

Information Collection and Reporting through Strategic Agents

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Bocconi University

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Quantifying Uncertainty: Stochastic, Adversarial, and Beyond
@ Simons Institute

Economics of Statistics

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 - ▶ strategic behavior

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 - ▶ data **collection**
 - ▶ information **reporting**
- ▶ Implications for **regulation**

Plan

Data: **HARD** information

1. Strategic sample selection
selective disclosure in “hard” data reporting
2. Persuasion bias
optional stopping in data collection

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Predictions: **SOFT** information

3. Forecasting contest
competition for best record
4. Reputational forecasting
reputation for accurate information

Impact of Sample Selection on Value of Information

Di Tillio-Ottaviani-Sørensen (EMA, 2021)

- ▶ Biased researchers in **observational studies**:
 - ▶ **select sample non randomly** from larger presample
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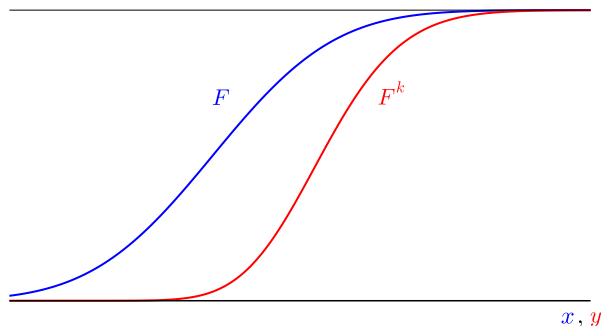
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- ▶ How does **sample selection** affect the **value of information**?

Impact of ANTICIPATED Selection

- ▶ Compare information value of two experiments:
 - ▶ **Random** : $X = \theta + \varepsilon$ with $\varepsilon \sim F$ [BLUE]
 - ▶ **Selected** : max of k iid draws: $Y = \theta + \varepsilon_{(k)}$ with $\varepsilon_{(k)} \sim F^k$ [RED]



Cournot (1843) on P-Hacking

“§101 ... A person not knowing how the data were analysed and whom the experimenter told the result of that analysis concerning the system ... but not **how many attempts he made** to achieve that result, is unable to judge with a determined chance of error whether the chances ... are equal or not...”

“... However, **unsuccessful tests usually leave no traces**; the public **only knows the results** which the experimenter thought to be deserving notice. It follows that a person alien to the testing is **absolutely unable** to regulate bets on **whether the result is, or is not attributable to anomalies of chance.**”

Illustration: Simple Hypothesis Testing

- ▶ Here we illustrate idea for **simple hypothesis testing**:

	θ_L	θ_H
reject	R	R
accept	θ_L	θ_H

$$\theta_L < R < \theta_H, \quad \text{prior } p = \Pr(\theta_H)$$

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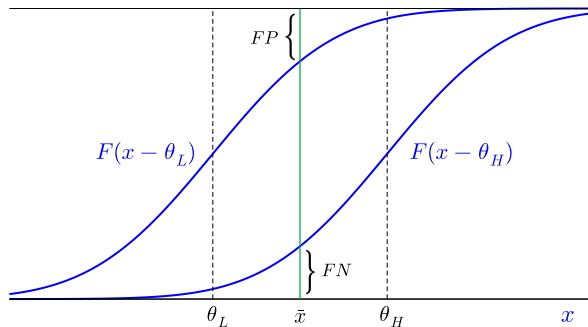
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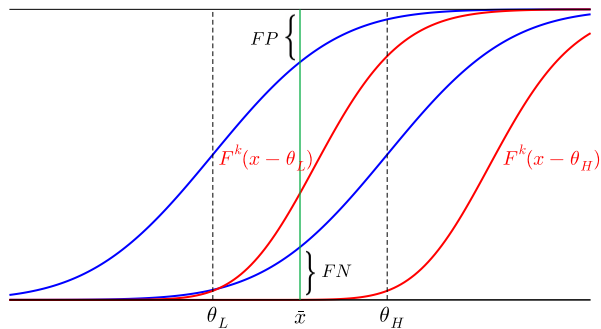
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- ▶ Location experiment $x = \theta + \varepsilon$, with $\varepsilon \sim F$ independent from θ
 - ▶ Assume **logconcave** density $f \Leftrightarrow$ monotone likelihood ratio property
- ▶ With a single draw, cutoff rule optimal: accept iff

$$\frac{f(x - \theta_H)}{f(x - \theta_L)} \geq \frac{1 - p}{p} \frac{R - \theta_L}{\theta_H - R} \Leftrightarrow x \geq \bar{x}$$

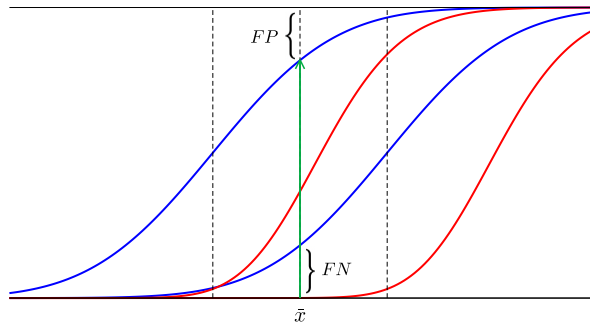
Random Experiment



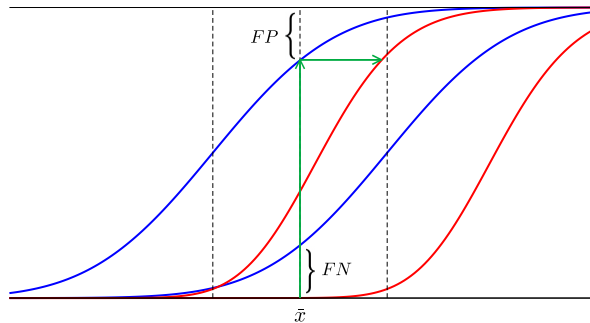
Selected Experiment



Random v. Selected



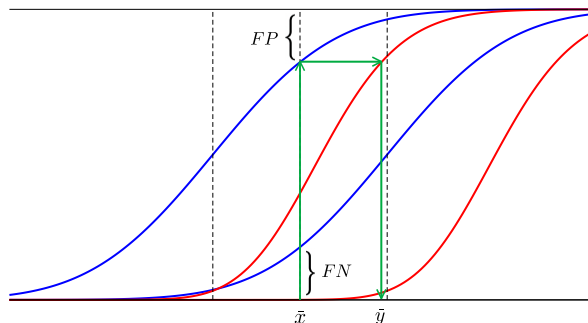
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$$\underbrace{1 - F^k(\bar{y} - \theta_L) = 1 - F(\bar{x} - \theta_L)}_{\text{Using cutoff } \bar{y} \text{ in } Y \text{ that matches False Positives}} \Rightarrow \bar{y} = (F^k)^{-1}F(\bar{x} - \theta_L) + \theta_L$$

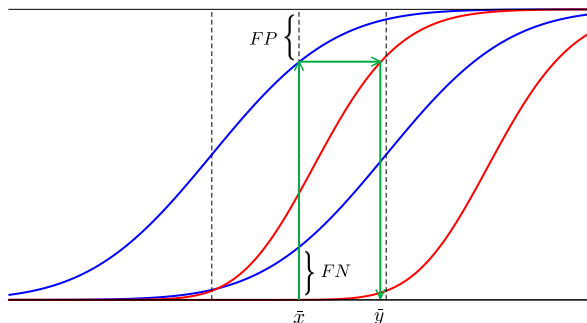
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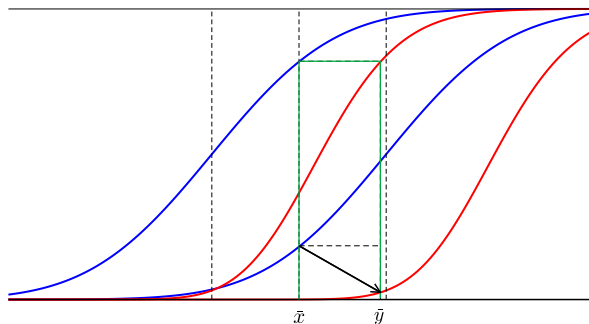
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Are False Negatives reduced? Yes, with F normal! More generally?

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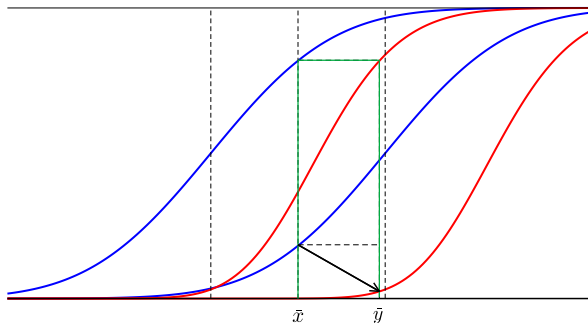
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$\Leftrightarrow F^k$ is **less dispersed** than F ie $(F^k)^{-1}(q) - F^{-1}(q) \searrow q$

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When is F^k steeper than F at same quantile?

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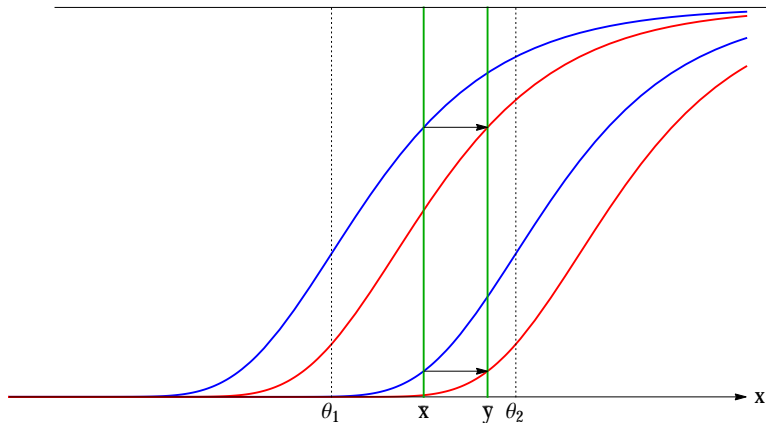
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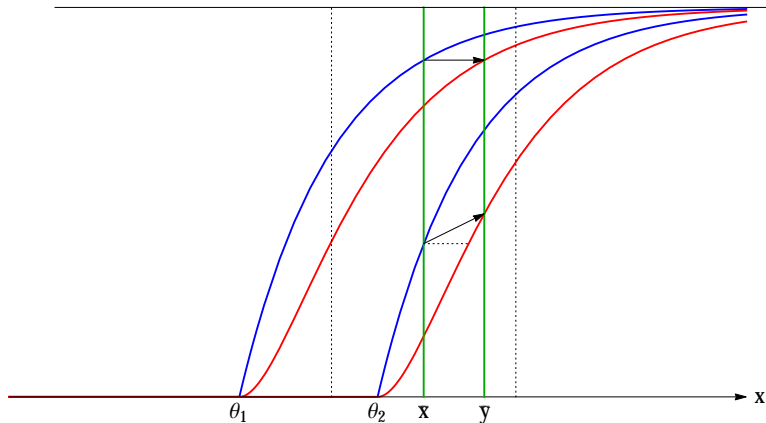
NEUTRAL Selection: Loglinear f/F

$$\text{Gumbel noise: } F(\varepsilon) = e^{-e^{-\varepsilon}}$$



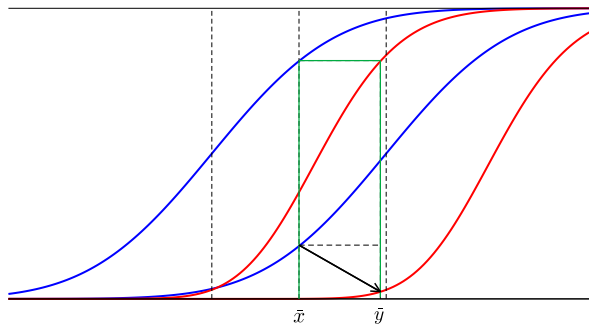
HARMFUL Selection: f LESS Logconcave than F

Exponential noise: $F(\varepsilon) = 1 - e^{-\varepsilon}$



BENEFICIAL Selection: f MORE Logconcave than F

Normal noise: $\varepsilon \sim \mathcal{N}$



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2. **Wald persuasion games** with costly information collection
 - ▶ optional stopping in data collection

Research and the Approval Process

Henry-Ottaviani (AER, 2019)

- ▶ Informer benefits from **approval** of drug with uncertain efficacy
 - ▶ **Evaluator** = FDA regulator

$\theta_e^H > 0$ in state H and $\theta_e^L < 0$ in state L

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 - ▶ instantaneous trial result from state-dependent Brownian motion
- ▶ Evaluator has **coarse instruments** for regulation
 - ▶ approve/reject, ask for additional evidence [impose liability]

Organizational Deconstruction of Wald

TWO players:

1. **Informer i**
 - a. directly **controls information** acquisition & pays info cost
 - b. but **always wants approval** and does not directly value info

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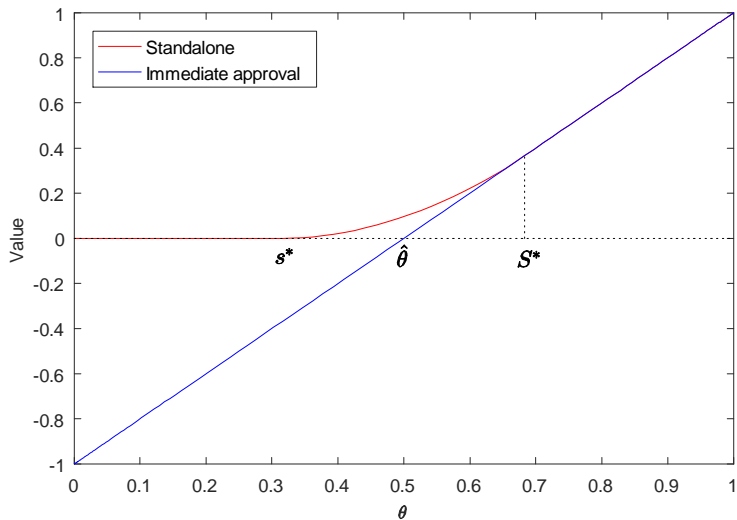
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Wald's **social planner w**

- a. controls **all decisions** (rejection/approval) & info acquisition
- b. obtains **total payoff** $v_w = \theta_e + v_i$ (evaluator+informer) & pays info cost

Wald Welfare Benchmark: Value Function



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► Planner (Wald) w : $\max_{s, S} u_w = u_e + u_i$

$$s = b_w(S) \text{ \& } S = B_w(s)$$

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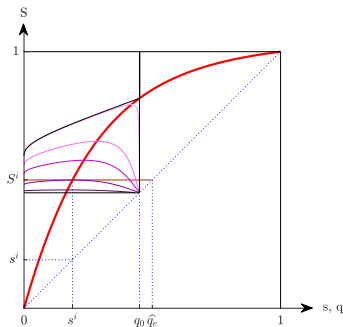
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3. Evaluator e Commitment: $\max_S u_e|_{s=b_i(S)}$

1. Informer Authority Game

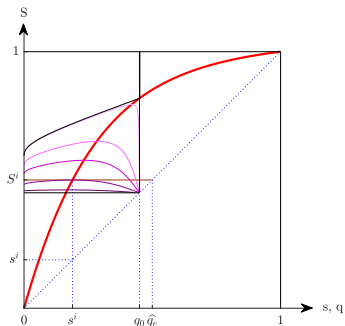
Informer Best Reply [RED]



- ▶ i 's best reply RED $s = b_i(S)$ **given** S [s on horizontal axis]

1. Informer Authority Game

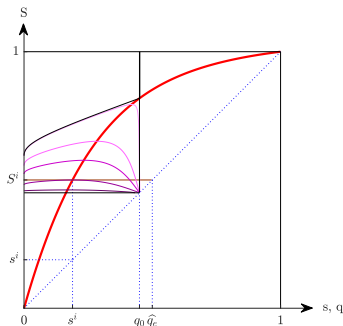
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 - ▶ locus of horizontal tangencies of iso-payoff curves PINK
 - ▶ $b_i(S) \nearrow S$: LOSS OF CONTROL

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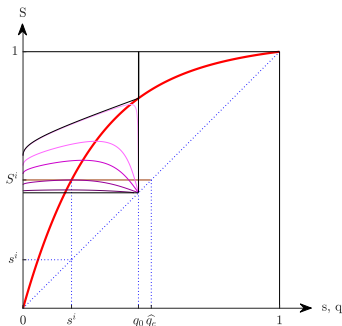
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- ▶ i expects e to adopt for $q \geq S$ [S on vertical axis]

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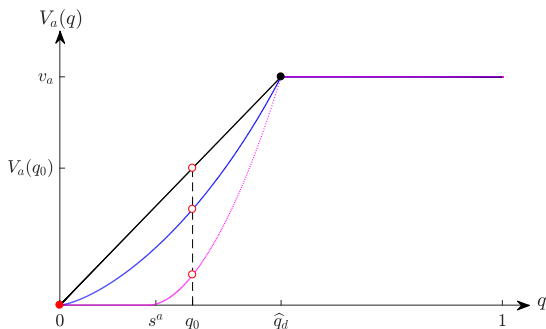
▶ TOP: Informer stops as soon as evaluator persuaded: $S^i = \hat{q}_e = \frac{-\theta_e^L}{\theta_e^H - \theta_e^L}$

Sequential Foundation of Bayesian Persuasion

- ▶ Comparison to Kamenica-Gentzkow's (2011) commitment solution?

Sequential Foundation of Bayesian Persuasion

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- ▶ We recover *KG without info frictions* if (1) $c \rightarrow 0$ & (2) $r \rightarrow 0$, so:
 - ▶ KG solution becomes **sequentially optimal** without commitment



2. No-Commitment “Nash” Outcome

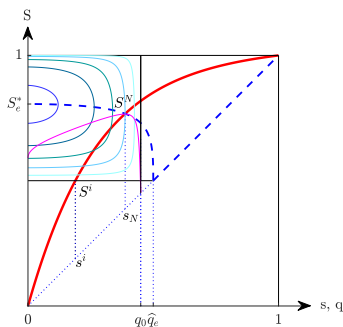
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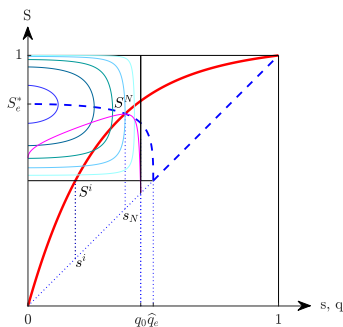
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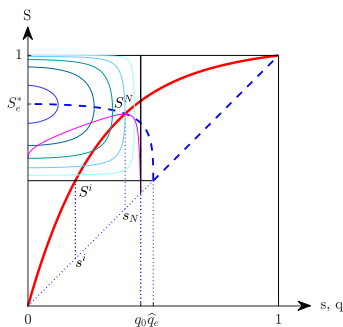
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- ▶ e sets **more stringent** approval standard: $S^N > S^i$
- ▶ i withdraws earlier: $s^N > s^i$

Plan

Data: HARD information

1. Hypothesis testing with **selected data**

- ▶ anticipated selection benefits/harms if data has thinner/thicker tail than Gumbel

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Honest Forecasting: Benchmark Statistical Model

- ▶ Unknown state with prior $x \sim N(\mu, \frac{1}{v})$
- ▶ Single forecaster with private signal s about state x
- ▶ Honest forecaster (naive statistician) minimizes forecast error

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- ▶ Best statistical forecast is posterior expectation

$$m = E[x|s]$$

- ▶ Forecasts are orthogonal to the forecast error
- ▶ Forecasts are dispersed, but less than the state

Forecasting Contest

Ottaviani-Sørensen (2006, J of Financial Economics)

Francis Galton's (1907) ox weight competition:

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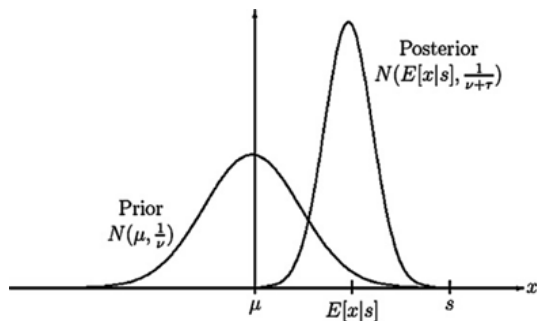
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4. Forecaster whose forecast is **closest** to the state wins

Forecasting Contest



- ▶ At the posterior expectation

$$m_i = E[x|s_i]$$

a small deviation away from the prior mean μ results in

- ▶ a **second-order loss** due to lower chance of winning, but
- ▶ a **first-order gain** due to reduced competition

Excessive Differentiation in Forecasting Contest

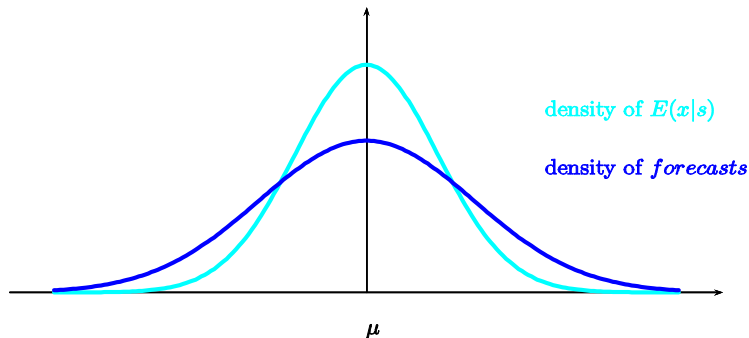


Figure: Equilibrium forecasts are more variable than posterior expectation

Reputational Cheap Talk

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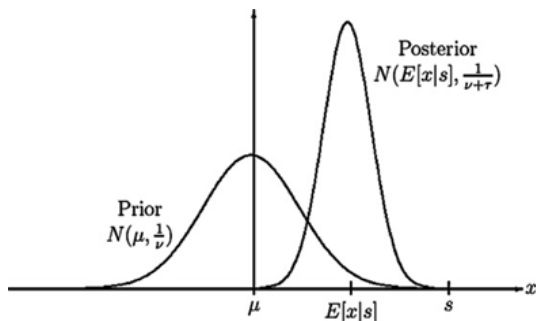
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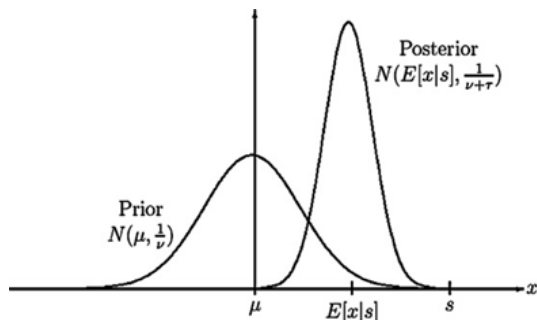
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 - ▶ Forecast m is a (cheap talk) signal
 - ▶ **Is honest $m = E[x|s]$ an equilibrium?**

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- ▶ If evaluator (naïvely) expects honest forecasting $m = E[x|s]$
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- ▶ If evaluator (naïvely) expects honest forecasting $m = E[x|s]$
 - ▶ Will forecaster want to report honestly?
- ▶ With location signal, forecaster has **incentive to lie** reporting

$$E[x|\hat{s} = E[x|s]],$$

Reputational Cheap Talk Equilibrium

- ▶ Equilibrium communication is coarse (as in Crawford and Sobel, 1982)
 - ▶ Forecasters with signals in an interval send identical message
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 - ▶ Forecasters with signals in an interval send identical message
 - ▶ Loss of forecast accuracy!
- ▶ E.g., there exists a two-message equilibrium:
 - ▶ Report whether s is above or below prior mean $E[x]$

Forecasting Summary

- ▶ Concern for accuracy leads to:
 - ▶ excessive conformity if the market is naïve
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- ▶ Competition for best accuracy record leads to excessive differentiation

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