• Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms
 - 2 Network Flows, Shortest Paths and other graph algorithms

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms
 - Petwork Flows, Shortest Paths and other graph algorithms
 - Sophisticated data strunctures

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms
 - 2 Network Flows, Shortest Paths and other graph algorithms
 - Sophisticated data strunctures
 - Optimization.

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms
 - 2 Network Flows, Shortest Paths and other graph algorithms
 - Sophisticated data strunctures
 - Optimization.
- Whp, answer would have been: (2) and (3).

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms
 - 2 Network Flows, Shortest Paths and other graph algorithms
 - Sophisticated data strunctures
 - Optimization.
- Whp, answer would have been: (2) and (3).
- Reality: Perhaps more (1) and (4).

- Circa 1990, if you asked a random Theory person, which of these methods would scale up and get applied to large problems:
 - Singular Value Decomposition (SVD), other LA algorithms
 - 2 Network Flows, Shortest Paths and other graph algorithms
 - Sophisticated data strunctures
 - Optimization.
- Whp, answer would have been: (2) and (3).
- Reality: Perhaps more (1) and (4).
- Crucial help: from Continuous Mathematics, Developments in Randomized algorithms.

SVD in Learning

Random Selection

• Topic Modeling, Clustering.

SVD in Learning

Random Selection

- Topic Modeling, Clustering.
- Learning Mixtures of Gaussians Vempala and Wong: For a mixture of spherical Gaussians, the SVD subspace is the space of component means → Learning Algorithm.

SVD in Learning

Random Selection

- Topic Modeling, Clustering.
- Learning Mixtures of Gaussians Vempala and Wong: For a mixture of spherical Gaussians, the SVD subspace is the space of component means → Learning Algorithm.
- Non-negative Matrix Factorization (NMF)

() Randomized Algorithms \equiv Algorithm tosses Coins.



() Randomized Algorithms \equiv Algorithm tosses Coins.

• But, data Worst-Case.

- Randomized Algorithms = Algorithm tosses Coins.
 - But, data Worst-Case.
- Average Case (Probabilistic) Analysis: Data tosses coins. Algorithm is deterministic.

- Randomized Algorithms \equiv Algorithm tosses Coins.
 - But, data Worst-Case.
- Average Case (Probabilistic) Analysis: Data tosses coins. Algorithm is deterministic.
- Hybrids also possible.
- Here more (1) than (2). More useful for large matrices peculiar to a single context, like Web, FB graph,

• Modern data matrices can be massive (> 10⁸ non-zero entries).

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and
 - Ability to Sample on the fly.

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and
 - Ability to Sample on the fly.
- Input data matrix may be distributed among servers. Randomization will help reduce communication.

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and
 - Ability to Sample on the fly.
- Input data matrix may be distributed among servers. Randomization will help reduce communication.
- Two Scenarios, One method:

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and
 - Ability to Sample on the fly.
- Input data matrix may be distributed among servers. Randomization will help reduce communication.
- Two Scenarios, One method:
 - Entire matrix exists (eg. Web). Alg. draws sample.

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and
 - Ability to Sample on the fly.
- Input data matrix may be distributed among servers. Randomization will help reduce communication.
- Two Scenarios, One method:
 - Entire matrix exists (eg. Web). Alg. draws sample.
 - Only sample of entries known: Netflix, Recommendation Systems. [Need handle on sampling probabilities to assert error bounds.]

- Modern data matrices can be massive (> 10⁸ non-zero entries).
 - $O(n^3)$ algorithms are too expensive. Time
 - RAM Cannot store matrix. So, an entry cannot be accessed in unit time. space.
- A Simple form of RA: Computes on a sample of rows/coulmns of matrix. Need:
 - Proven error guarantees and
 - Ability to Sample on the fly.
- Input data matrix may be distributed among servers. Randomization will help reduce communication.
- Two Scenarios, One method:
 - Entire matrix exists (eg. Web). Alg. draws sample.
 - Only sample of entries known: Netflix, Recommendation Systems. [Need handle on sampling probabilities to assert error bounds.]
 - Here, think of (1) generally.



• A an $m \times n$ data matrix, n, m large.



- A an $m \times n$ data matrix, n, m large.
- Do s i.i.d. trials; in each trial:



- A an $m \times n$ data matrix, n, m large.
- Do s i.i.d. trials; in each trial:
 - Pick a random column of A and scale it.



- A an $m \times n$ data matrix, n, m large.
- Do s i.i.d. trials; in each trial:
 - Pick a random column of A and scale it.
- Compute only with the sampled and scaled $n \times s$ matrix.

The Setting

- A an $m \times n$ data matrix, n, m large.
- Do s i.i.d. trials; in each trial:
 - Pick a random column of A and scale it.
- Compute only with the sampled and scaled $n \times s$ matrix.



• Matrix Multiplication:

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Graph Sparsification

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Graph Sparsification
- Linear Regression.

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Graph Sparsification
- Linear Regression.
- Tensors: Spectral Norm.

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Graph Sparsification
- Linear Regression.
- Tensors: Spectral Norm.
- Two things:

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Graph Sparsification
- Linear Regression.
- Tensors: Spectral Norm.
- Two things:
 - No Free Lunch. Samples can only get approximate answers.

- Matrix Multiplication:
 - Compute (approximately) (all entires of) AA^{T} .
 - More Generally: AB.
- Singular Value Decomposition, Low Rank Approximation.
- Matrix Sketches. [Compact representations of matrix.]
- Graph Sparsification
- Linear Regression.
- Tensors: Spectral Norm.
- Two things:
 - No Free Lunch. Samples can only get approximate answers.
 - But we will prove error bounds for all input matrices.

•
$$||A||_{F}^{2} = \sum_{i,j} A_{ij}^{2}$$

•
$$||A||_{F}^{2} = \sum_{i,j} A_{ij}^{2}$$

• $||A||_{2} = \text{Max}_{|X|=1} |AX|$ (Spectral norm)

- $||A||_F^2 = \sum_{i,j} A_{ij}^2$
- $||A||_2 = Max_{|x|=1}|Ax|$ (Spectral norm)
- *A* is *m* × *n*.

- $||A||_{F}^{2} = \sum_{i,j} A_{ij}^{2}$
- $||A||_2 = Max_{|x|=1}|Ax|$ (Spectral norm)
- *A* is *m* × *n*.
- *s* number of sampled columns.

• Seek a rank k approximation A* to A with

• Seek a rank *k* approximation *A*^{*} to *A* with

•
$$||A - A^*||_F \le \underbrace{\text{Best Possible}}_{\text{SVD}} + \underbrace{\varepsilon ||A||_F}_{\text{Sampling Error}}$$
.



Theorem s =poly(k/ε) suffices provided

- Seek a rank k approximation A* to A with
 - $||A A^*||_F \le \underbrace{\text{Best Possible}}_{SVD} + \underbrace{\varepsilon ||A||_F}_{Sampling Error}$
- Theorem $s = poly(k/\epsilon)$ suffices provided
- Sampling is done with probabilities proportional to squared length of columns.

- Seek a rank k approximation A* to A with
 - $||A A^*||_F \le \underbrace{\text{Best Possible}}_{SVD} + \underbrace{\varepsilon ||A||_F}_{Sampling Error}$
- Theorem $s = poly(k/\epsilon)$ suffices provided
- Sampling is done with probabilities proportional to squared length of columns.
- Only interesting if ε||A||_F < (Best Possible SVD error). Holds for PCA matrices.

- Seek a rank k approximation A* to A with
 - $||A A^*||_F \le \underbrace{\text{Best Possible}}_{SVD} + \underbrace{\varepsilon ||A||_F}_{Sampling Error}$
- Theorem $s = poly(k/\epsilon)$ suffices provided
- Sampling is done with probabilities proportional to squared length of columns.
- Only interesting if ε||A||_F < (Best Possible SVD error). Holds for PCA matrices.
 - "Length-squared sampling". Frieze, Kannan, Vempala (1998)

- Seek a rank k approximation A* to A with
 - $||A A^*||_F \le \underbrace{\text{Best Possible}}_{SVD} + \underbrace{\varepsilon ||A||_F}_{Sampling Error}$
- Theorem $s = poly(k/\epsilon)$ suffices provided
- Sampling is done with probabilities proportional to squared length of columns.
- Only interesting if ε||A||_F < (Best Possible SVD error). Holds for PCA matrices.
 - "Length-squared sampling". Frieze, Kannan, Vempala (1998)
 - Many improvements: Drineas, Mahoney, Sarlos, Deshpande, Rademacher,

- Seek a rank k approximation A* to A with
 - $||A A^*||_F \le \underbrace{\text{Best Possible}}_{SVD} + \underbrace{\varepsilon ||A||_F}_{Sampling Error}$
- Theorem $s = poly(k/\varepsilon)$ suffices provided
- Sampling is done with probabilities proportional to squared length of columns.
- Only interesting if ε||A||_F < (Best Possible SVD error). Holds for PCA matrices.
 - "Length-squared sampling". Frieze, Kannan, Vempala (1998)
 - Many improvements: Drineas, Mahoney, Sarlos, Deshpande, Rademacher,
- Alternative Scheme: Draw a sample of entries, set others to zero. Sparsity gain rather than reduction in dimensions. Achlioptas, McSherry; Bhojanapalli, Jain and Sanghavi.

AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.

- AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.
- i.i.d. trials. p_j =probability of picking column j, j = 1,2,...,n. What are good p_j?

- AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.
- i.i.d. trials. p_j =probability of picking column j, j = 1,2,...,n. What are good p_j?
- Uniform Sampling no good. Eg. All but one column of A is all zeros.

- AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.
- i.i.d. trials. p_j =probability of picking column j, j = 1,2,...,n. What are good p_j?
- Uniform Sampling no good. Eg. All but one column of A is all zeros.
- Unbiased Estimator: $X = \frac{1}{p_j}$ (Col. *j* of *A*) (Row *j* of *A*) (Scaling)

- AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.
- i.i.d. trials. p_j =probability of picking column j, j = 1,2,...,n. What are good p_j?
- Uniform Sampling no good. Eg. All but one column of A is all zeros.
- Unbiased Estimator: $X = \frac{1}{p_i}$ (Col. *j* of *A*) (Row *j* of *A*) (Scaling)
- Calculus: Length squared minimizes the variance.

- AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.
- i.i.d. trials. p_j =probability of picking column j, j = 1,2,...,n. What are good p_j?
- Uniform Sampling no good. Eg. All but one column of A is all zeros.
- Unbiased Estimator: $X = \frac{1}{D_i}$ (Col. *j* of *A*) (Row *j* of *A*) (Scaling)
- Calculus: Length squared minimizes the variance.
- With average of *s* samples:

 $E(||AA^T - \text{Estimate of } AA^T||_F) \leq \frac{||A||_F^2}{\sqrt{s}}.$

- AA^T = ∑_j(Col.j of A) (Rowj of A). [Outer Product]. Estimate by a sample of j.
- i.i.d. trials. p_j =probability of picking column j, j = 1,2,...,n. What are good p_j?
- Uniform Sampling no good. Eg. All but one column of A is all zeros.
- Unbiased Estimator: $X = \frac{1}{D_i}$ (Col. *j* of *A*) (Row *j* of *A*) (Scaling)
- Calculus: Length squared minimizes the variance.
- With average of *s* samples:

 $E(||AA^{T} - \text{Estimate of } AA^{T}||_{F}) \leq \frac{||A||_{F}^{2}}{\sqrt{s}}.$

 Drineas, Kannan, Mahoney (Approx) Matrix Multiplication in O^{*}(n²) time.

• Massive Data - too large to be stored in RAM.

- Massive Data too large to be stored in RAM.
- Simplified Model: Three resources RAM time, space, Number of passes. Pass is a sequential read of entire matrix.

- Massive Data too large to be stored in RAM.
- Simplified Model: Three resources RAM time, space, Number of passes. Pass is a sequential read of entire matrix.
- Sampling Algorithms use O(1) passes and RAM space = O(1) columns/rows of matrix. One pass computes length squared probabilities. Pass 2 draws the sample and then only RAM computation.

- Massive Data too large to be stored in RAM.
- Simplified Model: Three resources RAM time, space, Number of passes. Pass is a sequential read of entire matrix.
- Sampling Algorithms use O(1) passes and RAM space = O(1) columns/rows of matrix. One pass computes length squared probabilities. Pass 2 draws the sample and then only RAM computation.
- An approximate Low rank Approximation can be carried out even in the Streaming Model - Edo Liberty (a vector version of frequent item mining).

- Massive Data too large to be stored in RAM.
- Simplified Model: Three resources RAM time, space, Number of passes. Pass is a sequential read of entire matrix.
- Sampling Algorithms use O(1) passes and RAM space = O(1) columns/rows of matrix. One pass computes length squared probabilities. Pass 2 draws the sample and then only RAM computation.
- An approximate Low rank Approximation can be carried out even in the Streaming Model - Edo Liberty (a vector version of frequent item mining).
- Also, one can first do length squared sampling to pick s columns, then again do length squared sampling to pick s rows (to form a s × s matrix) and so use only O(1) RAM space. Proof gets very complicated.

 Can a sample of rows form a sketch of the matrix? No. Sample of rows tells us nothing about the unsampled rows.

- Can a sample of rows form a sketch of the matrix? No. Sample of rows tells us nothing about the unsampled rows.
- How about a sample of rows and a sample of columns ? Will see the answer is Yes.

Sketch of a matrix

- Can a sample of rows form a sketch of the matrix? No. Sample of rows tells us nothing about the unsampled rows.
- How about a sample of rows and a sample of columns ? Will see the answer is Yes.
- First suppose *A* has rank *k*. Then a sample of 100*k* rows should pin down the row space of *A*.

- Can a sample of rows form a sketch of the matrix? No. Sample of rows tells us nothing about the unsampled rows.
- How about a sample of rows and a sample of columns ? Will see the answer is Yes.
- First suppose *A* has rank *k*. Then a sample of 100*k* rows should pin down the row space of *A*.
- But still don't know for an unsampled row what linear combination it is. Suppose we also pick a sample of 100k columns. Now, intuitively, (if the rows are in general position), there should be a unique linear way of expressing each row (in the 100k-column matrix) in the row space.

Length squared sample of rows and col.'s suffice

• *A* is *m* × *n*.

Length squared sample of rows and col.'s suffice

- *A* is *m* × *n*.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- A is $m \times n$.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- *R* is $\sqrt{s} \times n$ formed by sampling \sqrt{s} rows of *A* according to length squared.

- A is $m \times n$.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- *R* is $\sqrt{s} \times n$ formed by sampling \sqrt{s} rows of *A* according to length squared.
- Given just *C*, *R*, can find a $s \times \sqrt{s}$ matrix *U* such that

- A is $m \times n$.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- *R* is $\sqrt{s} \times n$ formed by sampling \sqrt{s} rows of *A* according to length squared.
- Given just *C*, *R*, can find a $s \times \sqrt{s}$ matrix *U* such that

•
$$E\left(||A-CUR||_2^2\right) \leq \frac{c||A||_F^2}{\sqrt{s}}$$
.

- A is $m \times n$.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- *R* is $\sqrt{s} \times n$ formed by sampling \sqrt{s} rows of *A* according to length squared.
- Given just *C*, *R*, can find a $s \times \sqrt{s}$ matrix *U* such that
- $E(||A CUR||_2^2) \le \frac{c||A||_F^2}{\sqrt{s}}$.
- Drineas, Kannan, Mahoney (2002)

- A is $m \times n$.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- *R* is $\sqrt{s} \times n$ formed by sampling \sqrt{s} rows of *A* according to length squared.
- Given just *C*, *R*, can find a $s \times \sqrt{s}$ matrix *U* such that
- $E(||A CUR||_2^2) \le \frac{c||A||_F^2}{\sqrt{s}}$.
- Drineas, Kannan, Mahoney (2002)
- Bourtsides and Woodruff (2015) Optimal time, size of *U*.

- A is $m \times n$.
- *C* is *m* × *s* formed by sampling (and scaling) *s* columns of *A* according to length squared.
- *R* is $\sqrt{s} \times n$ formed by sampling \sqrt{s} rows of *A* according to length squared.
- Given just *C*, *R*, can find a $s \times \sqrt{s}$ matrix *U* such that

•
$$E(||A - CUR||_2^2) \le \frac{c||A||_F^2}{\sqrt{s}}$$
.

- Drineas, Kannan, Mahoney (2002)
- Bourtsides and Woodruff (2015) Optimal time, size of U.

$$A \qquad \Bigg| \approx \left(\begin{array}{c} C \\ \end{array} \right) \left(\begin{array}{c} U \\ \end{array} \right) \left(\begin{array}{c} R \\ \end{array} \right)$$

• Traditional SVD, given data matrix *A*, finds best rank *k* approximation *A_k* to *A*. Two issues:

- Traditional SVD, given data matrix *A*, finds best rank *k* approximation *A_k* to *A*. Two issues:
 - Computation time.

- Traditional SVD, given data matrix *A*, finds best rank *k* approximation *A_k* to *A*. Two issues:
 - Computation time.
 - Not "interpolative". Gene Patient Matrix. You tell the Biologist: The principal component is 17 times first patient - 12 times 31st patient + 2.5 times the 7 th ...

- Traditional SVD, given data matrix *A*, finds best rank *k* approximation *A_k* to *A*. Two issues:
 - Computation time.
 - Not "interpolative". Gene Patient Matrix. You tell the Biologist: The principal component is 17 times first patient - 12 times 31st patient + 2.5 times the 7 th ...
- Interpolative approximation useful in Genetics, other areas Drineas, Mahoney.

- Traditional SVD, given data matrix *A*, finds best rank *k* approximation *A_k* to *A*. Two issues:
 - Computation time.
 - Not "interpolative". Gene Patient Matrix. You tell the Biologist: The principal component is 17 times first patient - 12 times 31st patient + 2.5 times the 7 th ...
- Interpolative approximation useful in Genetics, other areas Drineas, Mahoney.
- DataBase applications Falustos

• *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.

- *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.
- Varience-covarience matrix M: $M_{ij} = E_P(x_i x_j)$.

- *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.
- Varience-covarience matrix *M*: $M_{ij} = E_P(x_i x_j)$.
- $A d \times \infty$ matrix with each column a sample weighted by prob.

- *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.
- Varience-covarience matrix *M*: $M_{ij} = E_P(x_i x_j)$.
- $A d \times \infty$ matrix with each column a sample weighted by prob.
- Varience along **v** is $\mathbf{v}^T A A^T \mathbf{v} = |\mathbf{v}^T A|^2$.

- *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.
- Varience-covarience matrix *M*: $M_{ij} = E_P(x_i x_j)$.
- $A d \times \infty$ matrix with each column a sample weighted by prob.
- Varience along **v** is $\mathbf{v}^T A A^T \mathbf{v} = |\mathbf{v}^T A|^2$.
- Sample Complexity: How many i.i.d. samples according to P suffice to estimate varience to relative error along every direction?

AA^T and Varience-covarience matrix

- *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.
- Varience-covarience matrix *M*: $M_{ij} = E_P(x_i x_j)$.
- $A d \times \infty$ matrix with each column a sample weighted by prob.
- Varience along **v** is $\mathbf{v}^T A A^T \mathbf{v} = |\mathbf{v}^T A|^2$.
- Sample Complexity: How many i.i.d. samples according to P suffice to estimate varience to relative error along every direction?
- Want to sample a (finite, scaled) sub-matrix *B* of *A* so that $\forall \mathbf{v} : |\mathbf{v}^T B| = (1 \pm \varepsilon) |\mathbf{v}^T A|.$

AA^T and Varience-covarience matrix

- *P* probability distribution (density or discrete) on **R**^{*d*}. Mean **0**.
- Varience-covarience matrix *M*: $M_{ij} = E_P(x_i x_j)$.
- $A d \times \infty$ matrix with each column a sample weighted by prob.
- Varience along **v** is $\mathbf{v}^T A A^T \mathbf{v} = |\mathbf{v}^T A|^2$.
- Sample Complexity: How many i.i.d. samples according to P suffice to estimate varience to relative error along every direction?
- Want to sample a (finite, scaled) sub-matrix *B* of *A* so that $\forall \mathbf{v} : |\mathbf{v}^T B| = (1 \pm \varepsilon) |\mathbf{v}^T A|.$
- Question in this form arose in Volume computation and log-concave sampling Kannan, Lovász, Simonovits.

• Previously: Length-squared sampling estimate for AA^T satisfies: $E(||AA^T - \text{Estimate}||_F) \le \frac{||A||_F^2}{\sqrt{s}}$. (Proof Elementary)

- Previously: Length-squared sampling estimate for AA^T satisfies: $E(||AA^T - \text{Estimate}||_F) \le \frac{||A||_F^2}{\sqrt{s}}$. (Proof Elementary)
- Rudelson, Vershynin using beautiful technique of "Decoupling" from Probability, Functional Analysis proved:

- Previously: Length-squared sampling estimate for AA^T satisfies: $E(||AA^T - \text{Estimate}||_F) \le \frac{||A||_F^2}{\sqrt{s}}$. (Proof Elementary)
- Rudelson, Vershynin using beautiful technique of "Decoupling" from Probability, Functional Analysis proved:
- $E(||AA^T \text{Estimate}||_2) \le \frac{c||A||_F||A||_2}{\sqrt{s}}$.

- Previously: Length-squared sampling estimate for AA^T satisfies: $E(||AA^T - \text{Estimate}||_F) \le \frac{||A||_F^2}{\sqrt{s}}$. (Proof Elementary)
- Rudelson, Vershynin using beautiful technique of "Decoupling" from Probability, Functional Analysis proved:
- $E(||AA^T \text{Estimate}||_2) \leq \frac{c||A||_F||A||_2}{\sqrt{s}}$.
- Much more than a technical improvement as we will see.

- Previously: Length-squared sampling estimate for AA^T satisfies: $E(||AA^T - \text{Estimate}||_F) \le \frac{||A||_F^2}{\sqrt{s}}$. (Proof Elementary)
- Rudelson, Vershynin using beautiful technique of "Decoupling" from Probability, Functional Analysis proved:
- $E(||AA^T \text{Estimate}||_2) \le \frac{c||A||_F ||A||_2}{\sqrt{s}}$.
- Much more than a technical improvement as we will see.
- Now simpler proofs based on Matrix Höffding-Chernoff inequalities: Eg. Tropp: "User friendly tail bounds for sums of random marices"

- Previously: Length-squared sampling estimate for AA^T satisfies: $E(||AA^T - \text{Estimate}||_F) \le \frac{||A||_F^2}{\sqrt{s}}$. (Proof Elementary)
- Rudelson, Vershynin using beautiful technique of "Decoupling" from Probability, Functional Analysis proved:
- $E(||AA^T \text{Estimate}||_2) \leq \frac{c||A||_F||A||_2}{\sqrt{s}}$.
- Much more than a technical improvement as we will see.
- Now simpler proofs based on Matrix Höffding-Chernoff inequalities: Eg. Tropp: "User friendly tail bounds for sums of random marices"
- Rudelson, Vershynin Theorem implies for log-concave probability densities on R^d, O^{*}(d) samples suffice (improving earlier answers of Pisier and Bourgain).

• Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.

- Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.
- Want sparser sub-graph H (with O*(n) edges, say,), so that all cuts are approximately right.Benzur, Karger

- Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.
- Want sparser sub-graph H (with O*(n) edges, say,), so that all cuts are approximately right.Benzur, Karger
- Stronger condition (than cuts):

- Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.
- Want sparser sub-graph H (with O*(n) edges, say,), so that all cuts are approximately right.Benzur, Karger
- Stronger condition (than cuts):

•
$$\forall \mathbf{v}, |\mathbf{v}^T A_G| = (1 \pm \varepsilon) |\mathbf{v}^T A_H|$$

- Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.
- Want sparser sub-graph H (with O^{*}(n) edges, say,), so that all cuts are approximately right.Benzur, Karger
- Stronger condition (than cuts):

•
$$\forall \mathbf{v}, |\mathbf{v}^T A_G| = (1 \pm \varepsilon) |\mathbf{v}^T A_H|$$

• Same question as approximating varience-covarince matrix.

- Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.
- Want sparser sub-graph H (with O*(n) edges, say,), so that all cuts are approximately right.Benzur, Karger
- Stronger condition (than cuts):

•
$$\forall \mathbf{v}, |\mathbf{v}^T A_G| = (1 \pm \varepsilon) |\mathbf{v}^T A_H|$$

- Same question as approximating varience-covarince matrix.
- Rudelson-Vershynin implies: $\forall \mathbf{v} : ||\mathbf{v}^T A_G|^2 |\mathbf{v}^T A_H|^2| \le \frac{cn||A||_2^2 |\mathbf{v}|^2}{s}$

- Spielman and Srivatsava: *G* graph with *n* nodes and *m* edges; A_G = node-edge incidence matrix.
- Want sparser sub-graph H (with O*(n) edges, say,), so that all cuts are approximately right.Benzur, Karger
- Stronger condition (than cuts):

•
$$\forall \mathbf{v}, |\mathbf{v}^T A_G| = (1 \pm \varepsilon) |\mathbf{v}^T A_H|$$

- Same question as approximating varience-covarince matrix.
- Rudelson-Vershynin implies: $\forall \mathbf{v} : \left| |\mathbf{v}^T A_G|^2 |\mathbf{v}^T A_H|^2 \right| \le \frac{cn||A||_2^2 |\mathbf{v}|^2}{s}$.
- Not good enough. But if only make A_G an isometry, $||A_G||_2 |\mathbf{v}|^2 = |\mathbf{v}^T A_G|^2$ and take $s \ge cn$, it all works.

• A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.

- A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.
- Sample columns of *A* according to length-squared probabilities from *WA*:

- A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.
- Sample columns of *A* according to length-squared probabilities from *WA*:
 - Let $p_j = (\text{length squared of col } j \text{ of } WA) / ||WA||_F^2$.

- A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.
- Sample columns of *A* according to length-squared probabilities from *WA*:
 - Let $p_j = (\text{length squared of col } j \text{ of } WA) / ||WA||_F^2$.
 - Repeat *s* times: Pick col. *j* of *A* with probability p_j and scale it by $1/p_j$ to form a $n \times s$ matrix *B*.

- A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.
- Sample columns of *A* according to length-squared probabilities from *WA*:
 - Let $p_j = (\text{length squared of col } j \text{ of } WA) / ||WA||_F^2$.
 - Repeat *s* times: Pick col. *j* of *A* with probability p_j and scale it by $1/p_j$ to form a $n \times s$ matrix *B*.

•
$$\forall \mathbf{v} : |\mathbf{v}^T B|^2 = (1 \pm \frac{c\sqrt{n}}{\sqrt{s}}) |\mathbf{v}^T A|^2$$
. Rudelson, Vershynin
Pre-conditioned length squared sampling

- A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.
- Sample columns of *A* according to length-squared probabilities from *WA*:
 - Let $p_j = (\text{length squared of col } j \text{ of } WA) / ||WA||_F^2$.
 - Repeat *s* times: Pick col. *j* of *A* with probability p_j and scale it by $1/p_j$ to form a $n \times s$ matrix *B*.
- $\forall \mathbf{v} : |\mathbf{v}^T B|^2 = (1 \pm \frac{c\sqrt{n}}{\sqrt{s}}) |\mathbf{v}^T A|^2$. Rudelson, Vershynin
- All of the above true for **any matrix** A.

Pre-conditioned length squared sampling

- A is $n \times m$, $m \ge n$. W is the $n \times n$ left pseudo-inverse of A: WA = an isometry on the column space of A.
- Sample columns of *A* according to length-squared probabilities from *WA*:
 - Let $p_j = (\text{length squared of col } j \text{ of } WA) / ||WA||_F^2$.
 - Repeat *s* times: Pick col. *j* of *A* with probability p_j and scale it by $1/p_j$ to form a $n \times s$ matrix *B*.
- $\forall \mathbf{v} : |\mathbf{v}^T B|^2 = (1 \pm \frac{c\sqrt{n}}{\sqrt{s}}) |\mathbf{v}^T A|^2$. Rudelson, Vershynin
- All of the above true for **any matrix** A.
- Computing p_j involves finding W. Spielman, Srivatsava For node-edge adjacency matrix of a graph, can be done in linear time.
- Open question: Are there other class of interesting matrices for which p_j can be computed fast?

Rudelson-Vershynin theorem can be used to assert: O*(rank (A)) samples suffice.

- Rudelson-Vershynin theorem can be used to assert: O*(rank (A)) samples suffice.
- Can we save on rank (A)? Yes. First if we do SVD to find A_k, the best rank k approximation to A and then use pre-conditioned length squared probabilities of A_k, we can do with O^{*}(k) samples.

- Rudelson-Vershynin theorem can be used to assert: O*(rank (A)) samples suffice.
- Can we save on rank (A)? Yes. First if we do SVD to find A_k, the best rank k approximation to A and then use pre-conditioned length squared probabilities of A_k, we can do with O^{*}(k) samples.
- Drineas, Mahoney and Muthukrishnan: Theorem With $poly(k/\varepsilon)$ sample columns of *A* drawn according to pre-conditioned length squared probabilities on A_k , we can get an **interpolative** approximation *A'* to *A* with the following **relative error**:

- Rudelson-Vershynin theorem can be used to assert: O*(rank (A)) samples suffice.
- Can we save on rank (A)? Yes. First if we do SVD to find A_k, the best rank k approximation to A and then use pre-conditioned length squared probabilities of A_k, we can do with O^{*}(k) samples.
- Drineas, Mahoney and Muthukrishnan: Theorem With $poly(k/\varepsilon)$ sample columns of *A* drawn according to pre-conditioned length squared probabilities on A_k , we can get an **interpolative** approximation *A'* to *A* with the following **relative error**:
- $||A A'||_F \leq (1 + \varepsilon)||A A_k||_F$.

- Rudelson-Vershynin theorem can be used to assert: O*(rank (A)) samples suffice.
- Can we save on rank (A)? Yes. First if we do SVD to find A_k, the best rank k approximation to A and then use pre-conditioned length squared probabilities of A_k, we can do with O^{*}(k) samples.
- Drineas, Mahoney and Muthukrishnan: Theorem With poly(k/ε) sample columns of A drawn according to pre-conditioned length squared probabilities on A_k, we can get an interpolative approximation A' to A with the following relative error:
- $||A A'||_F \leq (1 + \varepsilon)||A A_k||_F$.
- An alternative way to get the same theorem: Draw a sample of r =poly(k/ε) sample columns of A with probabilities proportional to the square of the volume of the simplex spanned by them.
 Deshpande, Rademacher and Vempala Volume Sampling,
 Determinental process



• A is $n_1 \times n_2 \times n_3 \dots n_r$ symmetric.

- *A* is $n_1 \times n_2 \times n_3 \dots n_r$ symmetric.
- Want to maximize $\sum_{i,j,k,\dots} A_{ijk\dots} x_i x_j x_k \dots$ over unit length vector *x*.

- A is $n_1 \times n_2 \times n_3 \dots n_r$ symmetric.
- Want to maximize $\sum_{i,j,k,\dots} A_{ijk\dots} x_i x_j x_k \dots$ over unit length vector *x*.
- Theorem For any fixed ε > 0, can find in polynomial time a y satisfying:

- *A* is $n_1 \times n_2 \times n_3 \dots n_r$ symmetric.
- Want to maximize $\sum_{i,j,k,\dots} A_{ijk\dots} x_i x_j x_k \dots$ over unit length vector *x*.
- Theorem For any fixed ε > 0, can find in polynomial time a y satisfying:
 - $\sum_{i,j,k,\ldots} A_{ijk\ldots} y_i y_j y_k \ldots \ge MAX \text{ Possible } -\varepsilon ||A||_F.$

- A is $n_1 \times n_2 \times n_3 \dots n_r$ symmetric.
- Want to maximize $\sum_{i,j,k,\dots} A_{ijk\dots} x_i x_j x_k \dots$ over unit length vector *x*.
- Theorem For any fixed ε > 0, can find in polynomial time a y satisfying:
 - $\sum_{i,j,k,\ldots} A_{ijk\ldots} y_i y_j y_k \ldots \ge MAX \text{ Possible } -\varepsilon ||A||_F.$
 - Algorithm involves length squared sampling. Kannan, Vempala

- *A* is $n_1 \times n_2 \times n_3 \dots n_r$ symmetric.
- Want to maximize $\sum_{i,j,k,\dots} A_{ijk\dots} x_i x_j x_k \dots$ over unit length vector *x*.
- Theorem For any fixed ε > 0, can find in polynomial time a y satisfying:
 - $\sum_{i,j,k,\ldots} A_{ijk\ldots} y_i y_j y_k \ldots \ge MAX \text{ Possible } -\varepsilon ||A||_F.$
 - Algorithm involves length squared sampling. Kannan, Vempala
- Better results known under assumptions on the tensor known used: (for eg. orthogonal rank 1 decomposition) - Anandkumar, Foster, Hsu, Kakade, Liu

 "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>> n

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>> n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\epsilon)$. [Indep. of *m*.]

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>>n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\varepsilon)$. [Indep. of *m*.]
 - Whp, **SIMULTANEOUSLY FOR ALL** $x \in \mathbb{R}^n$, $|SAx| = (1 \pm \varepsilon)|Ax|$.

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>> n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\varepsilon)$. [Indep. of *m*.]
 - Whp, **SIMULTANEOUSLY FOR ALL** $x \in \mathbb{R}^n$, $|SAx| = (1 \pm \varepsilon)|Ax|$.
 - SA can be computed in linear time. Then LRA just on SA suffices.

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>> n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\varepsilon)$. [Indep. of *m*.]
 - Whp, **SIMULTANEOUSLY FOR ALL** $x \in \mathbb{R}^n$, $|SAx| = (1 \pm \varepsilon)|Ax|$.
 - SA can be computed in linear time. Then LRA just on SA suffices.

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>>n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\varepsilon)$. [Indep. of *m*.]
 - Whp, **SIMULTANEOUSLY FOR ALL** $x \in \mathbb{R}^n$, $|SAx| = (1 \pm \varepsilon)|Ax|$.
 - SA can be computed in linear time. Then LRA just on SA suffices.
- Clarkson, Woodruff: Low rank approximation, Regression, Matrix Multiplication,... Optimal algorithms (time linear in number of non-zeros).

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>>n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\varepsilon)$. [Indep. of *m*.]
 - Whp, **SIMULTANEOUSLY FOR ALL** $x \in \mathbb{R}^n$, $|SAx| = (1 \pm \varepsilon)|Ax|$.
 - SA can be computed in linear time. Then LRA just on SA suffices.
- Clarkson, Woodruff: Low rank approximation, Regression, Matrix Multiplication,... Optimal algorithms (time linear in number of non-zeros).
- Clarkson, Woodruff, STOC 2009 Space optimal Streaming algorithms.

- "Count-Sketch" Matrix: Has a single non-zero entry in each column which is ±1 with prob. 1/2 each, in a random row. Dasgupta, Kumar, Sarlos
- Clarkson, Woodruff, STOC(2013) Best Paper: A ANY m×n matrix. m>>n
 - *S* a $t \times m$ count-sketch matrix with $t = poly(n/\varepsilon)$. [Indep. of *m*.]
 - Whp, **SIMULTANEOUSLY FOR ALL** $x \in \mathbb{R}^n$, $|SAx| = (1 \pm \varepsilon)|Ax|$.
 - SA can be computed in linear time. Then LRA just on SA suffices.
- Clarkson, Woodruff: Low rank approximation, Regression, Matrix Multiplication,... Optimal algorithms (time linear in number of non-zeros).
- Clarkson, Woodruff, STOC 2009 Space optimal Streaming algorithms.
- Bourtsides, Woodruff, 2015 Optimal CUR.

Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.

- Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]

- Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]
- In many contexts, it is enough to compute with a random projection of A, i.e., with PA where, P is a s × m random matrix.

- Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]
- In many contexts, it is enough to compute with a random projection of A, i.e., with PA where, P is a s × m random matrix.
- Server *i* can find *PA*^(*i*) locally and communicate this *s* × *n* matrix to a Central Processor to sum ...

- Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]
- In many contexts, it is enough to compute with a random projection of A, i.e., with PA where, P is a s × m random matrix.
- Server *i* can find *PA*^(*i*) locally and communicate this *s* × *n* matrix to a Central Processor to sum ...
- Communication is O(snr) avoiding m, EXCEPT

- Suppose r servers each has a m × n matrix with m >> n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]
- In many contexts, it is enough to compute with a random projection of A, i.e., with PA where, P is a s × m random matrix.
- Server *i* can find *PA*^(*i*) locally and communicate this *s* × *n* matrix to a Central Processor to sum ...
- Communication is *O*(*snr*) avoiding *m*, EXCEPT
 - Servers need to agree on the same *P*. Needs *O*(*smr*) communication!
- Alon, Mataias, Szegedy Use of pseudo-random numbers.

- Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]
- In many contexts, it is enough to compute with a random projection of A, i.e., with PA where, P is a s × m random matrix.
- Server *i* can find *PA*^(*i*) locally and communicate this *s* × *n* matrix to a Central Processor to sum ...
- Communication is *O*(*snr*) avoiding *m*, EXCEPT
 - Servers need to agree on the same *P*. Needs *O*(*smr*) communication!
- Alon, Mataias, Szegedy Use of pseudo-random numbers.
- Kane, Mekha, Nelson: Let *x* be a fixed vector. To get |*P*A*x*| ≈ |*Ax*|, *O*(log *n*)-way independence suffices. Need to communicate only the *O*(log *n*) bit-seed to all servers.

- Suppose r servers each has a m×n matrix with m>>n; server i has matrix A⁽ⁱ⁾.
- Want to compute with A = A⁽¹⁾ + A⁽²⁾ + ··· + A^(r). [Examples: Net-flow data, web crawl data...]
- In many contexts, it is enough to compute with a random projection of A, i.e., with PA where, P is a s × m random matrix.
- Server *i* can find *PA*^(*i*) locally and communicate this *s* × *n* matrix to a Central Processor to sum ...
- Communication is *O*(*snr*) avoiding *m*, EXCEPT
 - Servers need to agree on the same *P*. Needs *O*(*smr*) communication!
- Alon, Mataias, Szegedy Use of pseudo-random numbers.
- Kane, Mekha, Nelson: Let *x* be a fixed vector. To get |*PAx*| ≈ |*Ax*|, *O*(log *n*)-way independence suffices. Need to communicate only the *O*(log *n*) bit-seed to all servers.
- To ensure |PAx| ≈ |Ax| for all x ∈ Rⁿ, poly(n)-way independence suffices.