# (Sub)Exponential advantage of adiabatic quantum computation with no sign problem

Matthew Hastings Microsoft András Gilyén Caltech Umesh Vazirani UC Berkeley



arXiv:2011.09495

arXiv:2005.03791

#### Adiabatic quantum computation – background

A model of quantum computation utilizing a slowly changing Hamiltonian H(s): The adiabatic evolution stays in the ground state  $\psi(s)$  and maps  $\psi(0)$  to  $\psi(1)$ .



• The ground state is accurately mapped if the evolution time is  $t = \Theta(1/\text{poly}(\Delta))$ 

#### Adiabatic quantum computation

▶ Is an equivalent universal model of quantum computation [Aharonov et al. 2004]

A popular heuristics for combinatorial optimization

$$H(s) = (s-1)\sum_{i=1}^n X_i + s \cdot H_z,$$

where  $H_z$  is the diagonal Hamiltonian describing the classical objective function

• Unfortunately, for hard problems the gap  $\Delta$  tends to become small

An interesting special case is when the Hamiltonians have "no sign problem",
i.e., all off-diagonal matrix elements of *H*(*s*) are non-positive for every *s* ∈ [0, 1]
(note that this is a basis-dependent property)

#### No sign problem (stoquastic) – classically tractable?

- Due to the Perron-Frobenius theorem all amplitudes in the ground state have the same sign
- If the Hamiltonians are also frustration-free, then the adiabatic evolution can be classically efficiently simulated [Bravyi & Terhal, 2008]
- Monte Carlo methods tend to work remarkably well in practice
- However, there are topological obstruction to path integral Monte Carlo [Hastings & Freedman, 2013]
- Diffusion Monte Carlo is sensitive to l<sub>1</sub> vs. l<sub>2</sub> differences in the ground state [Jarret, Jordan, & Lackey, 2016]

#### Exponential quantum advantage with no sign problem

#### Main result (informal)

There is a family of sparse stoquastic Hamiltonians on *n* qubits with a straight adiabatic path featuring a spectral gap  $\Delta = \Omega(1/\text{poly}(n))$ , whose evolution requires  $2^{\sqrt[5]{n}}$  queries to the Hamiltonian entries to simulate classically.

- ► This is an oracle separation
- If we want a provable advantage we need to rely on oracles

#### The corresponding graph problem (informal)

Given (via black-box access) a sparse graph on  $2^n$  vertices and a specific "ENTRANCE" vertex, we can find the "EXIT" vertex in poly(n) time via adiabatic evolution of a corresponding Hamiltonian which has 1/poly(n) spectral gap and no sign problem. At the same time any classical randomized algorithm must make at least  $2^{\sqrt[n]{n}}$  queries to the graph (i.e., to the black-box) for finding the "EXIT".

### The underlying adiabatic path ( $\ell = poly(n)$ )



We use a simple adiabatic path  $H_{\ell}(s)$  interpolating between  $H^{(i)}$  and  $H_{\ell}$ :

$$H_\ell(s) = (1-s)H^{(i)} + sH_\ell$$



## Step 1: obfuscation









#### Step 2a: decoration (tricking diffusion Monte Carlo)

- Attach disjoint "camouflage" or "decoration" trees to every vertex
- ► Each attached tree has a degree bound of *O*(*m*)
- The spectral norm of each tree, and thus the entire forest, is  $O(\sqrt{m})$
- The spectral gap before decoration is  $\Delta = \Theta(m/\ell^2)$
- ▶ If  $\sqrt{m} \gg \ell^2$ , then the spectral gap cannot close under  $O(\sqrt{m})$  perturbation
- Consequently, the ground state suffers only minor perturbation in  $\ell_2$ -norm
- However, if the trees are poly(m) deep, then the  $\ell_1$  weight moves onto the trees!

### Step 2b: fractal decoration (tricking every classical alg.)

- ▶ If all attached trees have the same depth *d*, we can effectively filter them out
- After traversing an edge perform a non-backtracking trial walk: if a leaf is found after d steps we know that a camouflage tree was entered
- ► To prohibit such algorithms we attach trees that have a fractal shape:
- The trees are designed such that the expected "hitting time" of leafs barely changes while moving deeper into a tree – making the "camouflage" trees very hard to recognize
- Due to the random labeling of vertices no classical algorithm can navigate the decorated graph, and any classical algorithm will "get lost" spending an exponential amount of time in the "camouflage forest" before finding the EXIT.

# Compare to the glued-trees problem [Childs et al., 2002]

 $C_1 \quad C_2 \quad C_3 \quad C_4 \quad C_5 \qquad \qquad \cdots \qquad \qquad C_{\ell-4} \quad C_{\ell-3} \quad C_{\ell-2} \quad C_{\ell-1} \quad C_{\ell}$ 

#### **Relationship to the glued-trees problem**

- Neither Hamiltonians have a sign problem.
- ► The quantum advantage stems from staying in the "symmetric subspace".
- ► A quantum walk can efficiently find the EXIT given the ENTRANCE.
- The glued-trees are 3-regular and have an exponentially small spectral gap.
- Our graph is non-regular but has a large spectral gap.
- Classical hardness stems from regularity vs. fractal shaped trees.

### Outlook and open questions

- The original construction of Hastings utilized an adiabatic method for sign-problem-free ground state energy estimation for sign-problem-free Hamiltonians. Could that construction be used for devising further results?
- Find a sign-problem-free Hamiltonian of practical interest providing a large speed-up!
- ► Are sign-problem-free Hamiltonians at least marginally easier in general? Is there a general simulation algorithm that works in time for example √2<sup>n</sup>?
- What is the classical complexity of simulating adiabatic evolution for frustrated local Hamiltonians with no sign problem? (See, e.g., [Bringewatt & Jarret, 2020].)