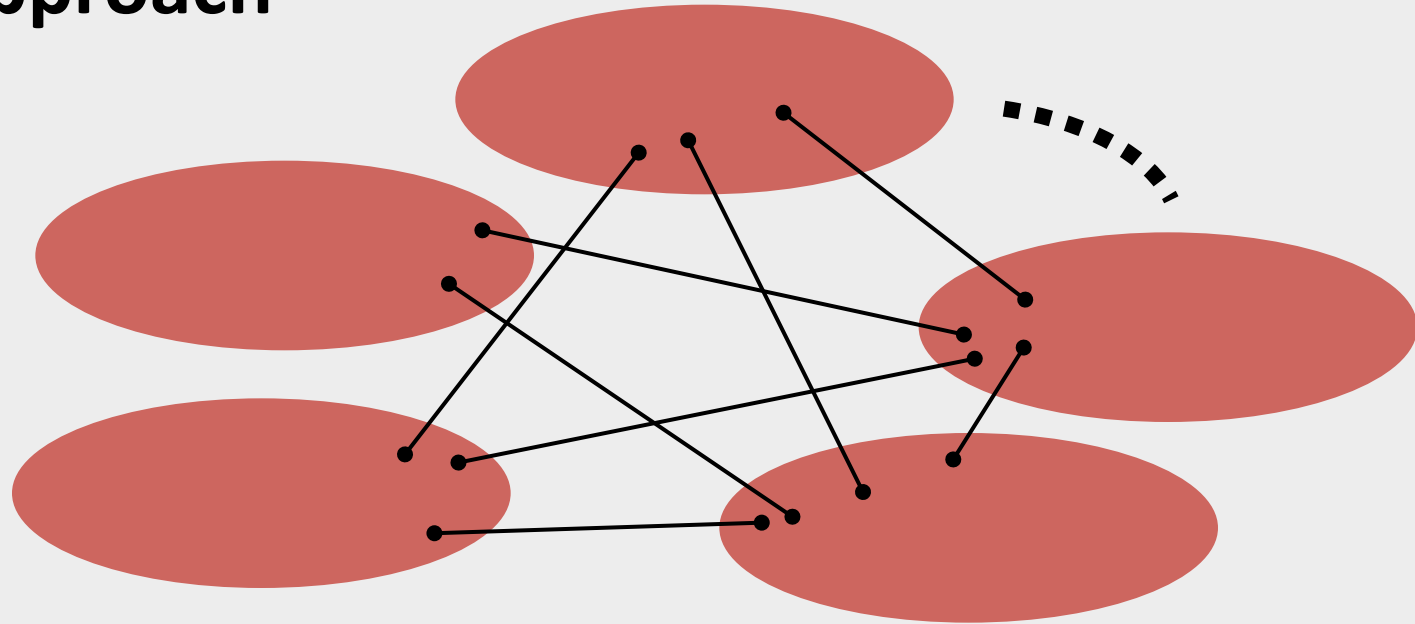
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Different Approach

[Kelner M. '09]

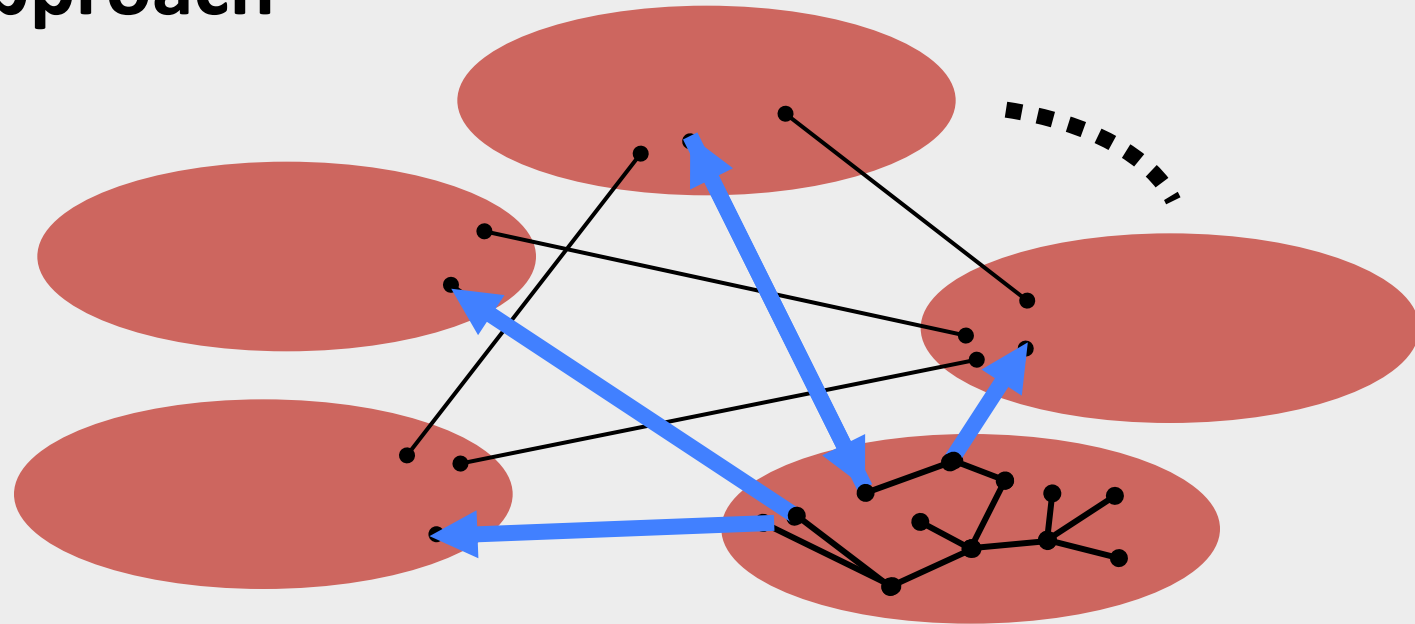


Decompose the graph into pieces with:

- Low diameter each
- Small “interface”

Different Approach

[Kelner M. '09]



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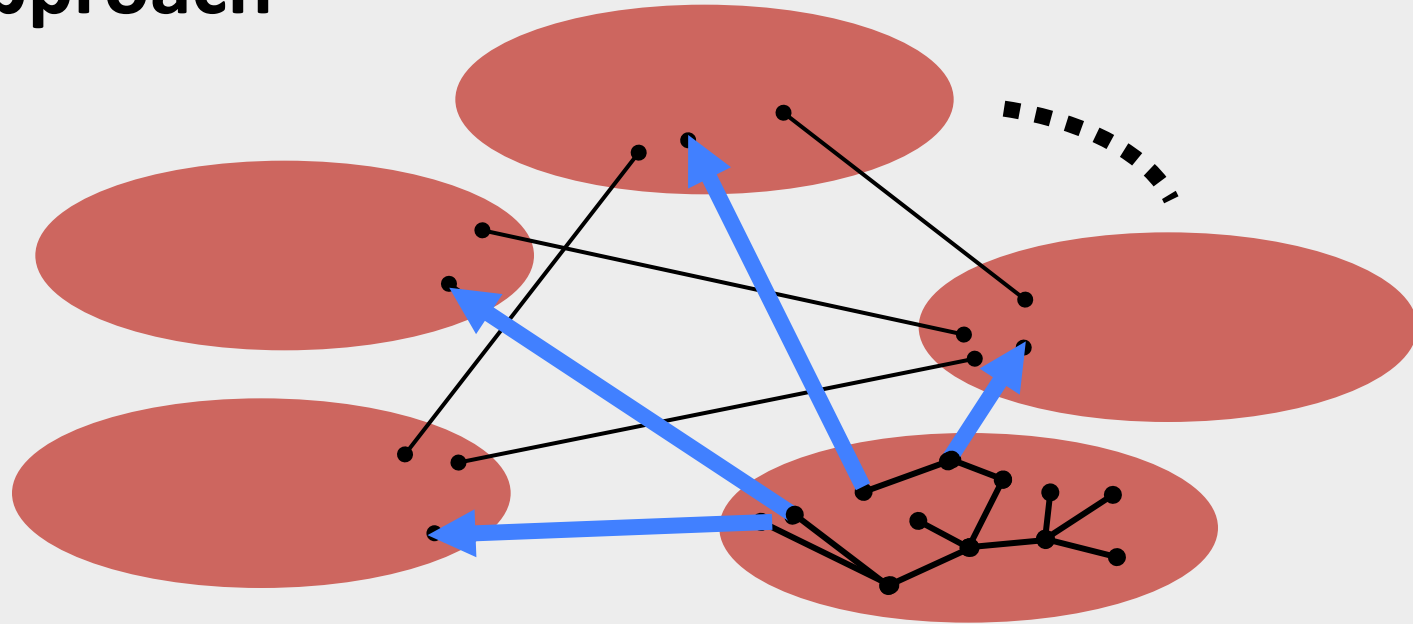
→ Small “interface”

Modification: When simulating the random walk, **shortcut** revisits to pieces that were already explored in full

Note: We still retain enough information to output the final tree

Different Approach

[Kelner M. '09]



Decompose the graph into pieces with:

→ Low diameter each = we cover each piece relatively quickly

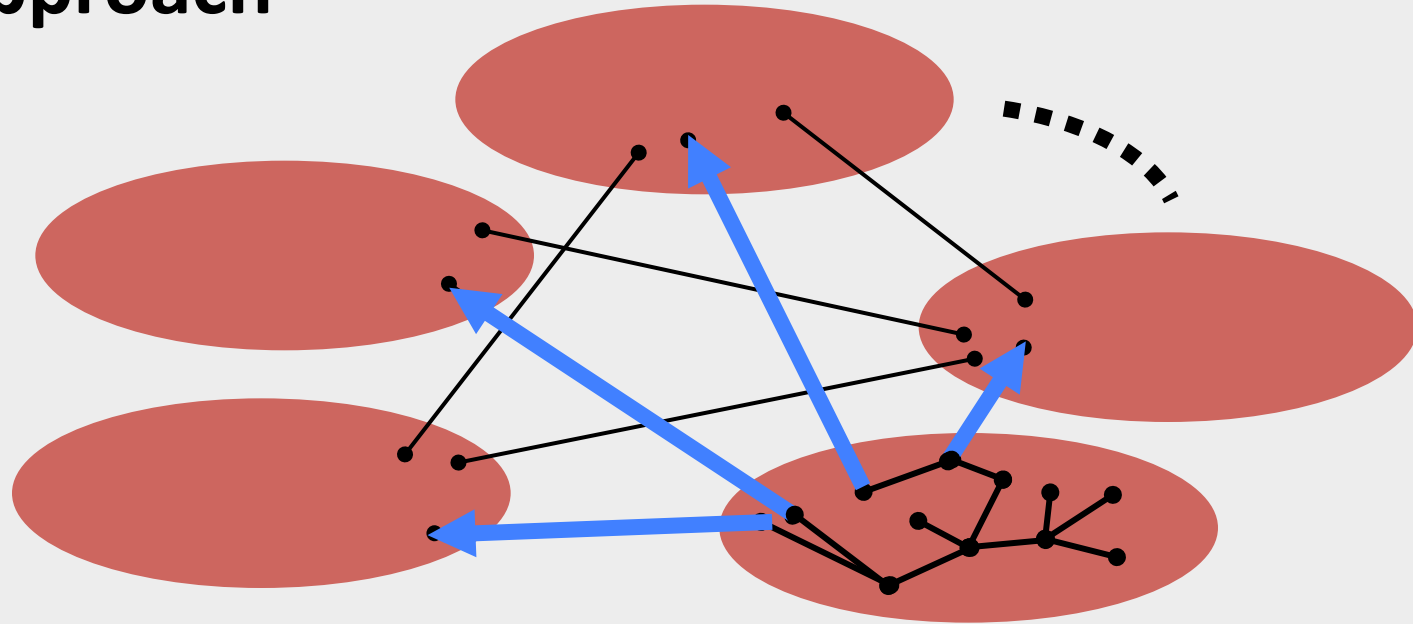
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Different Approach

[Kelner M. '09]



Decompose the graph into pieces with:

→ Low diameter each = we cover each piece relatively quickly

→ Small “interface” = we do not walk too much over that interface

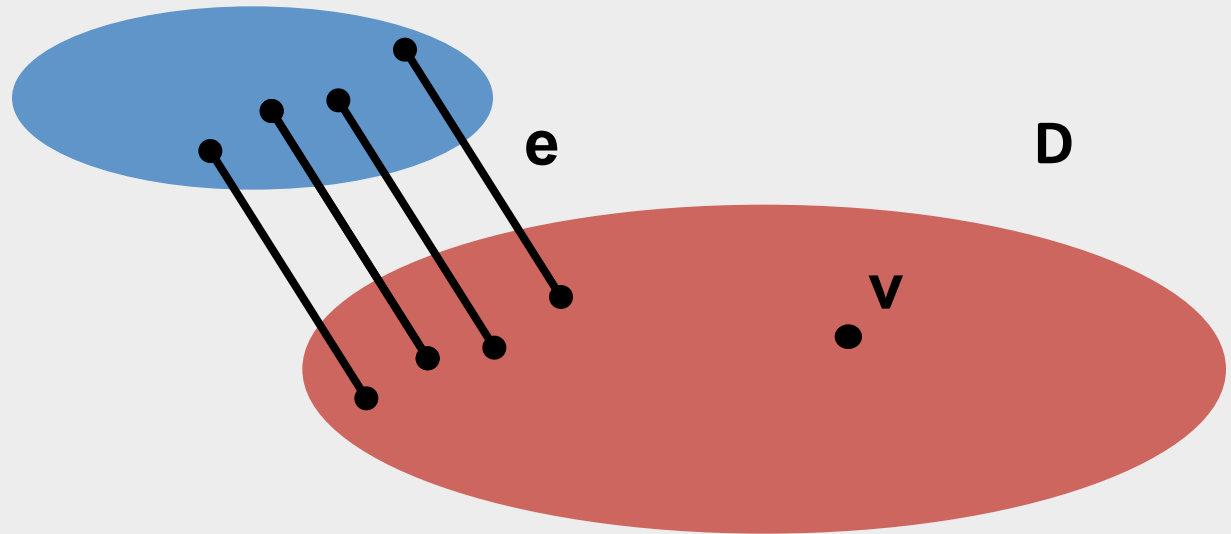
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Missing element: How to compute the shortcutting jumps?

Different Approach

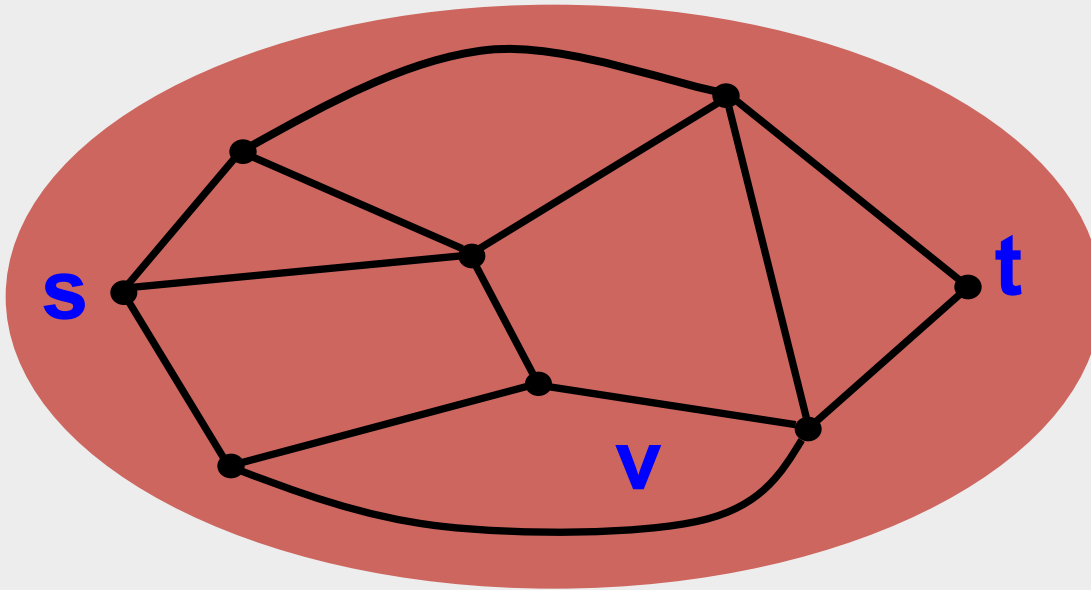
[Kelner M. '09]



Need: $P_D(e, v)$ = prob. we exit D via edge e after entering through v

Electrical flows can help us compute that!

Connection III: Absorption of Random Walks



Want to compute:
 $q_{st}(\mathbf{v})$ = prob. that
a random walk
started at \mathbf{v} reaches \mathbf{t}
before reaching \mathbf{s}

To compute $q_{st}(\mathbf{v})$:

→ Compute an electrical $\mathbf{s-t}$ flow

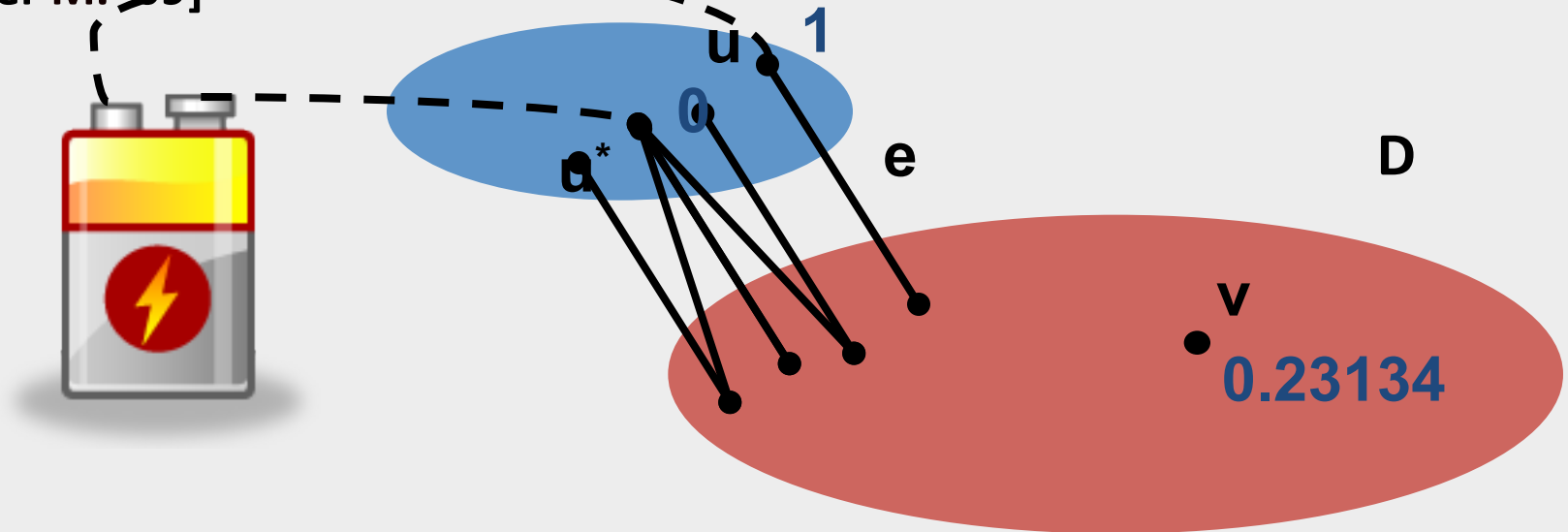
→ Normalize the voltage potentials ϕ so as $\phi_s=0$ and $\phi_t=1$

Then: $q_{st}(\mathbf{v}) = \phi_v$

Result: We can (approx.) compute $q_{st}(\mathbf{v})$ for all \mathbf{v} in $\tilde{O}(m)$ time

Different Approach

[Kelner M. '09]



Need: $P_D(e,v)$ = prob. we exit D via edge e after entering through v

Observe: $P_D(e,v) = q_{uu^*}(v)$

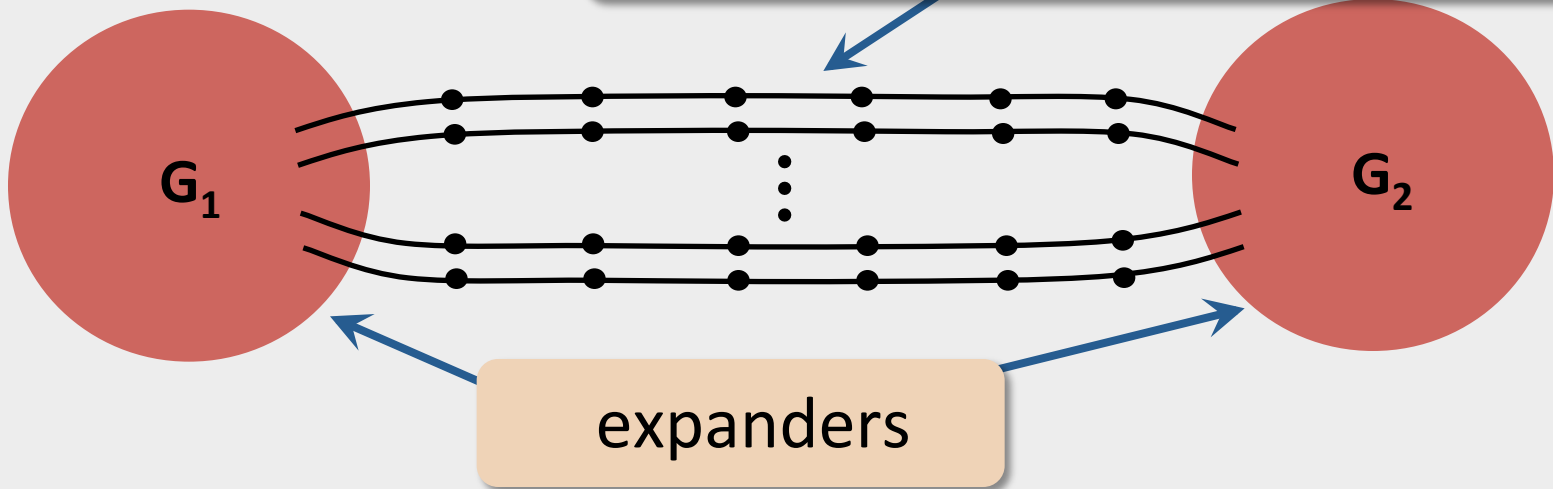
[Propp '09]: Computing good approx. to voltages suffices

Putting it all together: Generation of a random spanning tree in $\tilde{O}(mn^{1/2})$ time

Breaking the $\Omega(n^{3/2})$ barrier

[M. Straszak Tarnawski '14]

$\approx n^{1/2}$ paths with $\approx n^{1/2}$ vertices each



Problem: This graph has an $\Omega(n^{3/2})$ cover time and there is no nice way to cut it

To overcome this: Work with the “right” metric.

Connection IV: Cover and Commute Times of Random Walks

Recall (effective resistance between s and t):
 $R_{\text{eff}}(s,t)$ = potential difference $\phi_t - \phi_s$ induced by
an electrical flow f that sends a **unit current** from s to t

Can show: For any two vertices s and t

$$\text{CommuteTime}(s,t) = 2m R_{\text{eff}}(s,t)$$

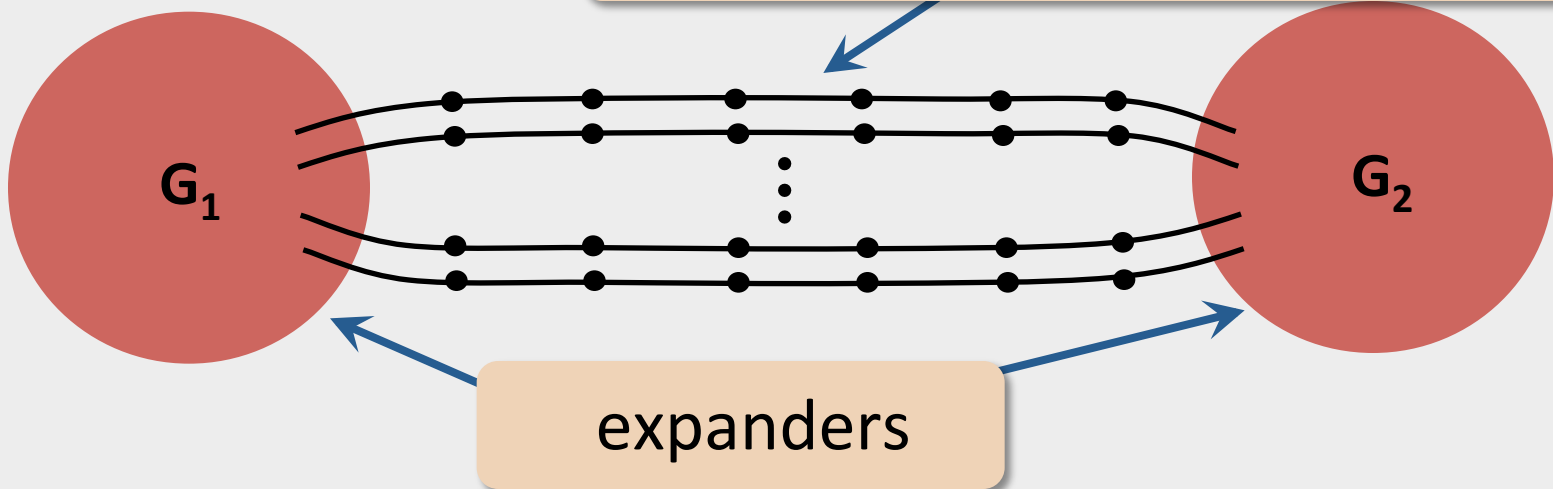
[Matthews '88]: For any subgraph D of **effective resistance diameter** γ

$$\text{CoverTime}(D) = O(m \gamma)$$

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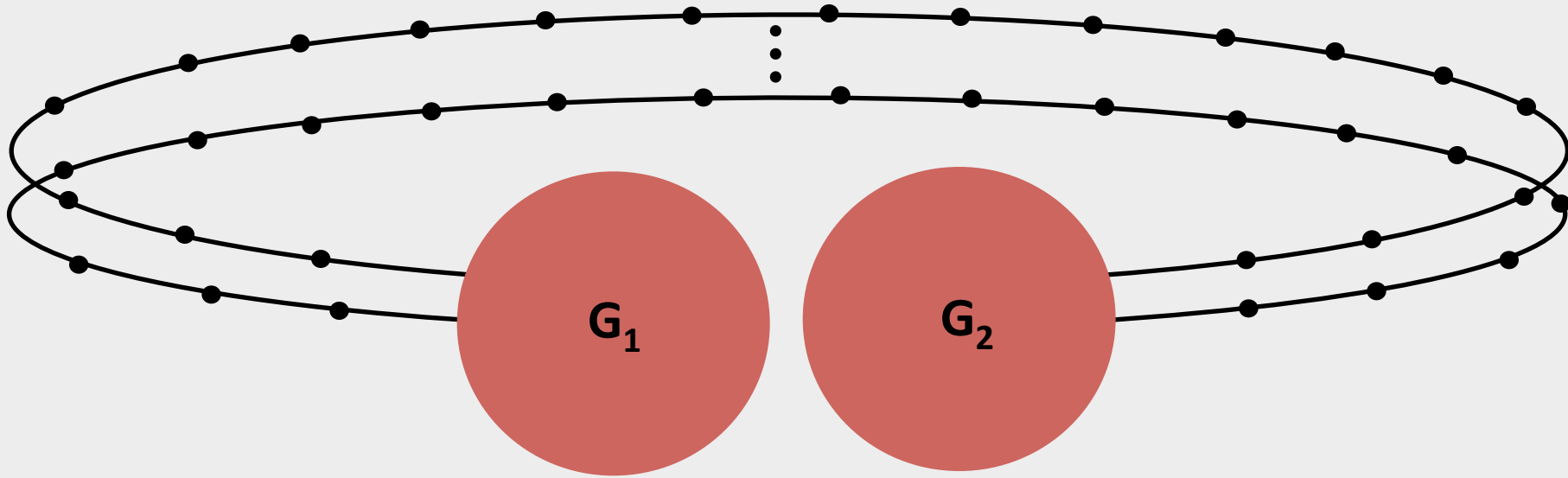
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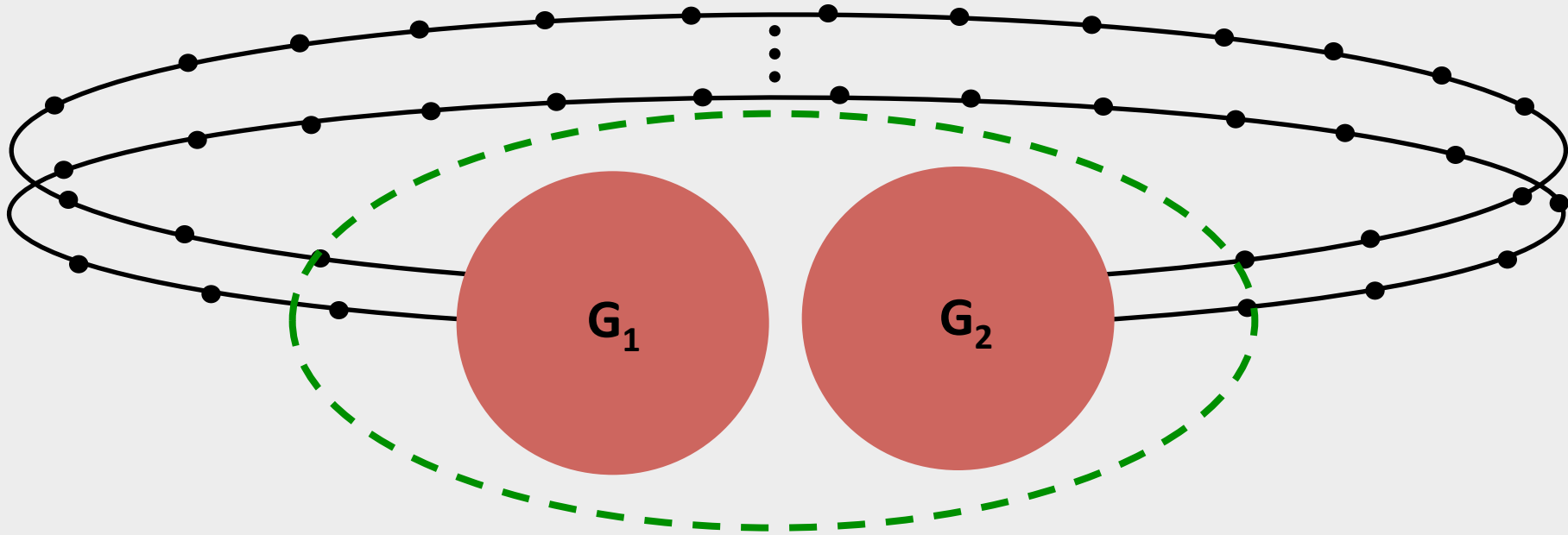
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This identifies a **large, low-diameter region** in the **effective resistance metric** with “**simple**” exterior

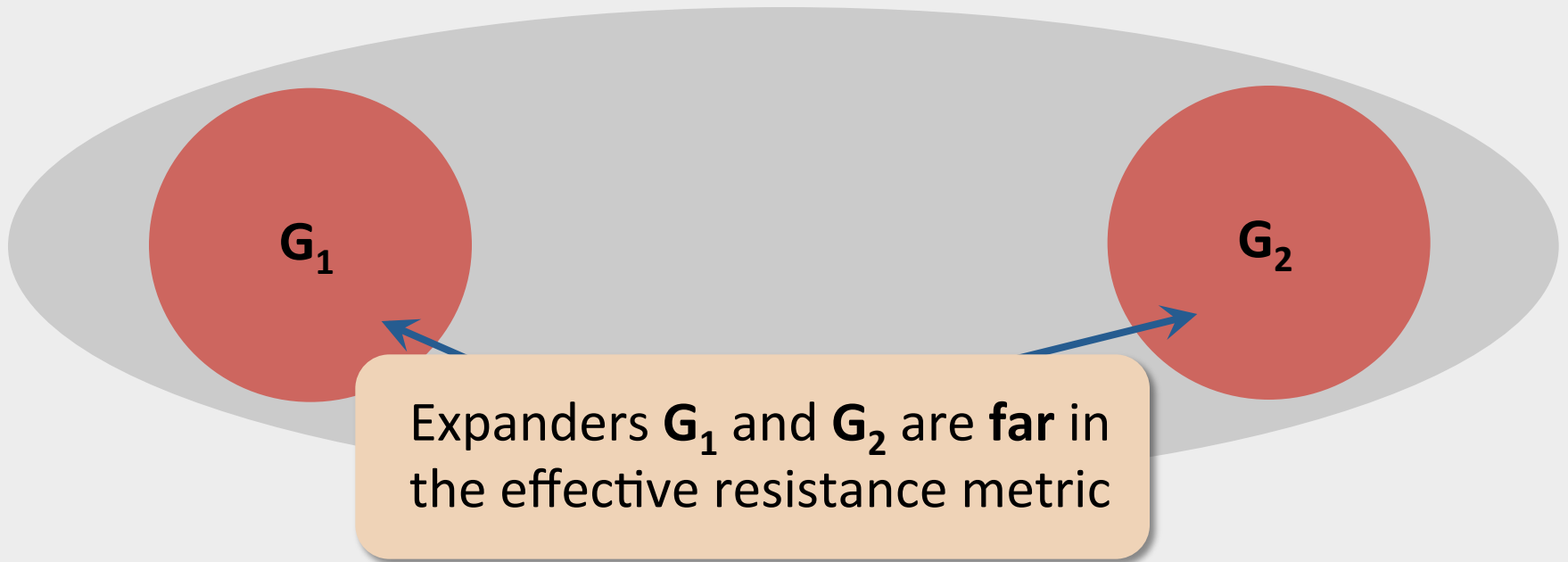
Effective resistance diam. vs. Cover time connection:

- Figure out how the tree looks like in this region quickly
- **Condition** on this choice (by modifying the graph) and proceed to next phase (we made a lot of progress!)

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[M. Straszak Tarnawski '14]

Missing element: What if the exterior of our large low-diameter region is **not** “simple”?

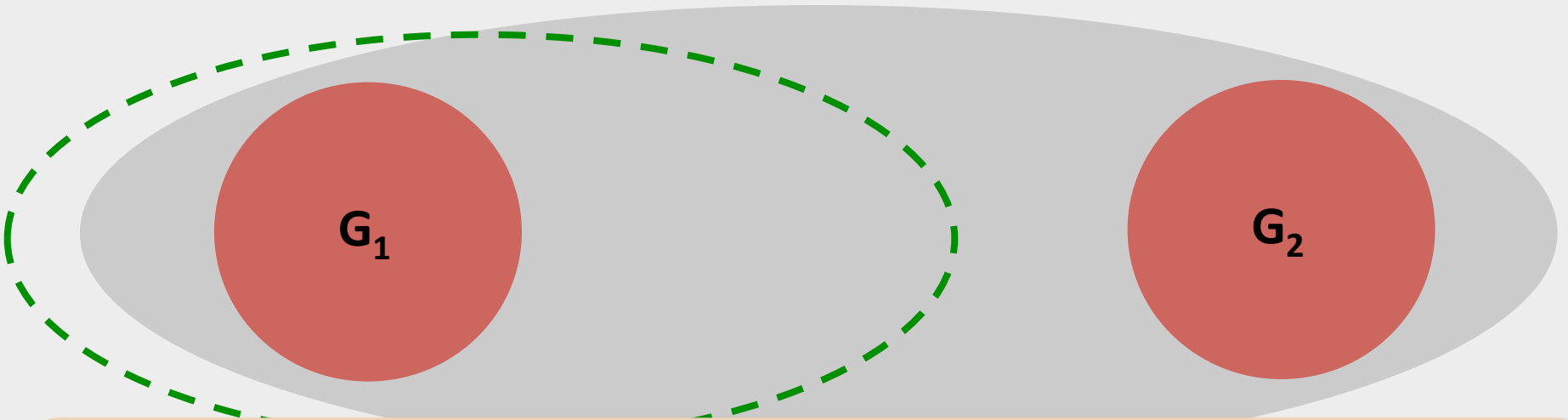


Tie effect. resist. to graph cuts: Argue that there exists a **good cut** separating the two regions

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Putting it all together: An $O(m^{4/3+o(1)})$ time sampling algorithm

Tie effect. resist. to graph cuts: Argue that there exists a **good cut** separating the two regions

Electrical Flows and Cuts

Electrical Flows and Sparsification [Spielman Srivastava '08]

A simple sparsification algorithm:

- Given graph \mathbf{G} , **compute** effective resistances $R_{\text{eff}}(\mathbf{e})$ of all edges
- **Sample** $\approx \varepsilon^{-2}n \log n$ edges **independently** (with replacements) and proportionally to their effective resistances $R_{\text{eff}}(\mathbf{e})$
- Take $\mathbf{H} = \mathbf{union}$ of all the sampled edges (after reweighting by an inverse of sampling probability)

[Spielman Srivastava '08]: Whp \mathbf{H} preserves all the cuts of \mathbf{G} up to a multiplicative error of $(1+\varepsilon)$

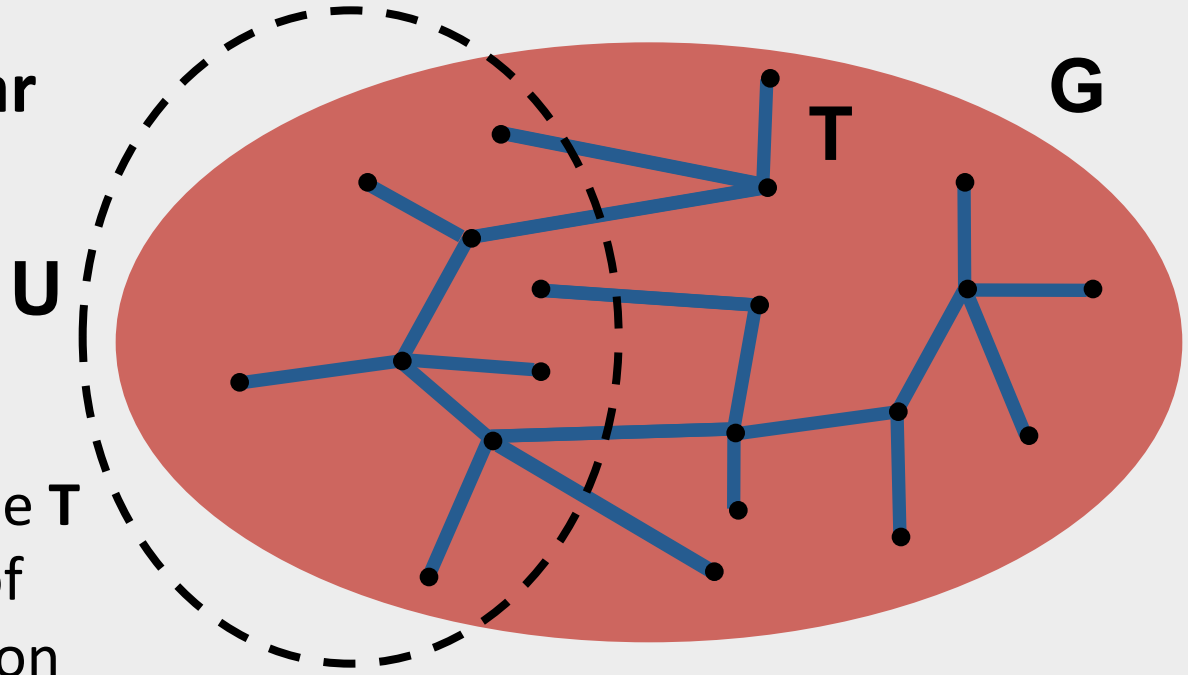
Bottom line: $R_{\text{eff}}(\mathbf{e})$ is a good measure of importance of an edge \mathbf{e} wrt connectivity.

Electrical Flows and Thin Trees

[Asadpour Goemans M. Oveis Gharan Saberi '10]

Assume: G k -regular
and k -connected

Think: Finding such tree T
is an “extreme” form of
(upper) cut sparsification



Spanning tree T is α -thin iff

$$\delta_T(U) \leq \alpha \delta_G(U)/k, \text{ for every cut } U$$

[Asadpour Goemans M. Oveis Gharan Saberi '10]:

Ability to find α -thin trees = $O(\alpha)$ -approx. to ATSP

Electrical Flows and Thin Trees

[Asadpour Goemans M. Oveis Gharan Saberi '10]

How to find good α -thin trees?

Independent sampling: Gives $\alpha = \Theta(\log n)$

A better way:

- (1) Compute weights w_e so as $\Pr[e \text{ in a rand. tree}]$ close to **uniform**
- (2) Sample a random spanning tree with respect to these weights

(1) \rightarrow All cuts are good in expectation

Negative correlation of random tree edge sampling
+ Karger's "trick" \rightarrow Gives $\alpha = \Theta(\log n / \log \log n)$

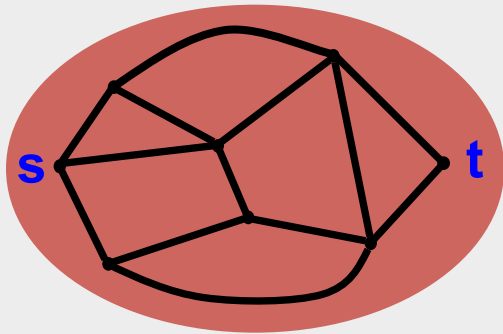
Can we do better?

[Markus Spielman Srivastava '13]+[Harvey Olver '14]:

Can get $\alpha = O(1)$ for a **spectral** analogue of the question

Conclusions

Electrical Flows and Graph Algorithms



Electrical flows: A powerful new tool for fast graph alg.

- Wealth of connections to graphs
- Very fast computation

Key question: Where else can electrical flows primitive be useful?

Electrical Flows and Graph Algorithms

Key question: Where else can electrical flows primitive be useful?

- Advancing our understanding of the convergence of interior-point methods? Inspire new types of IPMs?
- Better “spectral” graph algorithms? (Stability is the key?)
- What other properties of random walks we can get a hold on using electrical flows?
- Effective resistance metric as a basic way of looking at graphs? (Seems more robust than shortest-path metric)
- Theory of directed flows/walks?

Thank you

Questions?