

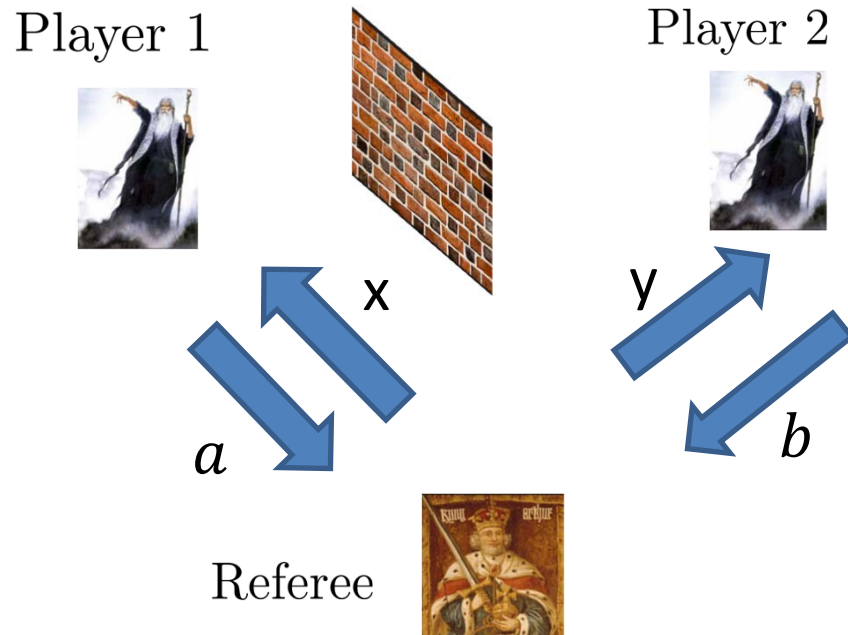
# Non-local binary games with noisy EPR states are decidable

Penghui Yao

Workshop “Quantum protocols: Testing & Quantum PCPs”

<https://arxiv.org/abs/1904.08832>

# Classical non-local games



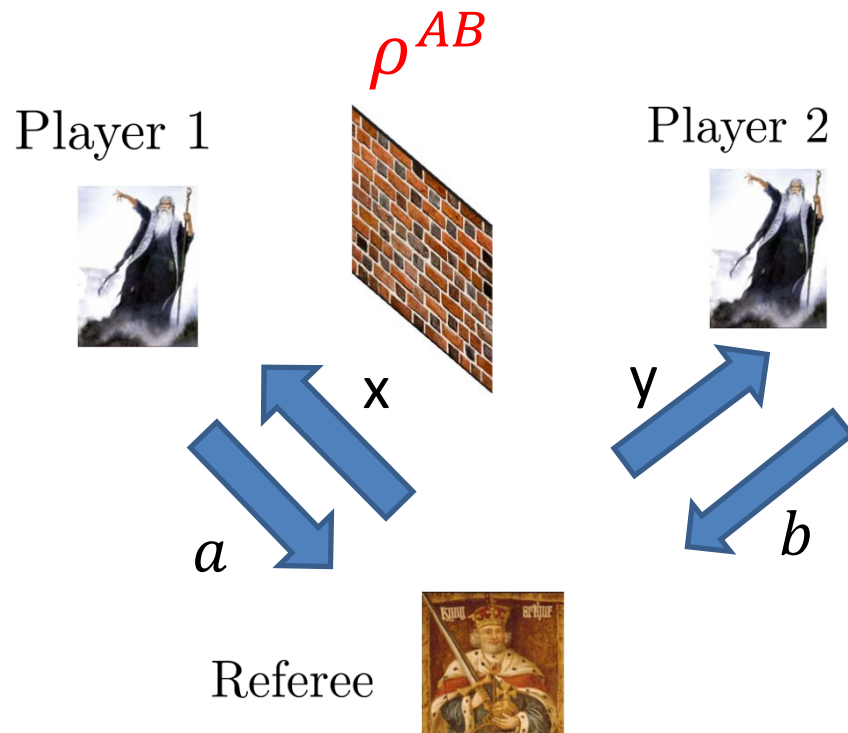
- $(x, y) \sim \mu$
- $V(x, y, a, b) \in \{0(\textit{lose}), 1(\textit{win})\}$
- $\omega(G) :=$ the highest probability to win the game

- It captures the complexity of many optimization problems.
- Computing  $\omega(G)$  is NP-hard

## PCP theorem.

It is NP-hard to approximate  $\omega(G)$  to a constant precision.

# Quantum non-local games

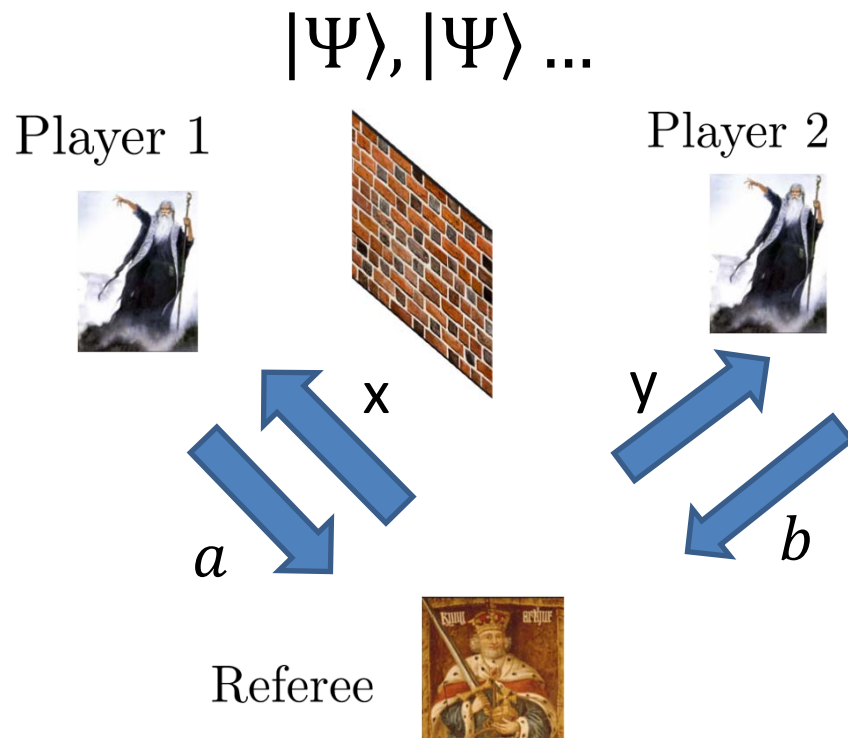


Q. What is the complexity of computing  $\omega^*(G)$ ?

- [JNWVY] RE-complete to approximate  $\omega^*(G)$  to a constant precision

$\omega^*(G)$  := the highest probability to win the game

# Quantum non-local games



Q. What is the complexity of computing  $\omega^*(G)$ ?

- [JNWVY] RE-complete to approximate  $\omega^*(G)$  to a constant precision **even if only sharing EPR states.**

$\omega^*(G)$  := the highest probability to win the game

Q. Are strategies for non-local games are robust against noise?

# Quantum non-local games



$$\Psi_\varepsilon := (1 - \varepsilon)|\Psi\rangle\langle\Psi| + \varepsilon \frac{I}{4}$$

- $\omega(G, \Psi_\varepsilon, n) :=$  highest prob. if  $n$  copies of  $\Psi_\varepsilon$  are provided.
- $\omega^*(G, \Psi_\varepsilon) = \lim_{n \rightarrow \infty} \omega(G, \Psi_\varepsilon, n)$

- Ji. et al. undecidable to a constant precision if  $\varepsilon = 0$
- The entanglement tends to infinity if  $\varepsilon$  is sufficiently small
- Are strategies robust against the noise from the shared states?

# Binary games with noisy EPR states

## Main result

For any **binary** game, if the players only share  $\varepsilon$  –noisy EPR states,

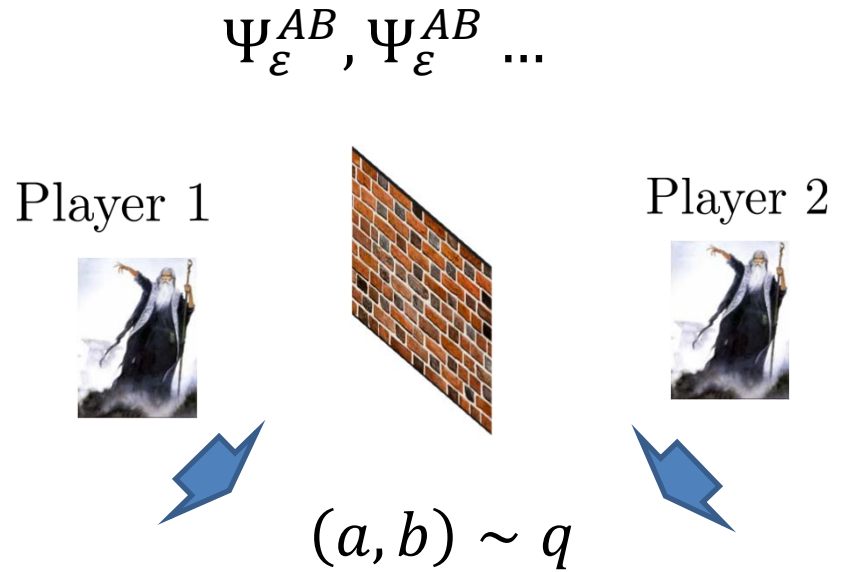
$$D = \exp \left( \text{poly} \left( |X|, |Y|, \exp \left( \frac{1}{\varepsilon}, \frac{1}{\delta} \right) \right) \right)$$

copies of the states are sufficient to achieve the optimal value to precision  $\delta$ .

- Previous algorithms for  $\omega^*(G)$  are via convex optimization, such as quantum XOR games, quantum unique games.
- We simulate high-entangled strategies by low-entangled strategies

# High level of the proofs

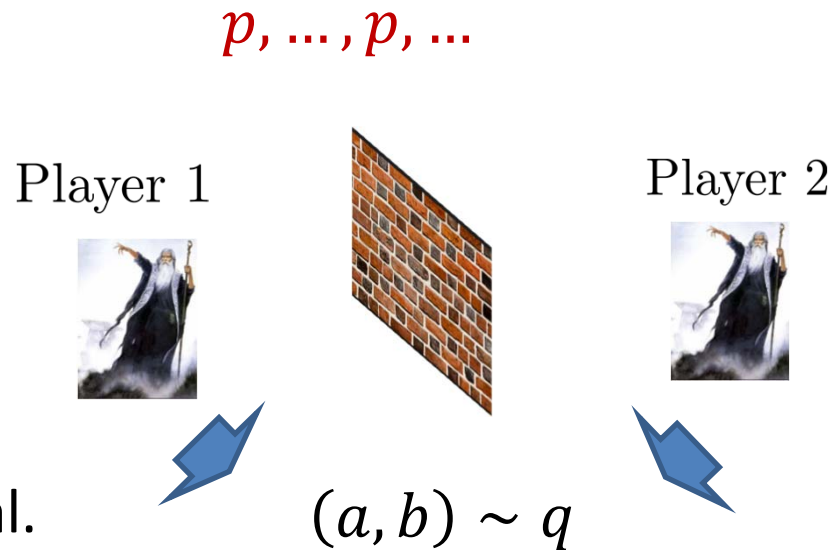
Q. What distributions  
can the players sample?



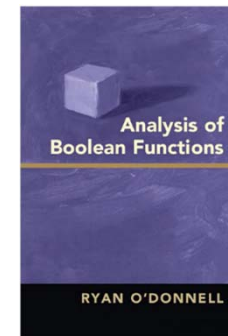
# High level of the proofs

Q. What distributions can the players sample?

- Non-interactive simulation of Joint distributions
- It roots back to 70's by Gács et.al.



- The decidability was resolved recently by Ghazi et al. in a series of work using Boolean analysis
  - Yes.  $\exists n$  and strategy to jointly sample  $q'$  s.t.  $\|q - q'\|_1 \leq \varepsilon$
  - No.  $\forall n$  and strategy jointly sample  $q'$ ,  $\|q - q'\|_1 > 2\varepsilon$

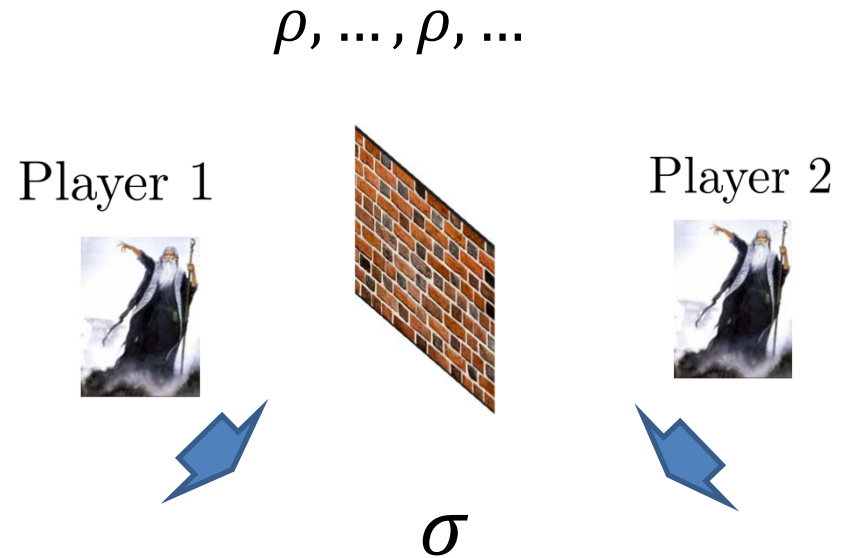




# High level of the proofs

Q. What quantum states can players create?

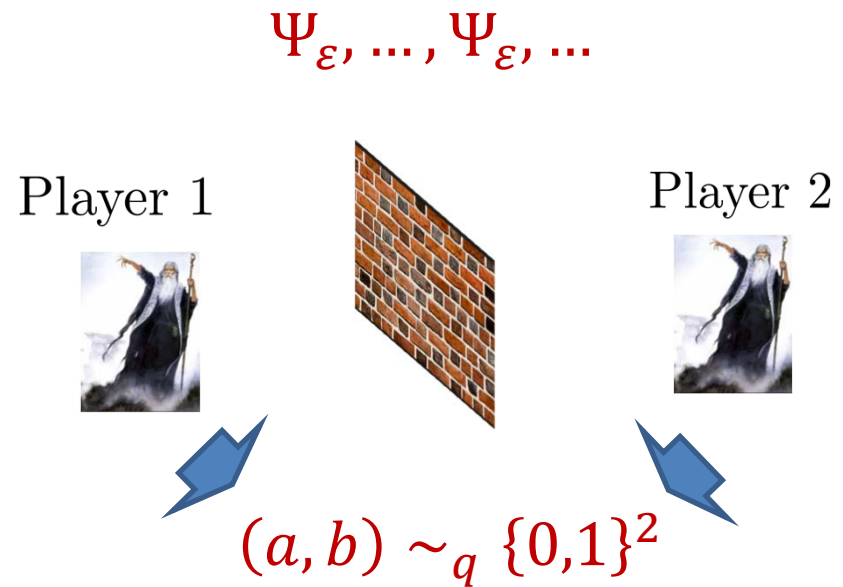
- Local state transformation
- It was first studied by Beigi



# High level of the proofs

Q. What quantum states can players create?

- Local state transformation
- It was first studied by Beigi
- We proved that it is decidable if sharing noisy EPR states and the target state is a binary distribution
- It is via generalizing Boolean analysis to Hermitian operators and random operators.



# High level of the proofs

Player 1:  $(P, I - P) \in H_2^{\otimes n}$   
Player 2:  $(Q, I - Q) \in H_2^{\otimes n}$



Player 1:  $(P', I - P') \in H_2^{\otimes D}$   
Player 2:  $(Q', I - Q') \in H_2^{\otimes D}$

## Requirements.

$\exists D \forall n$

1.  $0 \leq P', Q' \leq I$

2.  $\Pr[\text{Player 1 outputs 1}] = \frac{\text{Tr } P'}{2^D} \approx \frac{\text{Tr } P}{2^n}$

3.  $\Pr[\text{Player 2 outputs 1}] = \frac{\text{Tr } Q'}{2^D} \approx \frac{\text{Tr } Q}{2^n}$

4.  $\Pr[\text{both output 1}] = \text{Tr}(P \otimes Q) \Psi_\varepsilon^{\otimes n} \approx \text{Tr}(P' \otimes Q') \Psi_\varepsilon^{\otimes D}$

5.  $P'$  only depends on  $P$  and  $Q'$  only depends on  $Q$  (applicable for non-local games)

# Fourier expansion

## Pauli basis

$$\sigma_0 = I, \sigma_1 = X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma_2 = Y = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}, \sigma_3 = Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$P \in \mathbb{M}_2: P = \hat{P}(0) \sigma_0 + \hat{P}(1) \sigma_1 + \hat{P}(2) \sigma_2 + \hat{P}(3) \sigma_3$$

$$P \in \mathbb{H}_2: \hat{P}(i)'s \text{ are reals}$$

$$P \in \mathbb{M}_2^{\otimes n}: P = \sum_{s \in \{0,1,2,3\}^n} \hat{P}(s) \sigma_s.$$

$$\sigma_s := \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_n}$$

$$\text{Parseval identity} \quad \sum_s |\hat{P}(s)|^2 = |||P|||_2^2$$

$$\text{Normalized } p\text{-norm} \quad |||P|||_p := \left( \frac{1}{2^n} |||P|||_p^p \right)^{1/p}$$

# Constructions

1. Smooth the operators by applying noise operators (depolarizing channels)  $T_\rho$

$$P = \sum_{s \in \{0,1,2,3\}^n} \hat{P}(s) \sigma_s$$

# Constructions

1. Smooth the operators by applying noise operators (depolarizing channels)  $T_\rho$

Exponentially small

$$P_1 = T_\rho P = \sum_{s \in \{0,1,2,3\}^n} \hat{P}(s) \rho^{|s|} \sigma_s = P_1^{\leq d} + \cancel{P_1^{> d}}$$

2. Number of **high influential** coordinates are bounded

$$\mathit{Inf}_i(P) := \left\| \|P - P_{-i} \otimes I/2\|_2 \right\|_2^2 = \sum_{i: s_i \neq 0} |\hat{P}(s)|^2$$

$$\sum_i \mathit{Inf}_i(P) = \sum_{i, s: s_i \neq 0} |\hat{P}(s)|^2 \leq \deg(P) \|P\|_2^2 \leq \deg(P)$$

# Constructions

2. Number of **high influential** coordinates are bounded

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \overbrace{\sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3}}^H \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n}$$

3. Substitute all basis elements in low influential coordinates by independent Gaussian variables

$$\left( \mathbf{g}_0^{(h+1)} = 1, \mathbf{g}_1^{(h+1)}, \mathbf{g}_2^{(h+1)}, \mathbf{g}_3^{(h+1)}, \dots, \mathbf{g}_3^{(n)} \right)$$

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_{h+1}} \otimes \sigma_{s_{h+2}} \otimes \dots \otimes \sigma_{s_n}$$

$\uparrow$   
 $\mathbf{g}_{s_{h+1}}^{(h+1)}$

$\uparrow$   
 $\mathbf{g}_{s_{h+2}}^{(h+2)}$

$\uparrow$   
 $\mathbf{g}_{s_n}^{(n)}$

# Constructions

2. Number of **high influential** coordinates are bounded

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \overbrace{\sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3}}^H \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n}$$

3. Substitute all basis elements in low influential coordinates by independent Gaussian variables

$$\left( \mathbf{g}_0^{(h+1)} = 1, \mathbf{g}_1^{(h+1)}, \mathbf{g}_2^{(h+1)}, \mathbf{g}_3^{(h+1)}, \dots, \mathbf{g}_3^{(n)} \right)$$

$$P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \dots \mathbf{g}_{s_n}^{(n)} \right)$$



# Constructions

3. Substitute all basis elements in low influential coordinates by independent Gaussian variables

$$\begin{aligned} \mathbf{P}_2 &= \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \cdots \mathbf{g}_{s_n}^{(n)} \right) \\ &= \sum_{s \in \{0,1,2,3\}^n} f_{s_h}(\vec{\mathbf{g}}) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \cdots \otimes \sigma_{s_h} \end{aligned}$$

$f_{s_h}$  's are low-deg polynomials.

4. Dimension reduction for **low-deg polynomials** on Gaussian space to reduce the # of Gaussian variables.

$$\mathbf{P}_3 = \sum_{s \in \{0,1,2,3\}^{n_0}} f'_{s_h} \left( \mathbf{g}_{s_{h+1}} \cdots, \mathbf{g}_{s_{n_0}} \right) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \cdots \otimes \sigma_{s_h}$$

# Constructions

4. Dimension reduction for **low-deg polynomials** on Gaussian space to reduce the # of Gaussian variables.

$$\begin{aligned}
 P_3 &= \sum_{s \in \{0,1,2,3\}^{n_0}} f'_{s_h}(\mathbf{g}_{s_{h+1}}, \dots, \mathbf{g}_{s_{n_0}}) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_h} \\
 &= \sum_{\substack{s \in \{0,1,2,3\}^h \\ t \in \mathbb{Z}_{\geq 0}^m}} \widehat{P}_3(s, t) H_{t_1}(\mathbf{g}_{h+1}) H_{t_2}(\mathbf{g}_{h+2}) \dots H_{t_m}(\mathbf{g}_{h+m}) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_h}
 \end{aligned}$$

$H_i(x)$ : Hermite polynomials

5. With some extra work, substitute Gaussian vars. by matrix bases

$$P_4 = \sum_{s \in \{0,1,2,3\}^D} \widehat{P}_4(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_D}$$

# Constructions

Noise is required.

Exponentially small

Smooth  
 $\sigma_i \rightarrow \rho^{\delta_{i,0}} \sigma_i$

$$P = \sum_{s \in \{0,1,2,3\}^n} \hat{P}(s) \sigma_s$$

Bounded # of  
 high inf. Coord.

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \hat{P}(s) \rho^{|s|} \sigma_s = P_1^{\leq d} + P_1^{> d}$$

Substitution

$\sigma_i \rightarrow \mathbf{g}_i^{(j)}$

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \hat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \sigma_{s_4} \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n}$$

Dimension  
 reduction

$$P_2 = \sum_{s \in \{0,1,2,3\}^n} \hat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \cdot \mathbf{g}_{s_4}^{(4)} \dots \mathbf{g}_{s_{n-1}}^{(n-1)} \cdot \mathbf{g}_{s_n}^{(n)}$$

Substitution

$\mathbf{g}_i \rightarrow \sigma_i$

$$P_3 = \sum_{s \in \{0,1,2,3\}^{n_0}} f_{s_h}(\mathbf{g}_{s_{h+1}}, \dots, \mathbf{g}_{s_{n_0}}) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_h}$$

$$P_4 = \sum_{s \in \{0,1,2,3\}^D} \hat{P}_4(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_D}$$

# Constructions

Step 1	Smooth	Low degree
Step 2	Regularization	Bounded # of high influential coordinates
Step 3	Substitution: Pauli $\rightarrow$ Gaussian	Bounded # of matrix bases & unbounded # of gaussian
Step 4	Dimension reduction	Bounded # of matrix bases & bounded # of gaussian
Step 5	Substitution: Gaussian $\rightarrow$ Pauli	Bounded # of matrix bases

# Constructions

Step 1	Smooth (unital & linear)	Low degree
Step 2	Regularization	Bounded # of high influential coordinates
Step 3	Substitution Pauli $\rightarrow$ Gaussian	Bounded # of matrix bases & unbounded # of gaussian
Step 4	Dimension reduction (unital & linear)	Bounded # of matrix bases & bounded # of gaussian
Step 5	Substitution Gaussian $\rightarrow$ Pauli	Bounded # of matrix bases

# Constructions

Step 1	Smooth (unital & linear)	Low degree
Step 2	Regularization	Bounded # of high influential coordinates
Step 3	Substitution & <b>rounding</b> : Pauli $\rightarrow$ Gaussian	Bounded # of matrix bases & unbounded # of gaussian
Step 4	Dimension reduction (unital & linear)	Bounded # of matrix bases & bounded # of gaussian
Step 5	Substitution & <b>rounding</b> : Gaussian $\rightarrow$ Pauli	Bounded # of matrix bases

# Constructions

Step 1	Smooth (unital & linear)	Low degree
Step 2	Regularization	Bounded # of high influential coordinates
Step 3	Substitution & rounding: Pauli → Gaussian ( <b>nonlinear</b> )	Bounded # of matrix bases & unbounded # of gaussian
Step 4	Dimension reduction (unital & linear)	Bounded # of matrix bases & bounded # of gaussian
Step 5	Substitution & rounding: Gaussian → Pauli ( <b>nonlinear</b> )	Bounded # of matrix bases

# Constructions

Step 1	Smooth (unital & linear)	Low degree
Step 2	Regularization	Bounded # of high influential coordinates
Step 3	Substitution & rounding: Pauli → Gaussian ( <b>nonlinear</b> ) Quantum Invariance principle & Quantum hypercontractive ineq.	Bounded # of matrix bases & unbounded # of gaussian
Step 4	Dimension reduction (unital & linear)	Bounded # of matrix bases & bounded # of gaussian
Step 5	Substitution & rounding: Gaussian → Pauli ( <b>nonlinear</b> ) Quantum Invariance principle & Quantum hypercontractive ineq.	Bounded # of matrix bases



# Constructions

3. Substitute all bases in low influential coordinates by independent **Gaussian variables**  $(\mathbf{g}_0^{(j)} := 1, \mathbf{g}_1^{(j)}, \mathbf{g}_2^{(j)}, \mathbf{g}_3^{(j)})$ .

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_{h+1}} \otimes \sigma_{s_{h+2}} \otimes \cdots \otimes \sigma_{s_n}$$

$$\begin{array}{ccccccc} & & & \uparrow & \uparrow & & \uparrow \\ & & & \mathbf{g}_{s_{h+1}}^{(h+1)} & \mathbf{g}_{s_{h+2}}^{(h+2)} & & \mathbf{g}_{s_n}^{(n)} \end{array}$$

## Constructions

3. Substitute all bases in low influential coordinates by independent **Gaussian variables**  $(\mathbf{g}_0^{(j)} := 1, \mathbf{g}_1^{(j)}, \mathbf{g}_2^{(j)}, \mathbf{g}_3^{(j)})$ .

$$P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \cdots \mathbf{g}_{s_n}^{(n)} \right)$$

### Requirement.

1.  $0 \leq P', Q' \leq I$

2.  $\Pr[\text{Player 1 outputs 1}] = \frac{\text{Tr } P'}{2^D} \approx \frac{\text{Tr } P}{2^n}$

3.  $\Pr[\text{Player 2 outputs 1}] = \frac{\text{Tr } Q'}{2^D} \approx \frac{\text{Tr } Q}{2^n}$

4.  $\Pr[\text{both output 1}] = \text{Tr}(P' \otimes Q') \Psi_\varepsilon^{\otimes n} \approx \text{Tr}(P \otimes Q) \Psi_\varepsilon^{\otimes D}$

5.  $P'$  only depends on  $P$  and  $Q'$  only depends on  $Q$  (applicable for non-local games)

## Constructions

3. Substitute all bases in low influential coordinates by independent **Gaussian variables**  $(\mathbf{g}_0^{(j)} := 1, \mathbf{g}_1^{(j)}, \mathbf{g}_2^{(j)}, \mathbf{g}_3^{(j)})$ .

$$\mathbf{P}_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \cdots \mathbf{g}_{s_n}^{(n)} \right)$$

### Requirement.

1.  $0 \leq \mathbf{P}_2, \mathbf{Q}_2 \leq I$

2.  $\Pr[\text{Player 1 outputs 1}] = E \left[ \frac{\text{Tr } \mathbf{P}_2}{2^D} \right] \approx \frac{\text{Tr } P}{2^n}$

3.  $\Pr[\text{Player 2 outputs 1}] = E \left[ \frac{\text{Tr } \mathbf{Q}_2}{2^D} \right] \approx \frac{\text{Tr } Q}{2^n}$

4.  $\Pr[\text{both output 1}] = E \left[ \text{Tr}(\mathbf{P}_2 \otimes \mathbf{Q}_2) \Psi_\varepsilon^{\otimes h} \right] \approx \text{Tr}(P \otimes Q) \Psi_\varepsilon^{\otimes n}$

5.  $\mathbf{P}_2$  only depends on  $P$  and  $\mathbf{Q}_2$  only depends on  $Q$  (applicable for non-local games)

## Constructions

3. Substitute all bases in low influential coordinates by independent **Gaussian variables**  $(\mathbf{g}_0^{(j)} := 1, \mathbf{g}_1^{(j)}, \mathbf{g}_2^{(j)}, \mathbf{g}_3^{(j)})$ .

$$\mathbf{P}_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \cdots \mathbf{g}_{s_n}^{(n)} \right)$$

### Requirement.

$$1.0 \leq \mathbf{P}_2, \mathbf{Q}_2 \leq I$$

$$2. \Pr[\text{Player 1 outputs 1}] = E \left[ \frac{\text{Tr } \mathbf{P}_2}{2^D} \right] \approx \frac{\text{Tr } P}{2^n} \quad \checkmark$$

$$3. \Pr[\text{Player 2 outputs 1}] = E \left[ \frac{\text{Tr } \mathbf{Q}_2}{2^D} \right] \approx \frac{\text{Tr } Q}{2^n} \quad \checkmark$$

$$4. \Pr[\text{both output 1}] = E \left[ \text{Tr}(\mathbf{P}_2 \otimes \mathbf{Q}_2) \Psi_\varepsilon^{\otimes h} \right] \approx \text{Tr}(P \otimes Q) \Psi_\varepsilon^{\otimes n} \quad \checkmark$$

5.  $\mathbf{P}_2$  only depends on  $P$  and  $\mathbf{Q}_2$  only depends on  $Q$  (applicable for non-local games)  $\checkmark$

## Constructions

3. Substitute all bases in low influential coordinates by independent **Gaussian variables**  $(\mathbf{g}_0^{(j)} := 1, \mathbf{g}_1^{(j)}, \mathbf{g}_2^{(j)}, \mathbf{g}_3^{(j)})$ .

$$\mathbf{P}_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \cdots \mathbf{g}_{s_n}^{(n)} \right)$$

### Requirement.

1.  $E[\text{dist}(\mathbf{P}_2, \text{POVM elements})] \approx 0$ . Same for  $\mathbf{Q}_2$
2.  $\Pr[\text{Player 1 outputs 1}] = E\left[\frac{\text{Tr } \mathbf{P}_2}{2^D}\right] \approx \frac{\text{Tr } P}{2^n} \quad \checkmark$
3.  $\Pr[\text{Player 2 outputs 1}] = E\left[\frac{\text{Tr } \mathbf{Q}_2}{2^D}\right] \approx \frac{\text{Tr } Q}{2^n} \quad \checkmark$
4.  $\Pr[\text{both output 1}] = E\left[\text{Tr}(\mathbf{P}_2 \otimes \mathbf{Q}_2) \Psi_\varepsilon^{\otimes h}\right] \approx \text{Tr}(P \otimes Q) \Psi_\varepsilon^{\otimes n} \quad \checkmark$
5.  $\mathbf{P}_2$  only depends on  $P$  and  $\mathbf{Q}_2$  only depends on  $Q$  (applicable for non-local games)  $\checkmark$

# Quantum invariance principle

2. Choose a bounded set  $H$  of coordinates with **high influence**

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \overbrace{\sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3}}^H \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n}$$

3. Substitute all bases in low influential coordinates by Gaussian variables

$$P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_h} \cdot \left( \mathbf{g}_{s_{h+1}}^{(h+1)} \cdot \mathbf{g}_{s_{h+2}}^{(h+2)} \dots \mathbf{g}_{s_n}^{(n)} \right)$$

**Quantum Invariance Principle:**

$$E \left[ \left\| \left\| P_2 - POVM \text{ elements} \right\|_2^2 \right\| \right] \leq \varepsilon$$

# Quantum invariance principle

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n} \iff P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \mathbf{g}_{s_{n-1}}^{(n-1)} \sigma_0 \otimes \mathbf{g}_{s_n}^{(n)} \sigma_0$$

$$R(x) := \begin{cases} 1 & \text{if } x \geq 1 \\ x & \text{if } 0 \leq x < 1. \\ 0 & \text{otherwise} \end{cases}$$

$$R(P_1) = P_1 \Rightarrow E[\|R(P_2) - P_2\|_2^2] \approx 0$$

$$\zeta(x) := |x - R(x)|^2 = \begin{cases} x^2 & \text{if } x \leq 0 \\ 0 & \text{if } 0 \leq x \leq 1. \\ (1 - x)^2 & \text{if } x \geq 1. \end{cases}$$

$$\text{Tr} \zeta(P_1) = 0 \Rightarrow E[\text{Tr} \zeta(P_2)] \approx 0$$

# Quantum invariance principle

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n} \iff P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \mathbf{g}_{s_{n-1}}^{(n-1)} \sigma_0 \otimes \mathbf{g}_{s_n}^{(n)} \sigma_0$$

**Goal:**  $\text{Tr} \zeta(P_1) = 0 \Rightarrow E[\text{Tr} \zeta(P_2)] \approx 0$

$$P^{(i)} = \sum_s \widehat{P}_1(s) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_h} \otimes \mathbf{g}_{s_{h+1}}^{(h+1)} \sigma_0 \otimes \dots \otimes \mathbf{g}_{s_{h+i}}^{(h+i)} \sigma_0 \otimes \sigma_{s_{h+i+1}} \otimes \dots$$

$$Q := \sum_{s_{h+i+1}=0} \widehat{P}_1(s) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_h} \otimes \mathbf{g}_{s_{h+1}}^{(h+1)} \sigma_0 \otimes \dots \otimes \mathbf{g}_{s_{h+i+1}}^{(h+i)} \sigma_0 \otimes \sigma_{s_{h+i+1}} \otimes \dots$$

$$R^{(i)} := \sum_{s_{h+i+1} \neq 0} \widehat{P}_1(s) \sigma_{s_1} \otimes \dots \otimes \sigma_{s_h} \otimes \mathbf{g}_{s_{h+1}}^{(h+1)} \sigma_0 \otimes \dots \otimes \mathbf{g}_{s_{h+i}}^{(h+i)} \sigma_0 \otimes \sigma_{s_{h+i+1}} \otimes \dots$$

$$P^{(i)} = Q + R^{(i)}, P^{(i+1)} = Q + R^{(i+1)}$$

$$P_1 = P^{(0)}, P_2 = P^{(n-h)}$$



# Quantum invariance principle

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n} \quad \Big\} P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \mathbf{g}_{s_{n-1}}^{(n-1)} \sigma_0 \otimes \mathbf{g}_{s_n}^{(n)} \sigma_0$$

$$\text{Tr} \zeta(P_1) = 0 \Rightarrow E[\text{Tr} \zeta(P_2)] \approx 0$$

$$\mathbf{P}^{(i)} = \mathbf{Q} + \mathbf{R}^{(i)}, \mathbf{P}^{(i+1)} = \mathbf{Q} + \mathbf{R}^{(i+1)}$$

$$E[\|\mathbf{R}^{(i)}\|_2^2] = \sum_{i:s_i \neq 0} |\widehat{P}_1(s)|^2 = \text{Inf}_i(P_1) \text{ is small!}$$

$$E[\text{Tr} \zeta(\mathbf{P}^{(i)})] \approx E[\text{Tr} \zeta(\mathbf{P}^{(i+1)})]$$

Taylor expanding  $\text{Tr} \zeta(\cdot)$  at  $\mathbf{Q}$

$\zeta(\cdot) \in C^1$  not very smooth !

$$\zeta(x) = \begin{cases} x^2 & \text{if } x \leq 0 \\ 0 & \text{if } 0 \leq x \leq 1. \\ (1-x)^2 & \text{if } x \geq 1. \end{cases}$$

# Quantum invariance principle

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n} \quad \Big\} \quad P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \mathbf{g}_{s_{n-1}}^{(n-1)} \sigma_0 \otimes \mathbf{g}_{s_n}^{(n)} \sigma_0$$

$$\text{Tr} \zeta(P_1) = 0 \Rightarrow E[\text{Tr} \zeta(\mathbf{P}_2)] \approx 0$$

$$\mathbf{P}^{(i)} = \mathbf{Q} + \mathbf{R}^{(i)}, \mathbf{P}^{(i+1)} = \mathbf{Q} + \mathbf{R}^{(i+1)}$$

$$E[\|\mathbf{R}^{(i)}\|_2^2] = \sum_{i:s_i \neq 0} |\widehat{P}_1(s)|^2 = \text{Inf}_i(P_1) \text{ is small!}$$

$$E[\text{Tr} \zeta(\mathbf{P}^{(i)})] \approx E[\text{Tr} \zeta(\mathbf{P}^{(i+1)})]$$

- $\zeta_\lambda \approx \zeta$
- $\zeta_\lambda \in \mathbb{C}^2$

$$\zeta_\lambda(x) := \begin{cases} x^2 + \frac{1}{3}\lambda^2 & \text{if } x \leq -\lambda \\ \frac{(\lambda-x)^3}{6\lambda} & \text{if } -\lambda \leq x \leq \lambda \\ 0 & \text{if } \lambda \leq x \leq 1-\lambda \\ \frac{(x-1+\lambda)^3}{6\lambda} & \text{if } 1-\lambda \leq x \leq 1+\lambda \\ (1-x)^2 + \frac{1}{3}\lambda^2 & \text{if } x \geq 1+\lambda. \end{cases}$$

$$E[\text{Tr} \zeta_\lambda(\mathbf{P}^{(i)})] \approx E[\text{Tr} \zeta_\lambda(\mathbf{P}^{(i+1)})]$$

# Quantum invariance principle

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \sigma_{s_n} \quad \Bigg| \quad P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \cdots \otimes \mathbf{g}_{s_{n-1}}^{(n-1)} \sigma_0 \otimes \mathbf{g}_{s_n}^{(n)} \sigma_0$$

$$\text{Tr} \zeta(P_1) = 0 \Rightarrow E[\text{Tr} \zeta_\lambda(P_2)] \approx 0$$

$$\mathbf{P}^{(i)} = \mathbf{Q} + \mathbf{R}^{(i)}, \mathbf{P}^{(i+1)} = \mathbf{Q} + \mathbf{R}^{(i+1)}$$

$$E[\text{Tr} \zeta_\lambda(\mathbf{P}^{(i)})] - E[\text{Tr} \zeta_\lambda(\mathbf{Q})] =$$

$$E[\text{Tr} f_1(\mathbf{Q})\mathbf{R}^{(i)}] + E\left[\text{Tr} \left( f_2(\mathbf{Q})\mathbf{R}^{(i)} f_3(\mathbf{Q})\mathbf{R}^{(i)} + f_4(\mathbf{Q})(\mathbf{R}^{(i)})^2 \right)\right] + 3^{\text{rd}} \text{ term}$$

$$E[\text{Tr} \zeta_\lambda(\mathbf{P}^{(i+1)})] - E[\text{Tr} \zeta_\lambda(\mathbf{Q})] =$$

$$E[\text{Tr} f_1(\mathbf{Q})\mathbf{R}^{(i+1)}] + E\left[\text{Tr} \left( f_2(\mathbf{Q})\mathbf{R}^{(i+1)} f_3(\mathbf{Q})\mathbf{R}^{(i+1)} + f_4(\mathbf{Q})(\mathbf{R}^{(i+1)})^2 \right)\right] + 3^{\text{rd}} \text{ term}$$

Fréchet derivative:

$$Df(A)(B) = \left. \frac{d}{dt} f(A + tB) \right|_{t=0}$$

# Quantum invariance principle

$$P_1 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \sigma_{s_{n-1}} \otimes \sigma_{s_n} \iff P_2 = \sum_{s \in \{0,1,2,3\}^n} \widehat{P}_1(s) \sigma_{s_1} \otimes \sigma_{s_2} \otimes \sigma_{s_3} \otimes \dots \otimes \mathbf{g}_{s_{n-1}}^{(n-1)} \sigma_0 \otimes \mathbf{g}_{s_n}^{(n)} \sigma_0$$

$$\begin{aligned} & \mathbb{E}[\text{Tr } \zeta_\lambda(\mathbf{P}^{(i)})] - \mathbb{E}[\text{Tr } \zeta_\lambda(\mathbf{Q})] = \\ & \mathbb{E}[\text{Tr } f_1(\mathbf{Q})\mathbf{R}^{(i)}] + \mathbb{E}[\text{Tr } (f_2(\mathbf{Q})\mathbf{R}^{(i)}f_3(\mathbf{Q})\mathbf{R}^{(i)} + f_4(\mathbf{Q})(\mathbf{R}^{(i)})^2)] + 3^{\text{rd}} \text{ term} \end{aligned}$$

$$\begin{aligned} & \mathbb{E}[\text{Tr } \zeta_\lambda(\mathbf{P}^{(i+1)})] - \mathbb{E}[\text{Tr } \zeta_\lambda(\mathbf{Q})] = \\ & \mathbb{E}[\text{Tr } f_1(\mathbf{Q})\mathbf{R}^{(i+1)}] + \mathbb{E}[\text{Tr } (f_2(\mathbf{Q})\mathbf{R}^{(i+1)}f_3(\mathbf{Q})\mathbf{R}^{(i+1)} + f_4(\mathbf{Q})(\mathbf{R}^{(i+1)})^2)] + 3^{\text{rd}} \text{ term} \end{aligned}$$

- 1<sup>st</sup> order and 2<sup>nd</sup> order match.
- 3<sup>rd</sup> order terms  $\leq O(E[|||\mathbf{R}^{(i)}|||_3^3])$
- $E[\text{Tr } \zeta(\mathbf{P}_2)] \leq O(\sum_i E[|||\mathbf{R}^{(i)}|||_3^3])$
- $E[|||\mathbf{R}^{(i)}|||_2^2] = \text{Inf}_i(P)$  is small

# Quantum hypercontractive inequality

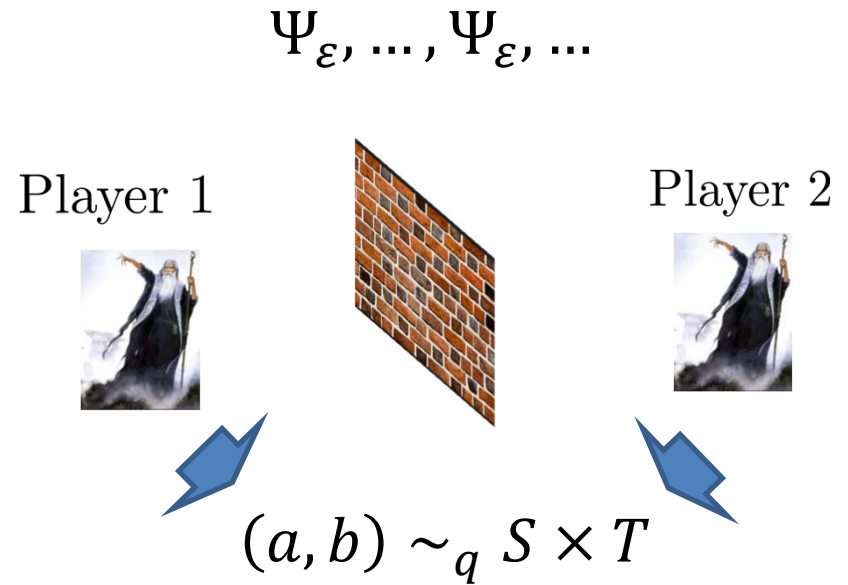
## Quantum hypercontractive inequality

$$\|R\|_2 \leq \|R\|_3 \leq 3^{\frac{\deg(R)}{2}} \|R\|_2$$

$$\begin{aligned} E[\text{Tr } \zeta(\mathbf{P}_2)] &\leq O\left(\sum_i E\left[\|\mathbf{R}_2^{(i)}\|_3^3\right]\right) \\ &\leq 3^{O(d)} \sum_i E\left[\|\mathbf{R}_2^{(i)}\|_2^2\right]^{3/2} \\ &\leq 3^{O(d)} \sum_i \text{Inf}_i(P)^{\frac{3}{2}} \\ &\leq 3^{O(d)} \cdot \sum_j \text{Inf}_j(P) \cdot \left(\max_i \sqrt{\text{Inf}_i(P)}\right) \\ &\leq 3^{O(d)} d \cdot \epsilon \end{aligned}$$

# Future directions & open problems

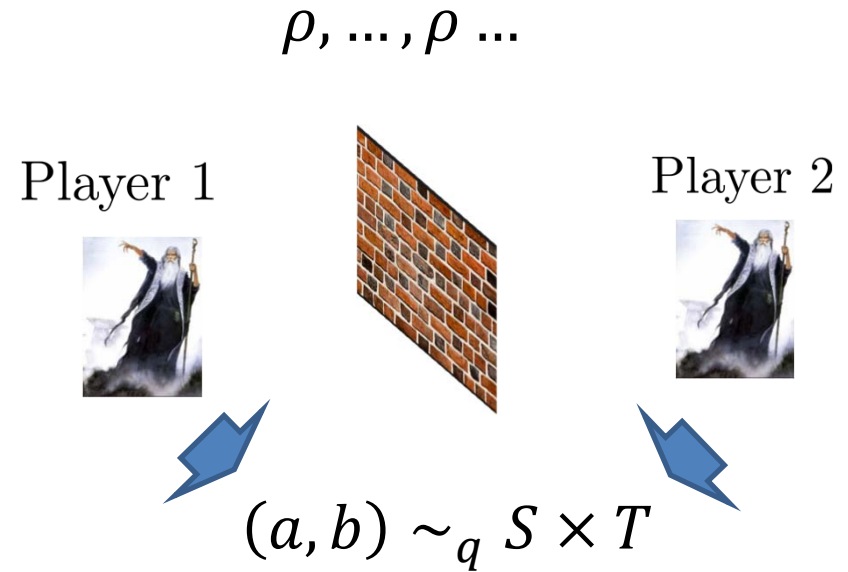
- Target distributions are non-binary?



# Future directions & open problems

- Target distributions are non-binary?
- Decidability of general mono-state games

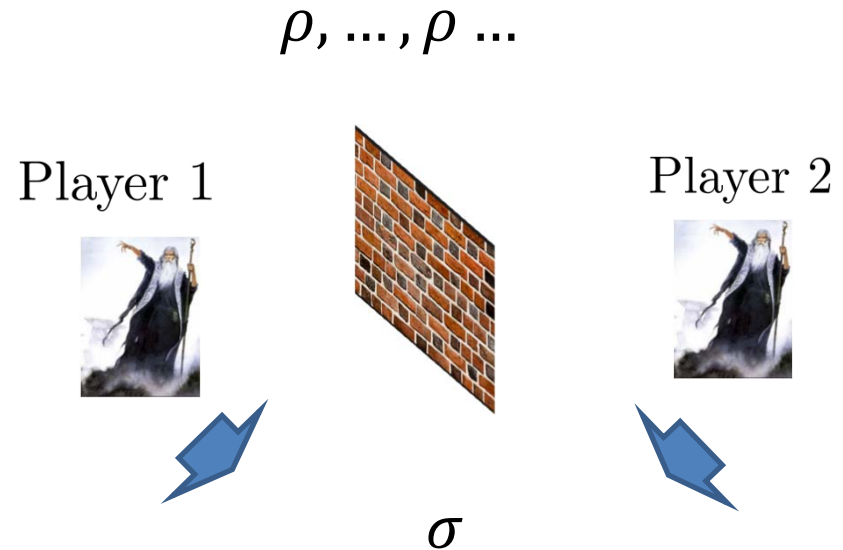
**Conjecture:** decidable if shared states are noisy.



# Future directions & open problems

- Target distributions are non-binary?
- Decidability of general mono-state games

**Conjecture:** decidable if shared states are noisy.



- Decidability of local state transformations and non-local games with quantum answers and quantum predicates?



# Future directions & open problems

- High dimensional quantum hypercontractive inequality?
- Multivariate quantum invariance principle?
- Computability of tensored quantities: quantum channel capacities, regularized entanglement measures, quantum information complexity etc.
- Other applications of Boolean analysis on quantum information theory and quantum complexity theory

**Thank you**