# Optimization Based Approach for Quantum Signal Processing and Its Energy Landscape 

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## Outline

Introduction

## Optimization based algorithm for finding phase factors

## Energy landscape of the optimization

## Matrix product state based optimization method

## Open question

## "Grand unification" of quantum algorithms

A Grand Unification of Quantum Algorithms

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Quantum algorithms offer significant speedups over their classical counterparts for a variety of problems. The strongest arguments for this advantage are borne by algorithms for quantum search, quantum phase estimation, and Hamiltonian simulation, which appear as subroutines for large families of composite quantum algorithms. A number of these quantum algorithms were recently tied together by a novel technique known as the quantum singular value transformation (QSVT), which enables one to perform a polynomial transformation of the singular values of a linear operator embedded in a unitary matrix. In the seminal GSLW'19 paper on QSVT [Gilyén, Su, Low, and Wiebe, ACM STOC 2019], many algorithms are encompassed, including amplitude amplification, methods for the quantum linear systems problem, and quantum simulation. Here, we provide a pedagogical tutorial through these developments, first illustrating how quantum signal processing may be generalized to the quantum eigenvalue transform, from which QSVT naturally emerges. Paralleling GSLW'19, we then employ QSVT to construct intuitive quantum algorithms for search, phase estimation, and Hamiltonian simulation, and also showcase algorithms for the eigenvalue threshold problem and matrix inversion. This overview illustrates how QSVT is a single framework comprising the three major quantum algorithms, suggesting a grand unification of quantum algorithms.

## Quantum signal processing

$$
U_{\Phi}(x)=e^{\mathrm{i} \phi_{0} Z} \prod_{j=1}^{d}\left[W(x) e^{\mathrm{i} \phi_{j}} Z\right]=\left(\begin{array}{cc}
P(x) & \mathrm{i} Q(x) \sqrt{1-x^{2}} \\
\mathrm{i} Q^{*}(x) \sqrt{1-x^{2}} & P^{*}(x)
\end{array}\right), \quad W(x)=\left(\begin{array}{cc}
x & \mathrm{i} \sqrt{1-x^{2}} \\
\mathrm{i} \sqrt{1-x^{2}} & x
\end{array}\right) .
$$



## Goal of QSP (real case)

- Given $f(x) \in \mathbb{R}[x]$. Polynomial of degree $d$. Even or odd. $|f(x)|<1$ on $[-1,1]$.
- Find phase factors $\Phi:=\left(\phi_{0}, \cdots, \phi_{d}\right) \in \mathbb{R}^{d+1}$ so that

$$
\begin{aligned}
& \operatorname{Re}[U(x, \Phi)]_{1,1} \equiv \operatorname{Re}[\langle 0| U(x, \Phi)|0\rangle]=f(x), \quad x \in[-1,1] \\
& U(x, \Phi):=e^{\mathrm{i} \phi_{0} Z} W(x) e^{\mathrm{i} \phi_{1} Z} W(x) \cdots e^{\mathrm{i} \phi_{d-1} Z} W(x) e^{\mathrm{i} \phi_{d} Z}
\end{aligned}
$$

- $W(x)=e^{\mathrm{i} \arccos (x) x}=\left(\begin{array}{cc}x & \mathrm{i} \sqrt{1-x^{2}} \\ \mathrm{i} \sqrt{1-x^{2}} & x\end{array}\right)$.
- Solution guaranteed to exist


## Once upon a time, phase factors were hard to compute..

## Toward the first quantum simulation with quantum speedup

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Section H.3:
...However, this computation is difficult in practice, so we can only carry it out for very small instances. Specifically, we found the time required to calculate the angles to be prohibitive for values of $M$ greater than about 32...It is a natural open problem to give a more practical method for computing the angles.

## Algorithms for finding phase factors

- (Gilyen et al 1806.01838; Haah 1806.10236): compute the roots of a high-degree polynomial to high precision. Limit to $\sim$ hundreds of phase factors with double precision arithmetic.
- (Dong, Meng, Whaley, L., 2002.11649): Optimization based algorithm. No rigorous proof. Standard double precision arithmetic. $>10000$ phase factors.
- (Chao et al, 2003.02831): "capitalization". No rigorous proof. Standard double precision arithmetic. $>3000$ phase factors.
- Should be able to compute much longer phase sequences. The problem is practically solved within 2 years!
- (Wang, Dong, L., in prep2): Matrix-product state based structure. Local convergence from fixed initial guess.


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## Optimization based formulation

- Parity: only $\tilde{d}:=\left\lceil\frac{d+1}{2}\right\rceil$ degrees of freedom to determine $f(x)$.
- Sampling on Chebyshev nodes $x_{k}=\cos \left(\frac{2 k-1}{4 d} \pi\right), k=1, \ldots, \tilde{d}$.

- Minimization problem

$$
\Phi^{*}=\underset{\Phi \in[-\pi, \pi)^{d+1}}{\operatorname{argmin}} F(\Phi), F(\Phi):=\frac{1}{\widetilde{d}} \sum_{k=1}^{\tilde{d}}\left|\operatorname{Re}\left[U\left(x_{k}, \Phi\right)\right]_{1,1}-f\left(x_{k}\right)\right|^{2},
$$

- Global minimum $F\left(\Phi^{*}\right)=0$.
- Dimension mismatch: $d>\widetilde{d}$, so solution cannot be unique.


## Symmetric QSP

Recall

$$
U(x, \Phi)=\left(\begin{array}{cc}
P(x) & \mathrm{i} Q(x) \sqrt{1-x^{2}} \\
\mathrm{i} Q^{*}(x) \sqrt{1-x^{2}} & P^{*}(x)
\end{array}\right)
$$

- General QSP: $Q(x) \in \mathbb{C}[x]$.
- Symmetric QSP: $Q(x) \in \mathbb{R}[x] \quad \Rightarrow$ $\Phi=\left(\phi_{0}, \phi_{1}, \ldots, \phi_{1}, \phi_{0}\right)$. Symmetric phase factors
- Degree of freedom: $\widetilde{d}=\left\lceil\frac{d+1}{2}\right\rceil \Rightarrow$ matches that in $f(x)$ !
- Modified optimization problem

$$
\Phi^{*}=\underset{\substack{\Phi \in[-\pi, \pi)^{d+1}, \\ \text { symmetric. }}}{\operatorname{argmin}} F(\Phi), F(\Phi):=\frac{1}{\widetilde{d}} \sum_{i=1}^{\tilde{d}}\left|\operatorname{Re}\left[U\left(x_{i}, \Phi\right)\right]_{1,1}-f\left(x_{i}\right)\right|^{2},
$$

## Example: solve linear systems



## Applications

Hamiltonian simulation:



- Similar performance for other applications such as eigenstate filtering and solving linear systems


## Streamlining the process of finding phase factors

Given a smooth function $f(x)$ (not necessarily a polynomial)

- Option 1: Numerically obtain near-best polynomial approximation (e.g. Remez method) + numerical optimization.
- Option 2: Direct optimization.

Option 1 is observed to be numerically more stable (objective function $=0$ at global minima) when $f(x)$ is real.

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## Optimization landscape

2 independent symmetric phase factors $\phi_{0}, \phi_{1}$. Only global minima (so far).


Even target function

$$
f(x)=x^{2}-\frac{1}{2}
$$



Odd target function

$$
f(x)=\frac{1}{\sqrt{3}} x^{3}-\frac{2}{\sqrt{3}} x
$$

## Local minima exists (and there are many)

There are many local minima at large $d$.


$$
F\left(\Phi^{l o c}+x u_{1}+y u_{2}\right)
$$

Randomly generated odd target function $(d=5) . F\left(\Phi^{\text {loc }}\right)=0.0084$
Two smallest eigenvalue of the Hessian: $0.015,3.7897$ with eigenvectors $u_{1}, u_{2}$.

## Uniqueness of symmetric phase factor

Theorem (Wang, Dong, L., in prep1)
For any $P \in \mathbb{C}[x]$ and $Q \in \mathbb{R}[x]$ satisfying

1. $\operatorname{deg}(P)=d$ and $\operatorname{deg}(Q)=d-1$.
2. $P$ has parity $(d \bmod 2)$ and $Q$ has parity $(d-1 \bmod 2)$.
3. (Normalization condition)

$$
\forall x \in[-1,1]:|P(x)|^{2}+\left(1-x^{2}\right)|Q(x)|^{2}=1
$$

4. If $d$ is odd, then the leading coefficient of $Q$ is positive.
there exists a unique set of symmetric phase factors $\Phi:=\left(\phi_{0}, \phi_{1}, \cdots, \phi_{1}, \phi_{0}\right) \in D_{d}$ such that

$$
U(x, \Phi)=\left(\begin{array}{cc}
P(x) & i Q(x) \sqrt{1-x^{2}} \\
i Q(x) \sqrt{1-x^{2}} & P^{*}(x)
\end{array}\right)
$$

## Global minimizer and $(P, Q)$ pair

## Corollary

There is a bijection between global minimizers and all admissible $(P(x), Q(x))$ pairs with $\operatorname{Re}[P](x)=f(x)$.

- $P(x)=f(x)+i P_{\operatorname{lm}}(x)$
- Need to find complementary polynomials $P_{\operatorname{lm}}(x), Q(x) \in \mathbb{R}[x]$.
- Normalization condition

$$
1-f(x)^{2}=P_{\operatorname{lm}}(x)^{2}+\left(1-x^{2}\right) Q(x)^{2}
$$

- Seems like an infinite number of choices ([Gilyen et al 2019; Haah 2019] constructs a class of solutions)


## Key: Laurent polynomials

- For any $x \in[-1,1], x=\frac{z+z^{-1}}{2}$ with $z=e^{i \theta}$.
- $f(x) \rightarrow f\left(\frac{z+z^{-1}}{2}\right)$ : Laurent polynomial $\mathbb{C}\left[z, z^{-1}\right]$.

- Factorization:

$$
\begin{aligned}
& 1-f\left(\frac{z+z^{-1}}{2}\right)^{2}=\left(p_{\operatorname{lm}}(z)+\frac{z-z^{-1}}{2} q(z)\right)\left(p_{\operatorname{lm}}(z)-\frac{z-z^{-1}}{2} q(z)\right), \\
& p_{\operatorname{lm}(z)}:=P_{\operatorname{lm}}\left(\frac{z+z^{-1}}{2}\right), \quad q(z):=Q\left(\frac{z+z^{-1}}{2}\right), \\
& 1-f\left(\frac{z+z^{-1}}{2}\right)^{2}=\beta z^{-2 d} \prod_{r \in \mathcal{S}}(z-r), \text { for some } \beta \in \mathbb{R} .
\end{aligned}
$$

- Pin down the roots of RHS $\Rightarrow$ finite \# of global minimizers.
- Generalize results in [Gilyen et al 2019; Haah 2019] to find all global minimizers.


## One special initial guess

$$
\Phi_{0}=(\pi / 4,0, \ldots, 0, \pi / 4)
$$

- Used in qsppack for all examples.
- Robust for virtually all real target functions.
- Corresponds to $P(x)=\mathrm{i} T_{d}(x), Q(x)=U_{d-1}(x)$.
- One special solution for $f(x)=0$, i.e. $c=0$.


## Condition number and the magnitude

$$
\|f\|_{\infty}=\max _{x \in[-1,1]}|f(x)|=1-\eta .
$$



Condition number of the Hessian at $\Phi^{*}$.

- III-conditioned optimization problem as $\eta \rightarrow 0$.
- Given $\|f\|_{\infty}<1$, consider $c f(x)$ with $|c|<1$.


## Not all global minima are equivalent



$$
\begin{aligned}
f(x) & =10^{-k} \\
\text { - class } 1 & \rightarrow\left(\frac{1}{4} T_{6}+\frac{5}{4} T_{4}+\frac{1}{8} T_{2}-\frac{1}{8} T_{0}\right) . \\
\text { - class } 2 & \rightarrow\left(\frac{\pi}{4}, 0, \frac{\pi}{4},-\frac{\pi}{2}, \frac{\pi}{4}, 0, \frac{\pi}{4}\right) \\
\text { - class } 3 & \rightarrow\left(\frac{\pi}{4}, 0,-\frac{\pi}{4}, \frac{\pi}{2},-\frac{\pi}{4}, 0, \frac{\pi}{4}\right) \\
\text { - class } 4 & \rightarrow\left(\frac{\pi}{4}, \frac{\pi}{4}, 0,-\frac{\pi}{2}, 0, \frac{\pi}{4}, \frac{\pi}{4}\right)
\end{aligned}
$$

$$
\left\|\Phi^{*}(k)-\Phi_{0}^{\text {class }}\right\|_{2}
$$

- The branch converging to $\Phi_{0}=(\pi / 4,0, \ldots, 0, \pi / 4)$ is called maximal solution (also generated by GSLW/Haah method)
- $\Phi_{0}$ has the largest "convergence basin".


## Actual faster convergence near $\Phi_{0}$

Initial 1: $\Phi_{0}$


## Distance of maximal solution to $\Phi_{0}$

Recall $\Phi_{0}=(\pi / 4,0, \ldots, 0, \pi / 4)$.
Theorem (Wang, Dong, L., in prep1)
Let $\Phi^{*}$ be the symmetric phase factors corresponding to the maximal solution for the target function $f(x)$ with $\|f\|_{\infty}<\frac{1}{\sqrt{2}}$. Then

$$
\left\|\Phi^{*}-\Phi_{0}\right\|_{2} \leq \sqrt{12}\|f\|_{\infty}
$$

- Bound independent of $d$ !
- Capitalization (perturbation with high order polynomials) is not effective for symmetric phase factors.


## Well-conditioned Hessian at maximal solution

## Corollary

If $\|f\|_{\infty} \leq \frac{1}{48 d}$, then

$$
\left\|\Phi^{*}-\Phi_{0}\right\|_{2} \leq \frac{\sqrt{3}}{24 \tilde{d}}
$$

Furthermore,

$$
\lambda_{\min }\left(\operatorname{Hess}\left(\Phi^{*}\right)\right) \geq 1 .
$$

- $\operatorname{Hess}\left(\Phi^{*}\right)$ is positive definite.
- Optimization algorithm expects to converge locally.


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## Matrix product state structure of QSP

- MPS structure for $\langle 0| U(x, \Phi)|0\rangle$.

- $\mathcal{G}_{0}\left(\phi_{0}\right)=\left(e^{\mathrm{i} \phi_{0}}, 0\right), \mathcal{G}_{d}\left(\phi_{d}\right)=\left(e^{\mathrm{i} \phi_{d}}, 0\right)^{\top}$
- $\mathcal{W}(x)=e^{\mathrm{i} \arccos (x) X}, \mathcal{G}\left(\phi_{j}\right)=e^{\mathrm{i} \phi_{j} Z}$


## Gradient calculation

- Computing the gradient $\langle 0| \partial_{\phi_{i}} U(x, \Phi)|0\rangle$ (note the symmetric structure)

- Sweeping based algorithm: $\mathcal{O}\left(d^{2}\right)$ per sweep.
- Sweeping directions: Edge to center; Edge to center to edge; Center to edge; Center to edge to center; etc


## Fast convergence (very few sweeps)



Even target function $f(x)=\cos (500 x), \tilde{d}=367$


Odd target function
$f(x)=\frac{1}{\kappa x}$ with $\kappa=50, \widetilde{d}=760$.

## Convergence from $\Phi_{0}$

Recall $\Phi_{0}=(\pi / 4,0, \ldots, 0, \pi / 4)$.
Theorem (Wang, Dong, L., in prep2)
There exists a constant $C$ (independent of $d$ and target function) s.t. for any $f(x)$ with $\|f\|_{\infty} \leq \frac{1}{C \tilde{d}}$,

$$
\begin{equation*}
F\left(\Phi^{k}\right) \leq\left[1-\frac{1}{12(1+\tilde{d})}\right]^{k} F\left(\phi^{0}\right) \tag{1}
\end{equation*}
$$

where $k$ is the number of sweeping.

Number of sweeps seems to be independent of $d$. Cost close to $\mathcal{O}\left(d^{2}\right)$.

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## Open question: decay behavior of the phase sequence




Hamiltonian simulation

Eigenstate filtering

Solving linear systems

## Acknowledgment

## Thank you for your attention!

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