New algorithms for the graph alignment problem

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Alignment of Graphs

From graph 1 (on the left), put indices on its vertices, perturb the graph by adding and removing a few edges and remove indices to obtain graph 2 (on the right).

Task : recover the indices on vertices of graph 2.



Green vertices are good predictions. Red vertices are errors (graph 2).



Green vertices are good predictions. Red vertices are errors (graph 1).



Here are the 'wrong' matchings or cycles.



Superposing the 2 graphs : green edges in both, orange and blue edges in graph 1 and 2 resp.



Result with FGNN

Matched edges.



Mismatched edges.



Green vertices are well paired vertices. Red vertices are errors.



Theoretical results

Two graphs G and G' with the same set of nodes [n] and with respectively blue and red edges. The blue and red edges are obtained by sampling uniformly at random :

- with probability $\lambda s/n$ to get two-colored edges;
- with probability $\lambda(1-s)/n$ to get a blue (monochromatic) edge;
- with probability $\lambda(1-s)/n$ to get a red (monochromatic) edge;
- with probability $1 \lambda(2 s)/n$ to get a non-edge,

where $\lambda > 0$ and $s \in [0, 1]$ are fixed parameters when *n* will tend to infinity.



We then relabel the vertices of the red graph \mathcal{G}' with an uniform independent permutation $\pi^* \in S_n$, and we observe \mathcal{G} and $\mathcal{H} := \mathcal{G}'^{\pi^*}$. The marginals \mathcal{G}, \mathcal{H} are Erdős-Rényi random graphs with average degree λ . The goal is to estimate the latent vertex correspondence π^* .





Dependence of joint distribution in $e(G \land G')$:

$$\mathbb{P}(\mathcal{G} = \mathsf{G}, \mathcal{G}' = \mathsf{G}') \propto \left[\frac{\mathsf{s}(n - \lambda(2 - \mathsf{s}))}{\lambda(1 - \mathsf{s})^2}\right]^{\mathsf{e}(\mathsf{G} \wedge \mathsf{G}')}$$

MAP estimator of π^* is the solution of the QAP problem :

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In the rest of this talk, we consider the sparse regime where the average degree λ is not scaling with **n**.

For any subset $\mathcal{C} \subset [n]$, the performance of any one-to-one estimator $\hat{\sigma} : \mathcal{C} \rightarrow [n]$

$$\operatorname{ov}(\pi^*, \hat{\sigma}) := \frac{1}{n} \sum_{i \in \mathcal{C}} \mathbf{1}_{\hat{\sigma}(i) = \pi^*(i)}.$$

Note that the estimator $\hat{\sigma}$ only consists in a partial matching. The *error* fraction of $\hat{\sigma}$ with the unknown permutation π^* is defined as

$$\operatorname{err}(\pi^*, \hat{\sigma}) := \frac{1}{n} \sum_{i \in \mathcal{C}} \mathbf{1}_{\hat{\sigma}(i) \neq \pi^*(i)} = \frac{|\mathcal{C}|}{n} - \operatorname{ov}(\pi^*, \hat{\sigma}).$$

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A sequence of injective estimators $\{\hat{\sigma}_n\}_n$ is said to achieve

- Partial recovery if there exists some $\epsilon > \mathbf{0}$ such that $\mathbb{P}(\operatorname{ov}(\pi^*, \hat{\sigma}) > \epsilon) \underset{n \to \infty}{\longrightarrow} \mathbf{1},$
- One-sided partial recovery if it achieves partial recovery and $\mathbb{P}(\operatorname{err}(\pi^*, \hat{\sigma}) = o(1)) \underset{n \to \infty}{\longrightarrow} 1.$











For $i \in V(\mathcal{G}), u \in V(\mathcal{H})$, look at the neighborhoods \mathcal{N}_i and \mathcal{N}_u at depth d:

- if $u = \pi^*(i)$, $(\mathcal{N}_i, \mathcal{N}_u) \simeq \text{GW}$ trees of offspring $\text{Poi}(\lambda)$, with intersection of offspring $\text{Poi}(\lambda s)$ (model $\mathbb{P}_{1,d}$);
- if u ≠ π*(i), (N_i, N_u) ≃ independent GW trees of offspring Poi(λ) (model P_{o,d}).

Hypothesis testing : Can we test $\mathbb{P}_{1,d}$ versus $\mathbb{P}_{0,d}$?

Computing the likelihood ratio



For two trees of depth d, the likelihood ratio $L_d(t,t') := rac{\mathbb{P}_{1,d}(t,t')}{\mathbb{P}_{0,d}(t,t')}$ verifies

$$L_d(t,t') = \sum_{k=0}^{c \wedge c'} \psi(k,c,c') \sum_{\substack{\sigma \in \mathcal{S}(k,c) \\ \sigma' \in \mathcal{S}(k,c')}} \prod_{i=1}^k L_{d-1}(t_{\sigma(i)},t'_{\sigma'(i)}),$$

where **c** and **c'** are the number of children of the roots, $\psi(\mathbf{k}, \mathbf{c}, \mathbf{c'}) = \mathbf{e}^{\lambda \mathbf{s}} \times \frac{\mathbf{s}^{k_{\mathbf{s}}\mathbf{c}+\mathbf{c'}-2k}}{\lambda^{k_{\mathbf{k}}!}}$, and $\mathcal{S}(\mathbf{k}, \ell)$ denotes the set of injective mappings from $[\mathbf{k}]$ to $[\ell]$. **One-sided tests :** tests $\mathcal{T}_d : \mathcal{X}_d \times \mathcal{X}_d \to \{0, 1\}$ such that $\mathbb{P}_{o,d}(\mathcal{T}_d = 0) = 1 - o(1)$ and $\liminf_d \mathbb{P}_{1,d}(\mathcal{T}_d = 1) > 0$ (i.e. vanishing type I error and non vanishing power).

Theorem

Let

$$\mathrm{KL}_d := \mathrm{KL}(\mathbb{P}_{1,d} \| \mathbb{P}_{0,d}) = \mathbb{E}_{1,d} \left[\log(L_d) \right].$$

Then the following propositions are equivalent :

- (i) There exists a one-sided test for deciding $\mathbb{P}_{o,d}$ versus $\mathbb{P}_{1,d}$,
- (ii) $\lim_{d \to =\infty} \mathrm{KL}_d = +\infty$ and $\lambda s >$ 1,
- (iii) with probability $1 p_{ext}(\lambda s) > 0$, L_d diverges to $+\infty$ with rate $\Omega\left(\exp\left(\Omega(1) \times (\lambda s)^d\right)\right)$.

Recall : estimator $\hat{\sigma}: \mathcal{C} \rightarrow [n]$ is said to achieve

- Partial recovery if there exists some $\epsilon > 0$ such that $\mathbb{P}(\operatorname{ov}(\pi^*, \hat{\sigma}) > \epsilon) \xrightarrow[n \to \infty]{} 1,$
- One-sided partial recovery if it achieves partial recovery and $\mathbb{P}(\operatorname{err}(\pi^*, \hat{\sigma}) = o(1)) \xrightarrow[n \to \infty]{} 1.$

Theorem

For given (λ, \mathbf{s}) , if one-sided correlation detection is feasible, then one-sided partial alignment in the correlated Erdős-Rényi model $\mathcal{G}(\mathbf{n}, \lambda/\mathbf{n}, \mathbf{s})$ is achieved in polynomial time by our algorithm.



Ganassali et al. (2021b)



Wu et al. (2021)

Results in the regime with constant mean degree



Sufficient conditions for the existence of one-sided test based on the Kullback-Leibler divergence or the number of automorphisms of GW trees. Ganassali et al. (2021a)

Results in the regime with constant mean degree



Conjectured hard phase based on the impossibility of one-sided test because KL_d is bounded. Ganassali et al. (2021a)

A learning algorithm



• The same FGNN is used for both graphs.



- The same FGNN is used for both graphs.
- We added a LAP solver to get a permutation from $E_1 E_2^T$.

For a permutation $\sigma \in S_n$, for $G \in \mathbb{F}^{n \times n}(\mathbb{F} = \mathbb{R}^p$ feature space), we define : $(\sigma \star G)_{\sigma(i_1),\sigma(i_2)} = G_{i_1,i_2}.$

 G_1, G_2 are isomorphic iff $G_1 = \sigma \star G_2$.

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Equivariance :

A function $f : \mathbb{F}^{n^2} \to \mathbb{F}^n$ is said to be equivariant if $f(\sigma \star G) = \sigma \star f(G)$.

For the graph alignment problem, we used an equivariant GNN from $\{0,1\}^{n \times n}$ to \mathbb{F}^n .

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Expressiveness : Azizian and Lelarge (2020)

FGNN has the **best power of approximation** among all architectures working with tensors of order **2** (MGNN or LGNN).

(Maron et al., 2019) to propose the folklore graph layer (FGL) :

$$h_{i \to j}^{\ell+1} = f_{\mathsf{o}}\left(h_{i \to j}^{\ell}, \sum_{k \in V} f_{\mathsf{1}}\left(h_{i \to k}^{\ell}\right) f_{\mathsf{2}}\left(h_{k \to j}^{\ell}\right)\right),$$

where f_0, f_1 and f_2 are learnable functions.

For FGNNs, messages are associated with pairs of vertices as opposed to MGNN where messages are associated with vertices.

FGNN : a FGNN is the composition of FGLs and a final invariant/equivariant reduction layer from \mathbb{F}^{n^2} to \mathbb{F}/\mathbb{F}^n .

Results on synthetic data



- Graphs : *n* = 50, density = 0.2
- Training set : 20000 samples
- Validation and Test sets : 1000 samples

Generalization for regular graphs



Each line corresponds to a model trained at a given noise level and shows its accuracy across all noise levels.

Comparison FGNN vs BPAlign



Overlap as a function of the correlation **s** for correlated E-R with average degree **3** (number of nodes : **200**).



Overlap as a function of $\sigma = \sqrt{\frac{1-s}{1-\lambda/n}}$ for correlated E-R with average degree 50 (number of nodes : 100). Fan et al. (2019)

From theory to practice



From theory to practice





Conclusion



The Bitter Lesson by Rich Sutton

The biggest lesson that can be read from 70 years of AI research is that general methods that leverage computation are ultimately the most effective, and by a large margin. Thank You!

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