## "Calibeating": Beating Forecasters at Their Own Game

**Sergiu Hart** 

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#### Joint work with

### Dean P. Foster

University of Pennsylvania & Amazon Research NY

# **Papers**

## **Papers**

- Dean P. Foster and Sergiu Hart "Forecast Hedging and Calibration"
  - First version: 2016
  - Journal of Political Economy, 2021

www.ma.huji.ac.il/hart/publ.html#calib-int

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- Dean P. Foster and Sergiu Hart "'Calibeating': Beating Forecasters at Their Own Game"
  - First version: 2020
  - Center for Rationality DP-743, 2021

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www.ma.huji.ac.il/hart/publ.html#calib-beat
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- Forecaster says: "The probability of rain tomorrow is p"
- Forecaster is CALIBRATED if
  - for every forecast p: in the days when the forecast was p, the proportion of rainy days equals p(or: is close to p in the long run)

**CALIBRATION** can be guaranteed

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(no matter what the weather will be)

Foster and Vohra 1994 [publ 1998]

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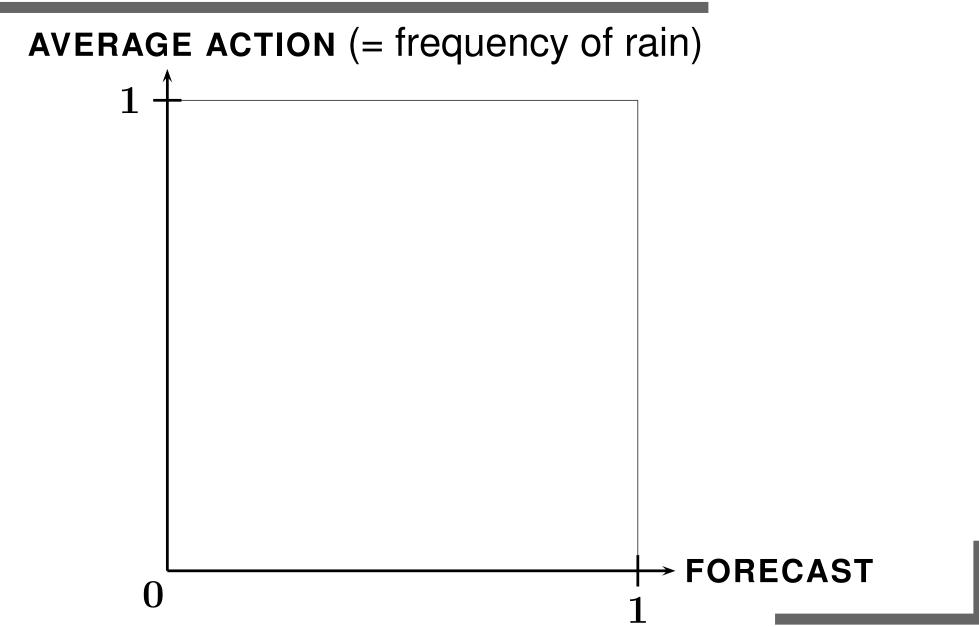
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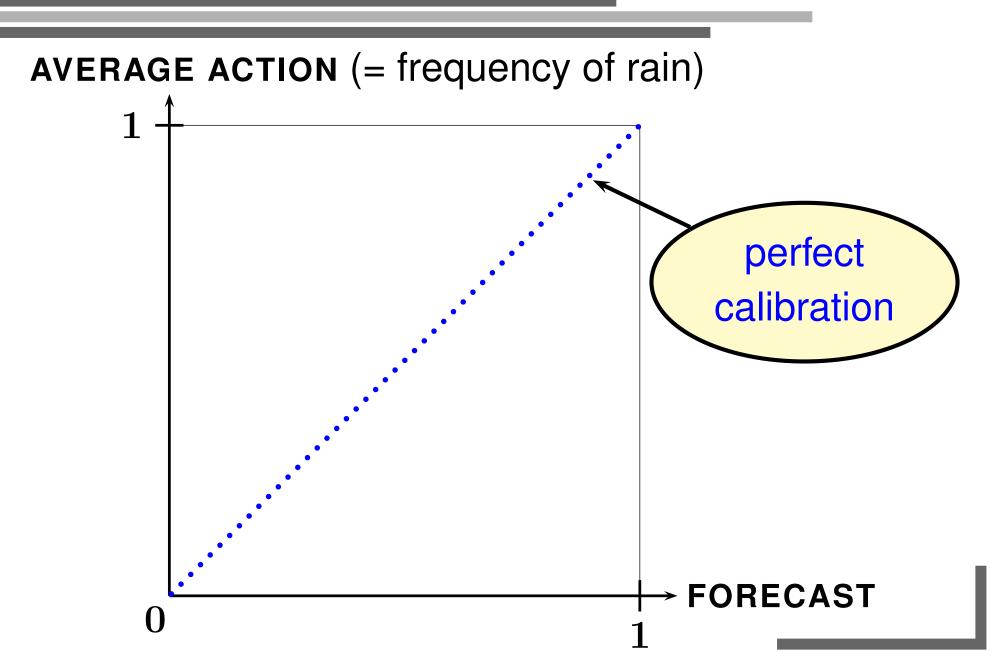
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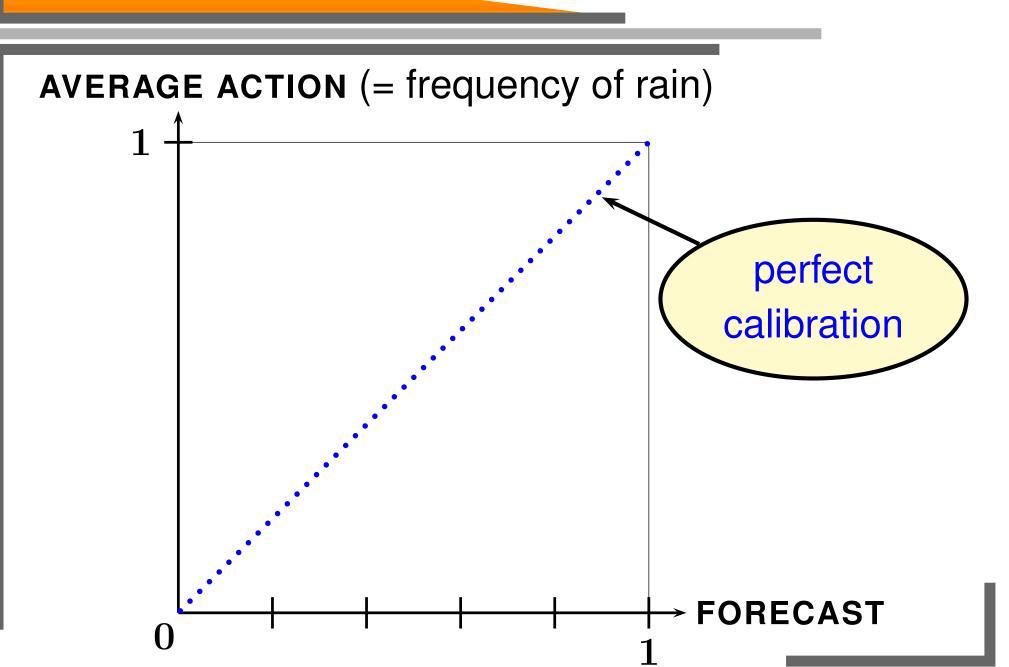
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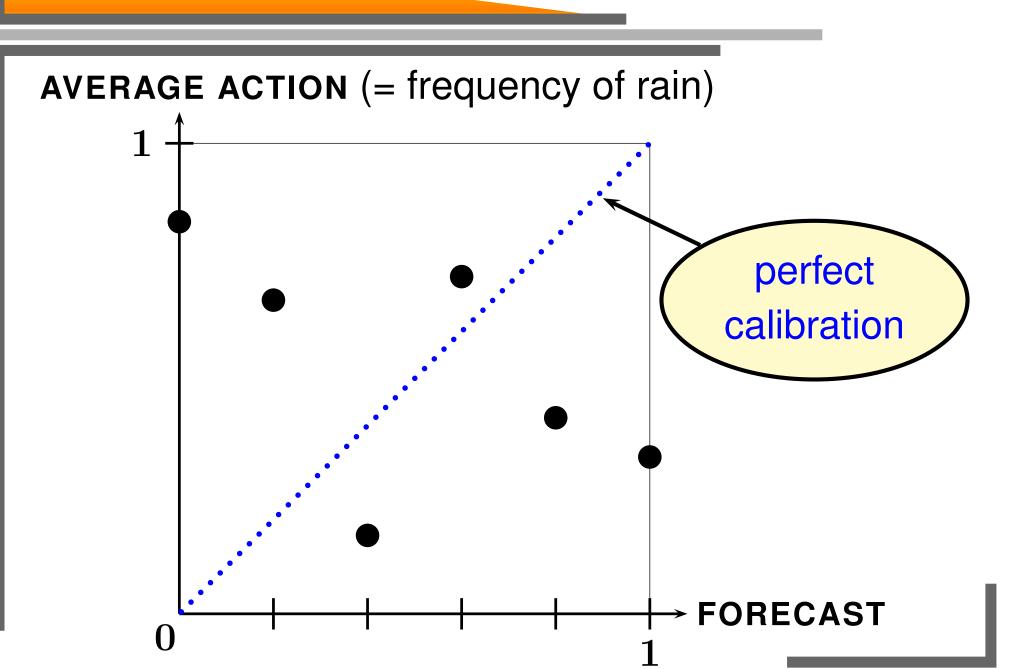
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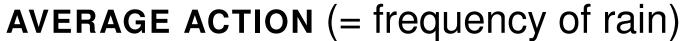
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- Foster and Hart 2016 [publ 2021]: simplest procedure, by "Forecast Hedging"

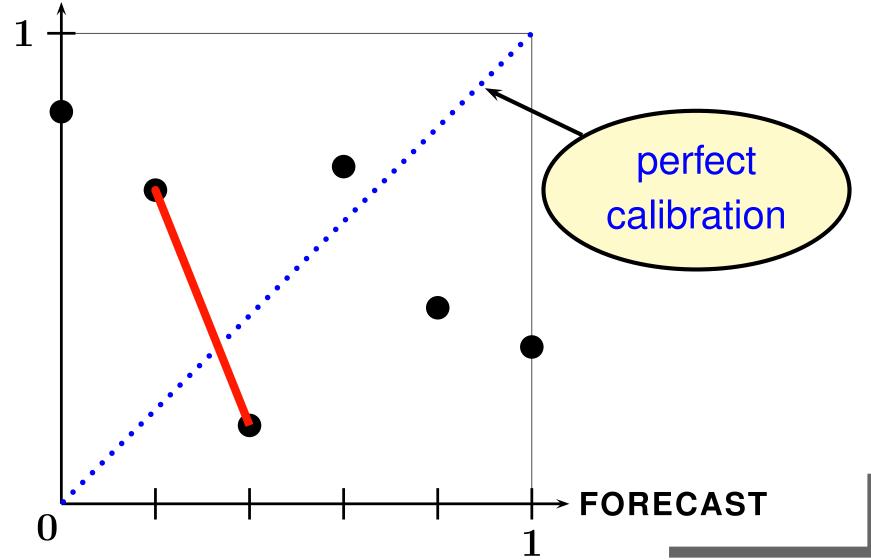


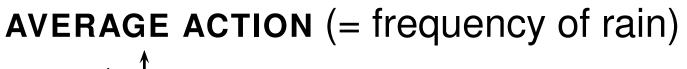


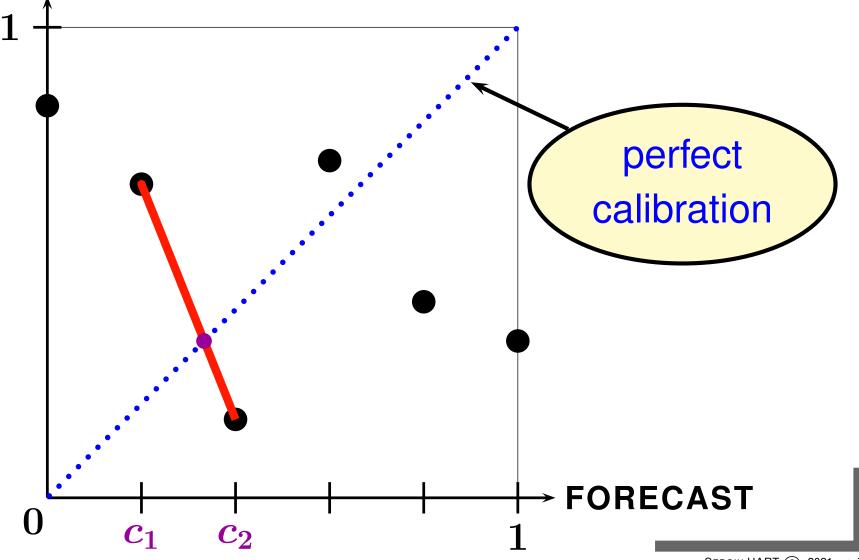






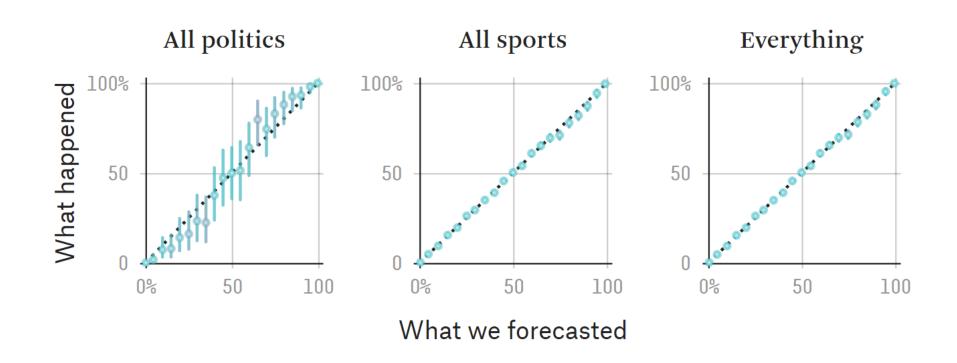






### **Calibration in Practice**

### Calibration in Practice



Calibration plots of FiveThirtyEight.com (as of June 2019)

### Calibration in Practice



**Prediction buckets** 

Calibration plot of ElectionBettingOdds.com (2016 – 2018)

time | 1 | 2 | 3 | 4 | 5 | 6 | ...

time	$oxed{1}$	2	3	4	5	6	
rain	1	0	1	0	1	0	

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

time	1	2	3	4	5	6	•••
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F1: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0

F2: CALIBRATION = 0

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0 IN-BIN VARIANCE = 0

F2: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0 IN-BIN VARIANCE = 0

F2: CALIBRATION = 0 IN-BIN VARIANCE =  $\frac{1}{4}$ 

•  $a_t = action at time t$ 

- $m{a}_t = ext{action at time } t$
- $c_t$  = forecast at time t

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$$ar{a}(x) = rac{\sum_{t=1}^T \mathbf{1}_x(oldsymbol{c}_t)\,a_t}{\sum_{t=1}^T \mathbf{1}_x(oldsymbol{c}_t)}$$

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$$\mathcal{K} = rac{1}{T} \sum_{t=1}^T \| oldsymbol{c}_t - ar{a}(oldsymbol{c}_t) \|^2$$

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**B**RIER = REFINEMENT + CALIBRATION

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$$\mathcal{B} = \mathcal{R} + \mathcal{K}$$

**BRIER** = REFINEMENT + CALIBRATION

Proof.

$$\mathbb{E}[(X-c)^2] = \mathbb{V}ar(X) + (ar{X}-c)^2$$

where c is a constant and  $oldsymbol{X}$  is a random variable with  $ar{oldsymbol{X}} = \mathbb{E}[oldsymbol{X}]$ 

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F1: 
$$\mathcal{K} = 0$$
  $\mathcal{R} = 0$ 

F2: 
$$K = 0$$
  $R = \frac{1}{4}$ 

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

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$$\mathcal{K} = 0$$
  $\mathcal{R} = 0$   $\mathcal{B} = 0$ 

F2: 
$$K = 0$$
  $R = \frac{1}{4}$   $B = \frac{1}{4}$ 

**Testing experts:** 

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- **✓ Brier** score
- X CALIBRATION score

Recognize patterns and regularities in the data

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**LOW** REFINEMENT SCORE

## "Expertise" and Calibration

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#### **Question:**

Can one GAIN CALIBRATION without LOSING "EXPERTISE"?

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ullet Can one get  $\mathcal K$  to 0 without increasing  $\mathcal R$ ?

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#### **Question:**

Can one GAIN CALIBRATION without LOSING "EXPERTISE"?

- Can one get K to 0 without increasing R?
- Can one decrease  $\mathcal{B} = \mathcal{R} + \mathcal{K}$  by  $\mathcal{K}$ ?

Can one decrease B by K?

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$$\Rightarrow \mathcal{K}' = 0 \quad \mathcal{R}' = \mathcal{R}$$

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$$\Rightarrow \mathcal{K}' = 0$$
  $\mathcal{R}' = \mathcal{R}$   $\mathcal{B}' = \mathcal{B} - \mathcal{K}$ 

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• IN RETROSPECT / OFFLINE (when the  $\bar{a}(c)$  are known)

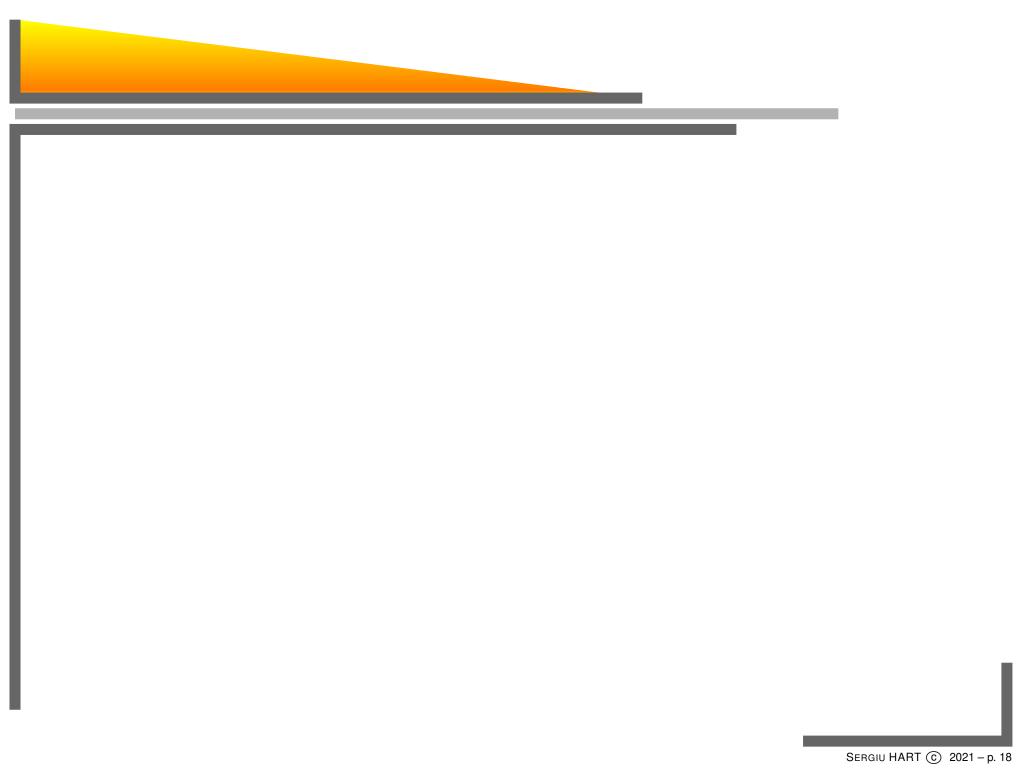
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• IN RETROSPECT / OFFLINE (when the  $\bar{a}(c)$  are known)

#### **Question:**

Can one do this **ONLINE**?



• Consider a forecasting sequence  $b_t$  (in a [finite] set B)

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$$\mathcal{B}_T^{\mathrm{c}} \leq \mathcal{B}_T^{\mathrm{b}} - \mathcal{K}_T^{\mathrm{b}} + \mathrm{o}(1) \quad \mathrm{as} \ T \to \infty$$

for ALL sequences  $a_t$  and  $b_t$  (uniformly)

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 $oldsymbol{c}$  "BEATS" b by b 's CALIBRATION score

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GUARANTEED for ALL sequences of actions and forecasts

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
b	80%	40%	80%	40%	80%	40%	
		•				•	

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rain	1	0	1	0	1	0	
b	80%	40%	80%	40%	80%	40%	
		•		•		•	

b: 
$$K^{\rm b} = 0.1$$
  $R^{\rm b} = 0$   $R^{\rm b} = 0.1$ 

$$\mathcal{R}^{\mathrm{b}}=0$$

$$\mathcal{B}^{\mathrm{b}}=0.1$$

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
$\overline{b}$	80%	40%	80%	40%	80%	40%	
c	100%	0%	100%	0%	100%	0%	

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$${\cal B}^{\rm b} = 0.1$$

c: 
$$\mathcal{K}^{c} = 0$$
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$$\mathcal{R}^{\mathrm{c}} = 0$$

$$\mathcal{B}^{c} = 0$$

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c calibeats b:  $\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$ 

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c: 
$$\mathcal{K}^{c} = 0$$
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c calibeats b:  $\mathcal{B}^{\mathrm{c}} \leq \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}} = \mathcal{R}^{\mathrm{b}}$ 

(that was easy ...)

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Can one CALIBEAT in general, non-stationary, situations?

Weather is arbitrary and not stationary

(that was easy ...)

- Weather is arbitrary and not stationary
- Forecasts of b are arbitrary

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(that was easy ...)

Can one CALIBEAT in general, non-stationary, situations?

- Weather is arbitrary and not stationary
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- **Binning of** b is not perfect ( $\mathcal{R}^{b} > 0$ )
- Bin averages do not converge
- ONLINE
- GUARANTEED (even against adversary)

# A Simple Way to Calibeat

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### **Theorem**

The procedure

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

**GUARANTEES b-CALIBEATING** 

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### **Theorem**

The procedure

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**GUARANTEES b-CALIBEATING** 

Forecast the average action of the current *b*-forecast

$$\mathbb{V} ext{ar} \; = \; rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2$$

$$\mathbb{V} ext{ar} \ = \ rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T\|^2 \ = \ rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}\|^2$$

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ight) \|x_t - ar{x}_{t-1}^T\|^2$$

$$\mathbb{V} ext{ar} \ = \ rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T\|^2 \ = \ rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}\|^2$$

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left( 1 - rac{1}{t} 
ight) \left\| x_t - ar{x}_{t-1} 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_{t-1} 
ight\|^2 - \mathrm{o}(1) \end{array}$$

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left( 1 - rac{1}{t} 
ight) \left\| x_t - ar{x}_{t-1} 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_{t-1} 
ight\|^2 - \mathrm{o}(1) \end{array}$$

(\*) 
$$o(1) = O\left(\frac{1}{T}\sum_{t=1}^{T} \frac{1}{t}\right) = O\left(\frac{\log T}{T}\right)$$

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left( 1 - rac{1}{t} 
ight) \left\| x_t - ar{x}_{t-1} 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_{t-1} 
ight\|^2 - \mathrm{o}(1) \end{array}$$

## **Proof: "Online Variance"**

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left( 1 - rac{1}{t} 
ight) \left\| x_t - ar{x}_{t-1} 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_{t-1} 
ight\|^2 - \mathrm{o}(1) \ &=& \widetilde{\mathbb{V} \mathrm{ar}} & - \mathrm{o}(1) \end{array}$$

## **Proof: "Online Variance"**

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$

## **Proof: "Online Refinement"**

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$
 $\mathcal{R}^\mathrm{b} = \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1)$ 

## **Proof: "Online Refinement"**

$$egin{array}{lll} \mathbb{V}\mathrm{ar} &=& \widetilde{\mathbb{V}}\mathrm{ar} - \mathrm{o}(1) \ & \mathcal{R}^\mathrm{b} &=& \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1) \ &=& rac{1}{T} \sum_{t=1}^T \|a_t - ar{a}_{t-1}(b_t)\|^2 - \mathrm{o}(1) \end{array}$$

### **Proof: "Online Refinement"**

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$
 $\mathcal{R}^\mathrm{b} = \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1)$ 
 $= \frac{1}{T} \sum_{t=1}^{T} \|a_t - \bar{a}_{t-1}(b_t)\|^2 - \mathrm{o}(1)$ 
 $= \mathcal{B}^\mathrm{c} - \mathrm{o}(1)$ 

### **Theorem**

$$\left[ oldsymbol{c}_t = ar{a}_{t-1}^{\mathrm{b}}(b_t) 
ight]$$

#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$$

## **Self-Calibeating**

### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{c} < \mathcal{B}^{b} - \mathcal{K}^{b}$$

#### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

#### **GUARANTEES C-CALIBEATING:**

$$\mathcal{B}^{c} < \mathcal{B}^{c} - \mathcal{K}^{c}$$

## **Self-Calibeating**

### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$$

#### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

#### **GUARANTEES C-CALIBEATING:**

$$\beta^{c} \leq \beta^{c} - \mathcal{K}^{c}$$

$$\Leftrightarrow \mathcal{K}^{c} = 0$$

# **Self-Calibeating** = Calibrating

### **Theorem**

$$oxed{c_t = ar{a}_{t-1}^{\mathrm{b}}(b_t)}$$

#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{\mathrm{c}} < \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}}$$

#### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

#### **GUARANTEES CALIBRATION:**

$$\beta^{c} \leq \beta^{c} - \mathcal{K}^{c}$$

$$\Leftrightarrow \mathcal{K}^{c} = 0$$

### "Fixed Point"

How do we get  $c_t$  "close to"  $\bar{a}_{t-1}(c_t)$ ?

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$$\mathbb{E}_{\boldsymbol{c}}\left[\left\|x-\boldsymbol{c}
ight\|^2-\left\|x-g(\boldsymbol{c})
ight\|^2
ight]\leq \delta^2$$

How do we get  $c_t$  "close to"  $\bar{a}_{t-1}(c_t)$ ?

$$\mathbb{E}_{\boldsymbol{c}}\left[\left\|x-\boldsymbol{c}\right\|^2-\left\|x-g(\boldsymbol{c})\right\|^2\right]\leq \delta^2$$

- $m{\mathcal{L}} \subset \mathbb{R}^m$  compact convex
- $m{ ilde{ ilde{}}} D \subset C$  finite  $\delta$ -grid of C for  $\delta>0$
- $m{g}:m{D} o\mathbb{R}^m$  arbitrary function

How do we get  $c_t$  "close to"  $\bar{a}_{t-1}(c_t)$ ?

Theorem There exists a probability distribution on (a  $\delta$ -grid D of) C such that for every  $x \in C$ 

$$\mathbb{E}_{\boldsymbol{c}}\left[\left\|x-\boldsymbol{c}\right\|^2-\left\|x-g(\boldsymbol{c})\right\|^2\right]\leq \delta^2$$

- $m{\mathcal{L}} \subset \mathbb{R}^m$  compact convex
- $m{ ilde{ ilde{}}} D \subset C$  finite  $\delta$ -grid of C for  $\delta>0$
- $m{g}:m{D} o\mathbb{R}^m$  arbitrary function

Obtained by solving a Minimax problem (LP)

## **Outgoing Minimax (FH)**

How do we get  $c_t$  "close to"  $\bar{a}_{t-1}(c_t)$ ?

Theorem There exists a probability distribution on (a  $\delta$ -grid D of) C such that for every  $x \in C$ 

$$\mathbb{E}_{\boldsymbol{c}}\left[\left\|x-\boldsymbol{c}\right\|^2-\left\|x-g(\boldsymbol{c})\right\|^2\right]\leq \delta^2$$

- $m{\mathcal{L}} \subset \mathbb{R}^m$  compact convex
- $D \subset C$  finite  $\delta$ -grid of C for  $\delta > 0$
- $m{g}:m{D} o\mathbb{R}^m$  arbitrary function

Obtained by solving a Minimax problem (LP)

Theorem There exists a probability distribution on (a  $\delta$ -grid D of) C such that for every  $x \in C$ 

$$\mathbb{E}_{\boldsymbol{c}}\left[\left\|x-\boldsymbol{c}\right\|^2-\left\|x-g(\boldsymbol{c})\right\|^2\right]\leq \delta^2$$

Obtained by solving a Minimax problem (LP)

$$\mathbb{E}_{\boldsymbol{c}}\left[\left\|x-\boldsymbol{c}\right\|^2-\left\|x-g(\boldsymbol{c})\right\|^2\right]\leq \delta^2$$

- Obtained by solving a Minimax problem (LP)
- Moreover, solving a Fixed Point problem yields a probability distribution that is **ALMOST DETERMINISTIC**: its support is included in a ball of size  $\delta$

### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBRATION** 

### **Theorem**

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*Proof.* Self-calibeating + Outgoing Minimax

### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBRATION** 

*Proof.* Self-calibeating + Outgoing Minimax

Note.  $\delta$ -CALIBRATION

# **Calibrated Calibeating**

### **Calibrated Calibeating**

### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBEATING** 

### **Calibrated Calibeating**

#### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBEATING** and **CALIBRATION** 

### **Calibrated Calibeating**

### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBEATING** and **CALIBRATION** 

*Proof.* Calibeat the joint binning of b and c, by the Outgoing Minimax theorem

#### **Theorem**

There is a *deterministic* procedure that **GUARANTEES** 

simultaneous CALIBEATING of several forecasters

#### **Theorem**

There is a **stochastic** procedure that **GUARANTEES** 

simultaneous CALIBEATING of several forecasters

and **CALIBRATION** 

### **Theorem**

There is a **stochastic** procedure that **GUARANTEES** 

simultaneous CALIBEATING of several forecasters

and **CALIBRATION** 

Proof. Calibeat the joint binning

### In all the results above:

#### In all the results above:

	CALIBRATION	
Obtained by	Minimax	
Procedure	stochastic	

### ... and Continuous Calibration

#### In all the results above:

	CALIBRATION	CONTINUOUS
Obtained by	Minimax	Fixed Point
Procedure	stochastic	deterministic

#### TAKING PRIDE IN OUR RECORD

#### TAKING PRIDE IN OUR RECORD

"We have correctly forecasted 8 of the last 5 recessions"



#### TAKING PRIDE IN OUR RECORD

"We have correctly forecasted 8 of the last 5 recessions"