Online Learning via Offline Greedy Algorithms: Applications in Market Design and Optimization

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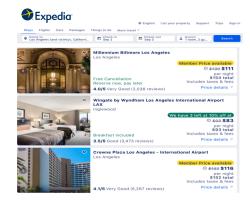
Joint work with R. Niazadeh, J. Wang, F. Susan, and A. Badanidiyuru

Simons Institute, Mathematics of Online Decision Making Workshop Oct 29<sup>th</sup>, 2020

# **Decision-making in Marketplaces**

Marketplaces have to make certain decisions repeatedly over time







**Assortment planning**: What items to offer to customers to maximize market share?

**Product ranking:** How to display products on online platforms?

**Reserve price optimization:** How to set reserve prices in auctions run to sell ads?

# **Challenges:** Online decision making under uncertainty in a time-varying environment

Without uncertainty, the offline problem is NP-hard to solve

## **Research Questions**

How to design learning algorithms for such combinatorial and time-varying environments?

Can we <u>transform</u> offline algorithms to online algorithms with sublinear (approximate) regret?

**Yes**, for a large class of offline problems that admit a robust greedy algorithm with a constant approximation factor

#### Use this problem to illustrate our technique



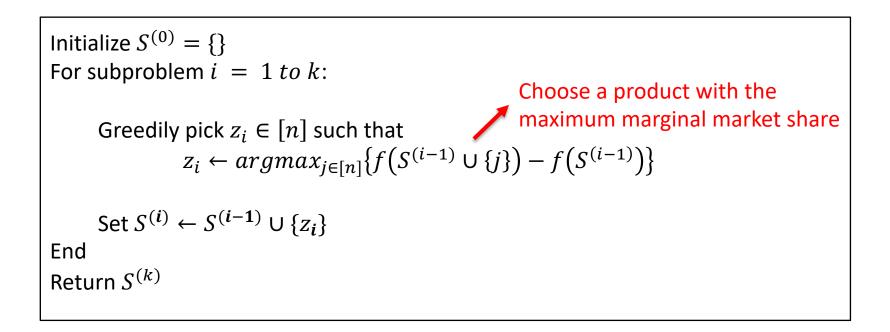
# **Preliminary: Offline Problem**

- There are n products
- Our goal is to choose set S with  $|S| \le k$  that maximizes market share (probability of purchase)
  - $f(S) = \sum_{i \in S} \text{Prob}(i \text{ is purchased } | S)$  is the market share (demand) under set S
  - $f(\cdot)$  is a monotone <u>submodular</u> function under all random utility choice models
- We want to find

$$S^* = \operatorname{argmax}_{|S| \le k} f(S)$$
 Offline Problem

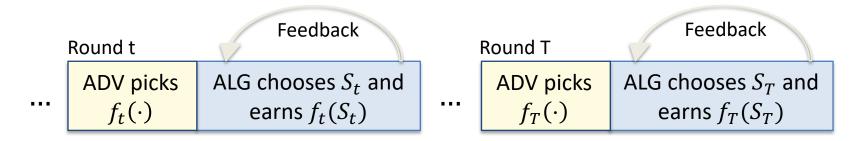
• The offline problem admits a greedy algorithm with  $\gamma = 1 - 1/e$  approx. factor [Nemhauser et al., 1978]

# **Greedy Algorithm for the Offline Problem**



Greedy algorithm builds the solution stage by stage

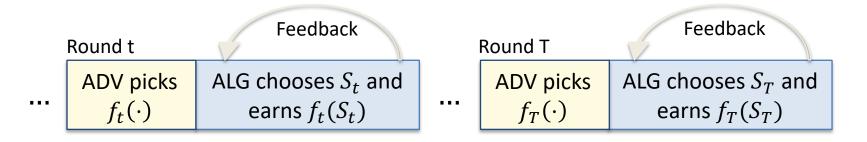
## **Preliminary: Online Problem**



- T periods
- In round t, nature (ADV) chooses a monotone submodular demand function  $f_t(\cdot)$
- $f_t(\cdot)$  is unobservable to the decision-maker (ALG) at the time of the decision
- ALG chooses a set  $S_t$  and obtains market share (reward) of  $f_t(S_t)$
- ALG gets feedback
  - Full information: ALG observes  $f_t(\cdot)$
  - Bandit: ALG only observes  $f_t(S_t)$

Today's talk

## **Preliminary: Online Problem**



Goal: minimize regret w.r.t.  $\gamma \cdot OPT$ 

$$OPT = \max_{S, |S| \le k} \sum_{t \in [T]} f_t(S)$$
  
Regret=  $\gamma \cdot OPT - \sum_{t \in [T]} f_t(S_t)$ 

### **Contributions and Main Results**

- Design an efficient framework to transform offline greedy-based algorithm to a lowregret online algorithm via Blackwell approachability
  - For full information and bandit feedback structures
- $O(\sqrt{T})\gamma$  regret for full information and  $O(T^{2/3})\gamma$  regret for bandit
- Maximizing monotone set submodular with cardinality constraints
  - **Full information**: our  $\gamma$ -regret bound  $O(k\sqrt{T \log n})$  [Best prior bound  $O(k\sqrt{T \log n})$  by Streeter and Golovin, 2008]
  - Bandit: our bound  $O(kn^{2/3}(\log n)^{1/3}T^{2/3})$  [Best prior bound  $O(k^2(n \log n)^{1/3}T^{2/3}(\log T)^2)$  by Streeter and Golovin, 2008]

## **Contributions and Main Results**

• Our framework has a wide-range of applications

		Online Full-Information Setting		Online Bandit Setting		
Applications	γ	Our γ-Regret Bound	The Best Prior Bound	Our $\gamma$ -Regret Bound	The Best Prior Bound	
Product Ranking	1/2	$O\left(n\sqrt{T\log n}\right)$	-	$O(n^{5/3}T^{2/3}(\log n)^{1/3})$	-	
Reserve Price Optimization	1/2	$O\left(n\sqrt{T\log T}\right)$	$O(n\sqrt{T\log T})^*$	$O(n^{3/5}T^{4/5}(\log nT)^{1/3})$	-	
Non-Monotone Set SM	1/2	$O(n\sqrt{T})$	$O(n\sqrt{T})^{\ddagger}$	$O(nT^{2/3})$	-	
Non-Monotone Strong-DR SM	1/2	$O(n\sqrt{T\log T})$	$\gamma = 1/4, \ O(T^{5/6})^{s}$	$O(nT^{4/5}(\log T)^{1/3})$	$\gamma = \frac{1}{4}, O(T^{11/12})^{\$}$	
Non-Monotone Weak-DR SM	1/2	$O\left(n\sqrt{T\log T}\right)$	-	$O\left(nT^{4/5}(\log T)^{1/3}\right)$	-	
		T dependency	Discrete:	<b>Discrete</b> : $T^{\frac{2}{3}}$ dependency; <b>Continuous</b> : $T^{\frac{4}{5}}$ dependency		

Bandit feedback structure captures more realistic scenarios; But, sparse results!

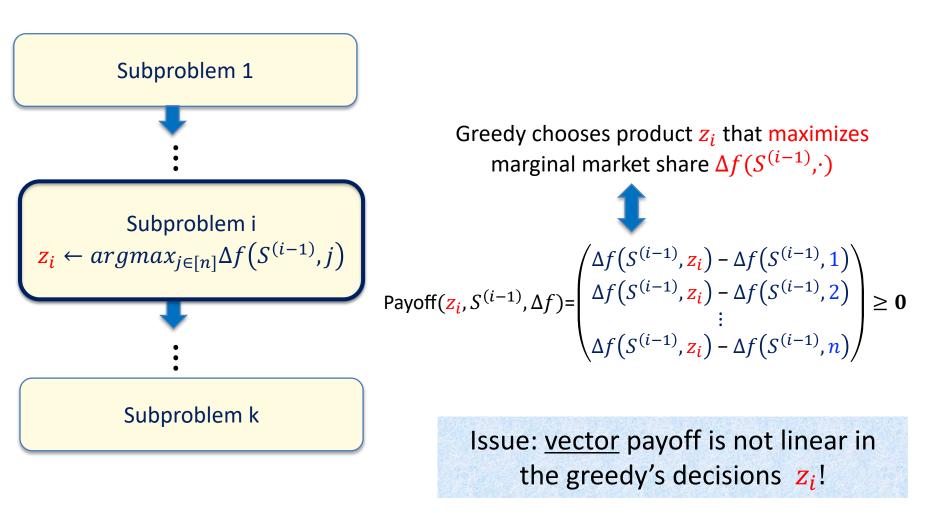
### **Related Work**

#### Offline-to-online transformation for NP-hard combinatorial problems

Offline-to-online transformation	<ul> <li>Hazan and Koren, 2016 – negative results for general comb. problems</li> <li>Kalai and Vempala, 2005, Dudik et al., 2017 – learner can solve offline problem efficiently</li> <li>Kakade et al., 2009 – NP-hard problem amenable to approximation, linear rewards</li> </ul>
Combinatorial learning	<ul> <li>Audibert et al., 2014 – exponentially weighted avg. forecaster for full-info setting, tight regret, linear rewards</li> <li>Bubeck et al., 2012, Hazan and Karnin, 2016 – efficient algorithm for the bandit setting, linear rewards</li> </ul>
Our contribution	<ul> <li>NP-hard problems with non-linear rewards</li> <li>Both bandit and full-information settings</li> <li>Transform offline greedy algorithms to online</li> </ul>

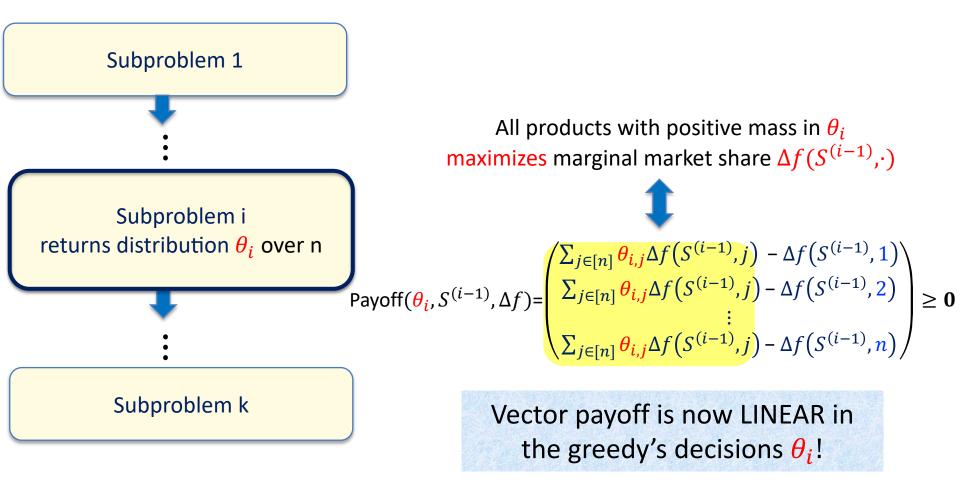
High level ideas and our algorithm

## **Revisiting the Greedy Algorithm**



 $\Delta f(S, j) = f(S \cup \{j\}) - f(S)$  marginal market share of adding product j to set S

## **Revisiting the Greedy Algorithm**



 $\sum_{j \in [n]} \theta_{i,j} \Delta f(S^{(i-1)}, j)$  is the expected value of marginal market share at the greedy solution  $\theta_i$ 

# Greedy Algorithm is Robust to Local Errors

Errorless system: For every subproblem i and coordinate j, if we have

 $[\operatorname{Payoff}(\theta_i, S^{(i-1)}, \Delta f)]_j \ge 0 \ j \in [n]$ 

we get  $\gamma = \left(1 - \frac{1}{e}\right)$  approx. factor:

 $f(S^{(k)}) \ge \gamma \cdot f(S^*)$ 

System with local errors: If  $\theta_i$  is replaced by its noisy version  $\tilde{\theta}_i$  such that  $[Payoff(\tilde{\theta}_i, S^{(i-1)}, \Delta f)]_j + \epsilon \ge 0 \ j \in [n]$ we get

$$f(S^{(k)}) \ge \gamma f(S^*) - \epsilon k$$

Local errors do not propagate!

## That Is Not All! Greedy is Extended Robust

Consider noisy run of the algorithm over  ${\cal T}$  rounds. Then, if for every subproblem i

$$\left[\sum_{t \in [T]} \mathsf{Payoff}\left(\widetilde{\theta_{i,t}}, S_t^{(i)}, \Delta f_t\right)\right]_j + \mathsf{Error}(\mathsf{T}) \ge 0 \qquad j \in [n]$$

we have

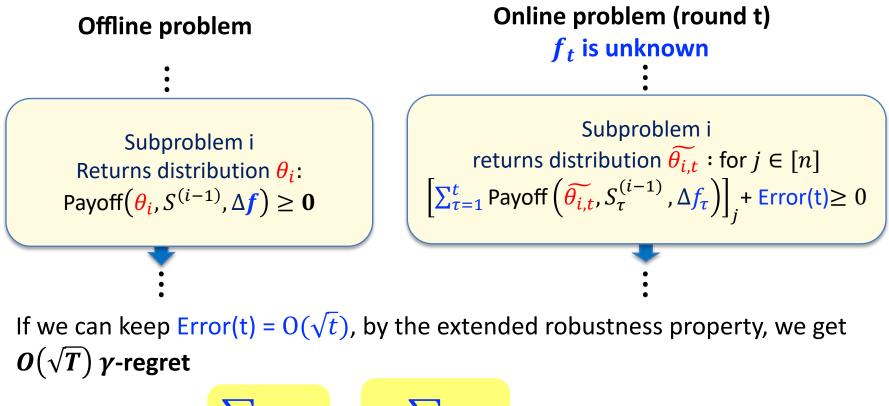
$$\sum_{t \in [T]} f_t(S_t) \ge \gamma \cdot \sum_{t \in [T]} f_t(S) - k \cdot \text{Error}(\mathsf{T}) \qquad \forall S \colon |S| \le k$$

If the aggregate error (over the T rounds) for every coordinate is small, the algorithm will still do well

- We say the greedy algorithm is extended robust
- Not every greedy algorithm has this property

# **Our High-level Idea**

Transforming offline greedy algorithm to an online algorithm



Extended robustness

 $\sum_{t \in [T]} f_t(S_t) \ge \gamma \cdot \sum_{t \in [T]} f_t(S) - k \cdot \operatorname{Error}(\mathsf{T}) \qquad \forall S \colon |S| \le k$ 

This is what ALG earns This is the benchmark

**Question**: How to design an algorithm for each subproblem with  $\text{Error}(t) = O(\sqrt{t})$ ?

## **Blackwell Approachability**

# **Blackwell Sequential Games**



Repeated two-player (P1 and P2) zero-sum game with vector-valued reward

Round t

P1 plays $x_t$	P1 obtains $r(x_t, y_t)$		
P2 plays $y_t$	P2 obtains $-r(x_t, y_t)$		

Round T

P1 plays $x_T$	P1 obtains $r(x_T, y_T)$	
P2 plays $y_T$	P2 obtains $-r(x_T, y_T)$	

 $r(\cdot,\cdot)$  is a vector-valued Reward vector r(x, y) is biaffine

Blackwell Game: P1 wants to approach a convex set S and P2 does not want

this to happen

A convex and closed target set S is g(T) —approachable if  $\exists$  a P1 strategy such that for every P2 strategy:

$$d_{\infty}\left(\frac{1}{T}\sum_{t=1}^{T}r(\mathbf{x}_{t},\mathbf{y}_{t}),S\right) \leq g(T) \quad \begin{array}{l} \text{We want } g(T) \text{ to go to} \\ \text{zero as } T \to \infty \end{array}$$

Average vector-valued reward

## Not Every Target Set Is Approachable

Set S is <u>approachable</u> if for every P2 action y, there exists a P1 action x, such that  $r(x, y) \in S$ 

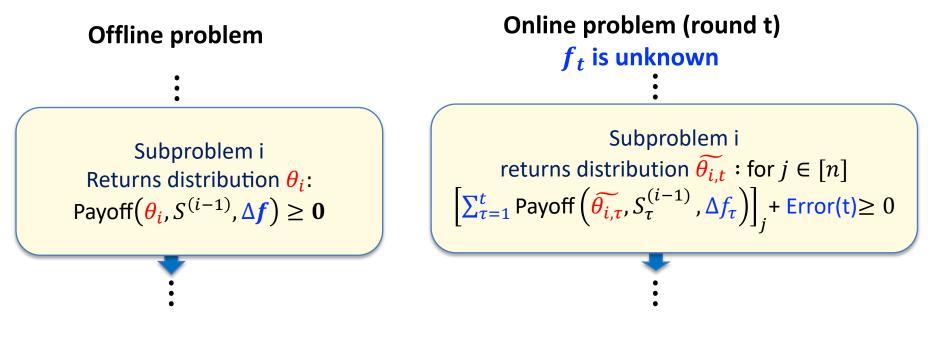
S is approachable  $\rightarrow S$  is  $g(T) = O(D(r)(\log d)^{1/2}T^{-1/2})$  –approachable

- D(r) is the diameter of the reward vector
- d is the dimension of the reward vector

For any approachable set, there is an algorithm *AlgB* with  $g(T) = O(D(r)(\log d)^{1/2}T^{-1/2})$ 

# **Revisiting our High-level Idea**

Transforming offline greedy algorithm to an online algorithm



We let AlgB handle each subproblem  $i \in [k]$ 

# **Blackwell Algorithms Handle Subproblems**

- P1 is algorithm that returns  $\tilde{\theta_{i,t}}$
- P2 is the nature (ADV) that chooses  $\Delta f(S^{(i-1)},.)$

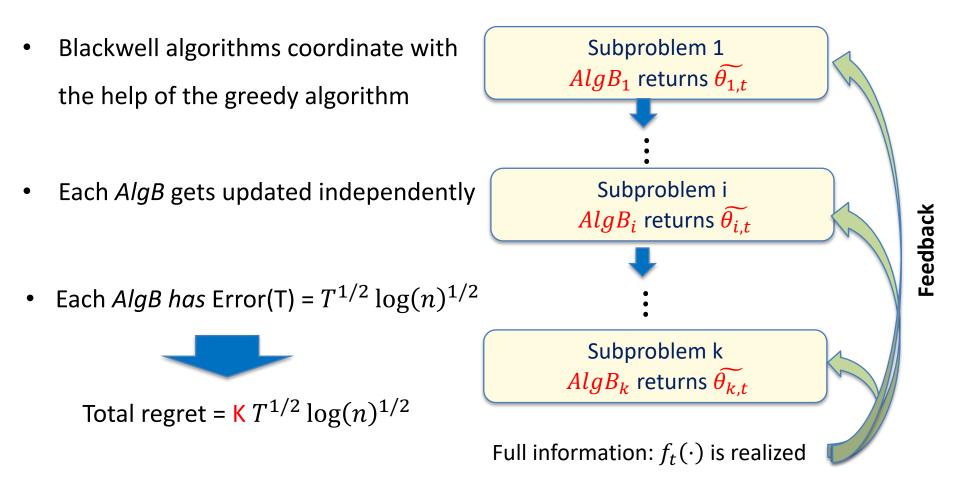
Subproblem i returns distribution  $\widetilde{\theta_{i,t}}$ : for  $j \in [n]$  $\left[\sum_{\tau=1}^{t} \operatorname{Payoff}\left(\widetilde{\theta_{i,\tau}}, S_{\tau}^{(i-1)}, \Delta f_{\tau}\right)\right]_{j} + \operatorname{Error}(t) \geq 0$ 

- Per period payoff vector is <u>biaffine</u> Payoff( $\theta_i$ ,  $S^{(i-1)}$ ,  $\Delta f$ ) =  $\begin{pmatrix} \sum_{j \in [n]} \theta_{i,j} \Delta f(S^{(i-1)}, j) - \Delta f(S^{(i-1)}, 1) \\ \sum_{j \in [n]} \theta_{i,j} \Delta f(S^{(i-1)}, j) - \Delta f(S^{(i-1)}, 2) \\ \vdots \\ \sum_{j \in [n]} \theta_{i,j} \Delta f(S^{(i-1)}, j) - \Delta f(S^{(i-1)}, n) \end{pmatrix} \ge \mathbf{0}$
- Target set S is the positive orthant Payoff  $\left(\widetilde{\theta_{i,t}}, S_t^{(i-1)}, \Delta f_t\right) \ge \mathbf{0}$  and is approachable
- We can approach set S with  $g(t) = O(D(r)(\log d)^{1/2}t^{-1/2}) = O(\log(n)^{1/2}t^{-1/2})$

Error(t) =  $t^{1/2} \log(n)^{1/2}$ 

# **Blackwell Algorithms Coordination and Regret**

**Online problem (round t)** 



# Full Information: Beyond Assortment Planning

**Theorem 1 (Full-information offline-to-online transformation)** Suppose that an offline algorithm

- is an extended robust approximation algorithm, and
- Blackwell reducible.

Then, in the full information setting, there exists an online algorithm that runs in polynomial time and satisfies:

$$\gamma - \text{regret} \le O\left(kD(p)(\log d)^{1/2}T^{1/2}\right)$$

where k is the number of subproblems, d is the dimension of the payoffs, and D(p) is the  $\ell_{\infty}$  diameter of the vector payoff.

#### Blackwell reducible:

- 1) Defining bi-affine vector payoff for each subproblem
- 2) Defining an approachable target set for each subproblem

### Maximizing Non-Monotone Submodular Functions

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Non-Monotone Weak-DR SM	1/2	$O(n\sqrt{T\log T})$	-	$O\left(nT^{4/5}(\log T)^{1/3}\right)$	-

\*Roughgarden and Wang, 2019; \*Roughgarden and Wang, 2018; <sup>§</sup>Thang and Srivastav, 2019

# Takeaway

- Transform offline greedy algorithms to online ones using Blackwell approachability
  - Need the greedy algorithm to be extended robust and bandit Blackwell reducible
- For full information setting, our algorithm has  $O(\sqrt{T}) \gamma$  -regret
- For Bandit setting, our algorithm has  $O(T^{2/3})\gamma$  -regret
- Our framework is flexible and can be applied to many applications
  - Product ranking optimization in online platforms
  - Reserve price optimization in auctions
  - Submodular maximization



#### Link to the paper: <a href="https://papers.ssrn.com/sol3/papers.cfm?abstract\_id=3613756">https://papers.ssrn.com/sol3/papers.cfm?abstract\_id=3613756</a>

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