

INTERFERENCE QUEUING NETWORKS

Wireless Spatial Birth-Death Processes

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En l'honneur de Jean Walrand

The Next Wave in Networking Research
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Structure of the Lecture

- **Background and Motivation**
- **Wireless Birth-Death Processes**
with **A. Sankararaman**, **IEEE Tr. IT**, **63(6) 2017**
1. **Stability**, 2. **Clustering**, 3. **Quantitative results**
- **Interference Queuing Networks**
with **S. Foss & A. Sankararaman**, **arXiv 1710.09797**
1. **Stability**, 2. **Minimal solution**, 3. **Initial condition**

Motivations in Wireless Networks

- **Lack of understanding and analysis of**

 - Space-time interactions**

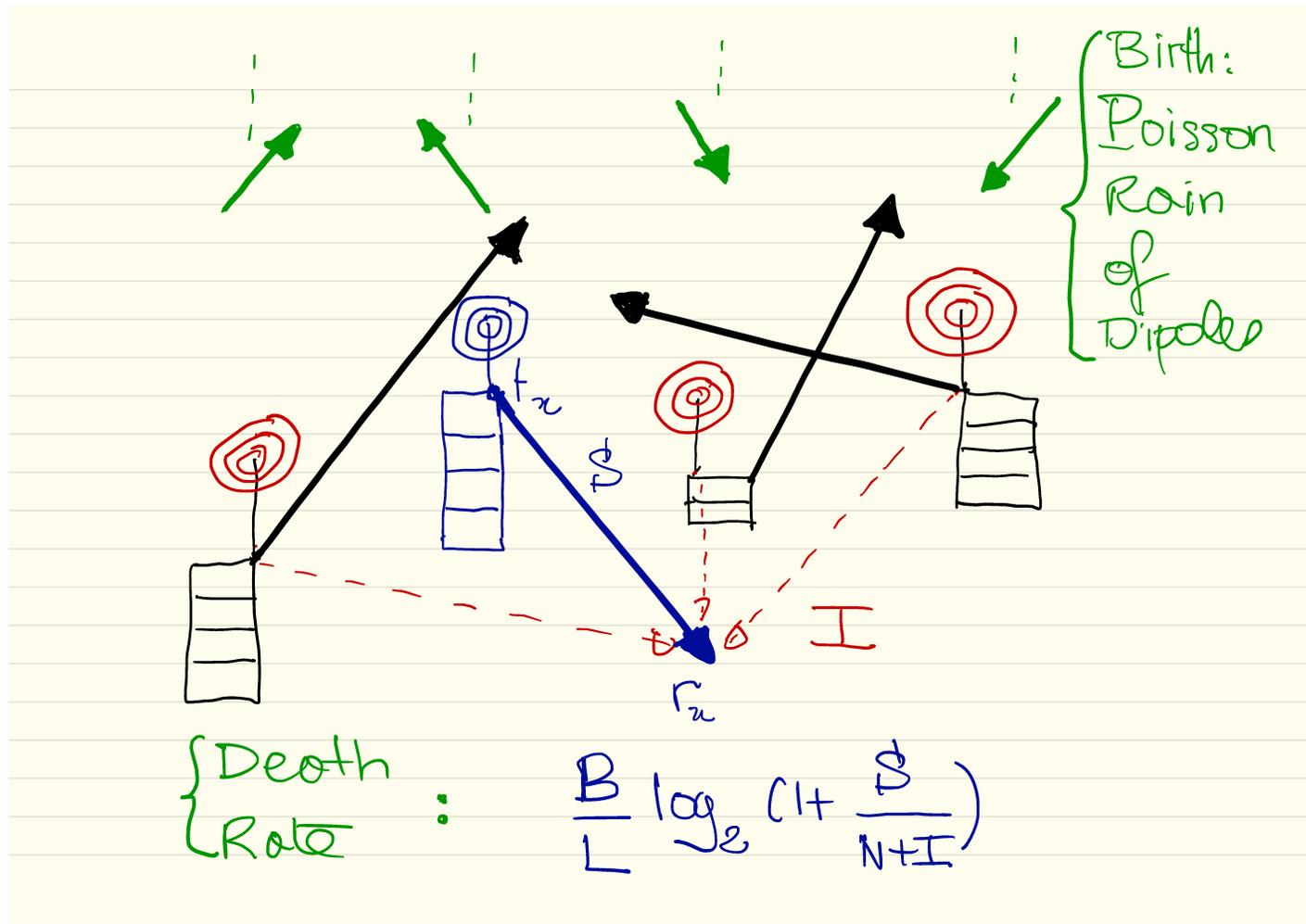
 - Static spatial setting well understood: Stochastic Geometry
[FB, Blaszczyszyn 01]
 - Churn taken into account in flow-based queuing
[Bonald, Proutiere 06], [Shakkottai, De Veciana 07]
[Jiang, Walrand 09]

- **Contents of this lecture:**

 - Models with such dynamics in stochastic geometry**

I. Wireless Birth-Death Processes

- **Setting: Infrastructureless Wireless Network:**
Ad-hoc Networks, D2D Networks, IoT
- **Statistical assumptions: Markov Models:**
Poisson, Exponential
- **Mathematical tools:**
Point processes, Fluid



Stochastic Network Model

- $S = [-Q, Q] \times [-Q, Q]$: torus where the wireless links live
- **Links**: (Tx-Rx pairs)
- **Links**: **arrive** as a PPP on $\mathbb{R} \times S$ with intensity λ :
 Prob. of a point arriving in space dx and time dt : $\lambda dx dt$
- Each Tx has an **i.i.d. exponential file size**
 of mean **L** bits to transmit to its Rx
- A point **exits** after the Tx finishes transmitting its file
- Φ_t : set of locations of links present at time t :

$$\Phi_t = \{\mathbf{x}_1, \dots, \mathbf{x}_{N_t}\}, \quad \mathbf{x}_i \in S$$

Interference and Service Rate

- Interference seen at point x due to configuration Φ

$$I(\mathbf{x}, \Phi) = \sum_{\mathbf{x}_i \in \Phi \neq \mathbf{x}} l(\|\mathbf{x} - \mathbf{x}_i\|)$$

- Distance on the torus
- $l(\cdot): \mathbb{R}^+ \rightarrow \mathbb{R}^+$: path loss function

- The speed of file transfer by link at \mathbf{x} in configuration Φ is

$$R(\mathbf{x}, \Phi) = B \log_2 \left(1 + \frac{1}{N + I(\mathbf{x}, \Phi)} \right)$$

- B, N Positive constants

B& D Master Equation

- A point born at \mathbf{x}_p and time b_p with file-size L_p dies at time

$$d_p = \inf \left\{ t > b_p : \int_{u=b_p}^t \mathbf{R}(\mathbf{x}_p, \Phi_u) du \geq L_p \right\}$$

- **Spatial Birth-Death Process**

- Arrivals from the Poisson Rain
- Departures happen at file transfer completion

Properties of the Dynamics

- The statistical assumptions imply that Φ_t is a Markov Process on the set of simple counting measures on \mathbf{S}
- **Euclidean extension** of the flow-level models of [Bonald, Proutiere 06], [Shakkottai, De Veciana 07]

Questions

- **Existence and uniqueness** of the stationary regimes of Φ_t
- **Characterization** of the stationary regime(s) if existence

Main Stability Results

$$a := \int_{x \in S} l(\|x\|) dx$$

■ Theorem

- If $\lambda > \frac{B}{\ln(2)La}$, then Φ_t admits no stationary regime.
- If $\lambda < \frac{B}{\ln(2)La}$, and $r \rightarrow l(r)$ bounded and monotone, then Φ_t admits a unique stationary regime

■ Necessary condition by **Palm calculus, Stochastic intensity**

■ Sufficient condition by **fluid limit**

■ Corollary

For the path-loss model $l(r) = r^{-\alpha}$, $\alpha \geq 2$, for all $\lambda > 0$, and all mean file sizes, the process Φ_t admits no stationary-regime

Main Qualitative Result

- Φ stationary point-process on S with Palm distribution \mathbb{P}^0
- **Clustering**
 Φ is clustered if for all bounded, positive, non-increasing functions $f(\cdot) : \mathbb{R}^+ \rightarrow \mathbb{R}^+$, the shot-noise

$$\mathbf{F}(\mathbf{x}, \Phi) := \sum_{\mathbf{y} \in \Phi \setminus \{\mathbf{x}\}} f(\|\mathbf{y} - \mathbf{x}\|)$$

satisfies

$$\mathbb{E}^0[\mathbf{F}(\mathbf{0}, \Phi)] \geq \mathbb{E}[\mathbf{F}(\mathbf{0}, \Phi)]$$

Main Qualitative Result (*continued*)

■ **Theorem**

The steady-state point process, when it exists, is **clustered**

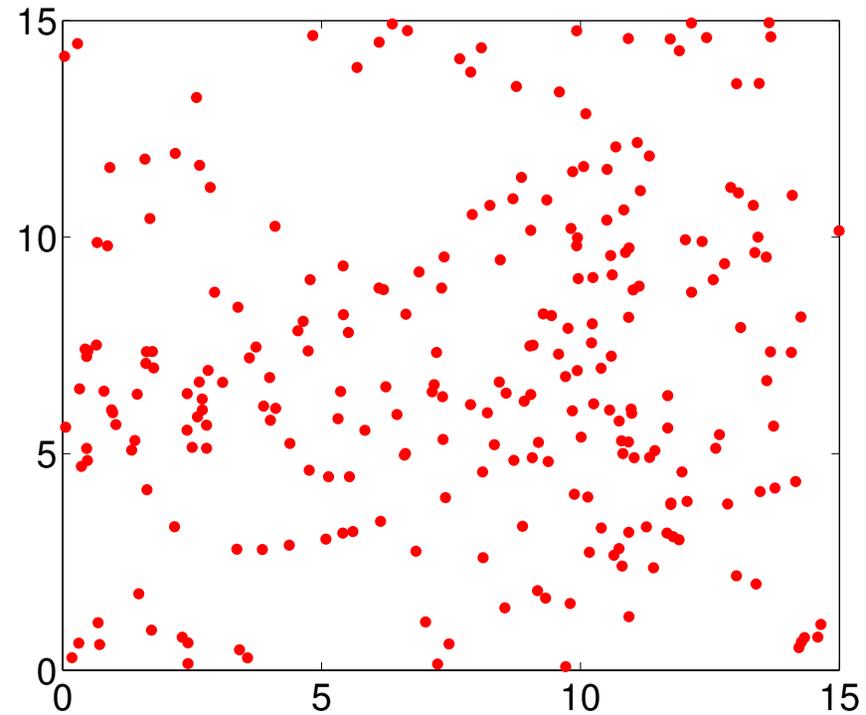
■ Follows from **Palm calculus + the FKG inequality**

■ **Interpretation of the result**

The steady-state interference measured at a uniformly randomly chosen point of is larger in mean than that at a uniformly random location of space.

■ **Key Observation**

- Dynamics Shapes Geometry
- Geometry Shapes Dynamics



A sample of Φ when $\lambda = 0.99$ and $l(\mathbf{r}) = (\mathbf{r} + \mathbf{1})^{-4}$.

Quantitative Results

- Heuristics for the intensity of the steady-state process
 1. Poisson heuristic β_f - derived by neglecting clustering and assuming Poisson
 2. Second-order heuristic β_s based on a second-order cavity approximation of the dynamics

Poisson Heuristic

■ Exact **Rate Conservation Law**:

$$\lambda \mathbf{L} = \beta \mathbb{E}_{\Phi}^0 \left[\log_2 \left(\mathbf{1} + \frac{\mathbf{1}}{\mathbf{N} + \mathbf{I}(\mathbf{0})} \right) \right].$$

Poisson Heur.: Largest solution to the fixed point equation:

$$\lambda \mathbf{L} = \frac{\beta_f}{\ln(2)} \int_{z=0}^{\infty} \frac{e^{-\mathbf{N}z} (1 - e^{-z})}{z} e^{-\beta_f \int_{\mathbf{x} \in \mathbf{S}} (1 - e^{-z\|\mathbf{x}\|}) d\mathbf{x}} d\mathbf{z}$$

Ignores the Palm effect and uses that if \mathbf{X}, \mathbf{Y} are non-negative and independent,

$$\mathbb{E} \left[\ln \left(\mathbf{1} + \frac{\mathbf{X}}{\mathbf{Y} + \mathbf{a}} \right) \right] = \int_{z=0}^{\infty} \frac{e^{-az}}{z} (1 - \mathbb{E}[e^{-z\mathbf{X}}]) \mathbb{E}[e^{-z\mathbf{Y}}] dz.$$

■ The **Poisson heuristic** is **tight** in heavy and light traffic

Second Order Heuristic

The intensity β_s is given by

$$\beta_s = \frac{\lambda L}{\mathbf{B} \log_2 \left(1 + \frac{1}{\mathbf{N} + \mathbf{I}_s} \right)}$$

where \mathbf{I}_s is the smallest solution of the fixed-point equation

$$\mathbf{I}_s = \lambda L \int_{\mathbf{x} \in \mathbf{S}} \frac{\mathbf{I}(\|\mathbf{x}\|)}{\mathbf{B} \log_2 \left(1 + \frac{1}{\mathbf{N} + \mathbf{I}_s + \mathbf{I}(\|\mathbf{x}\|)} \right)} d\mathbf{x}$$

Second Order Heuristic (continued)

- **Rationale** based on $\rho_2(\mathbf{x}, \mathbf{y})$: second moment measure of Φ
- **Rate Conservation for ρ_2** : when considering \mathbf{I}_s as a constant

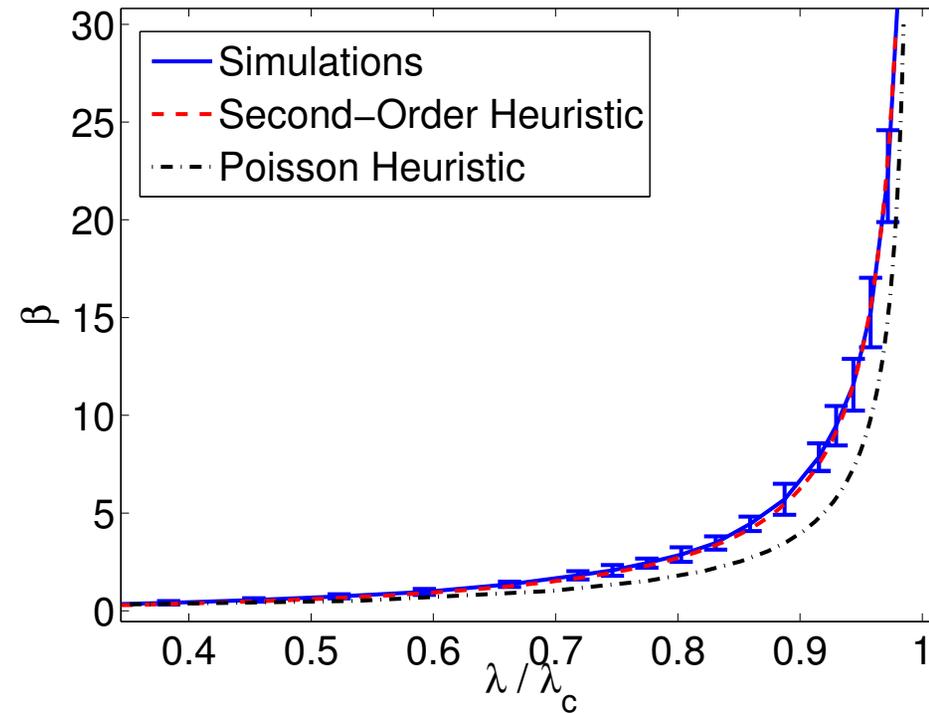
$$\rho_2(\mathbf{x}, \mathbf{y}) \frac{1}{L} \mathbf{B} \log_2 \left(1 + \frac{1}{\mathbf{N} + \mathbf{I}_s + \mathbf{l}(\|\mathbf{x} - \mathbf{y}\|)} \right) = \lambda \beta_s$$

- From the definition of second moment measure,

$$\mathbf{I}_s = \int_{\mathbf{x} \in \mathbf{S}} \mathbf{l}(\|\mathbf{x}\|) \frac{\rho_2(\mathbf{0}, \mathbf{x})}{\beta_s} d\mathbf{x}$$

which gives the fixed point equation for \mathbf{I}_s

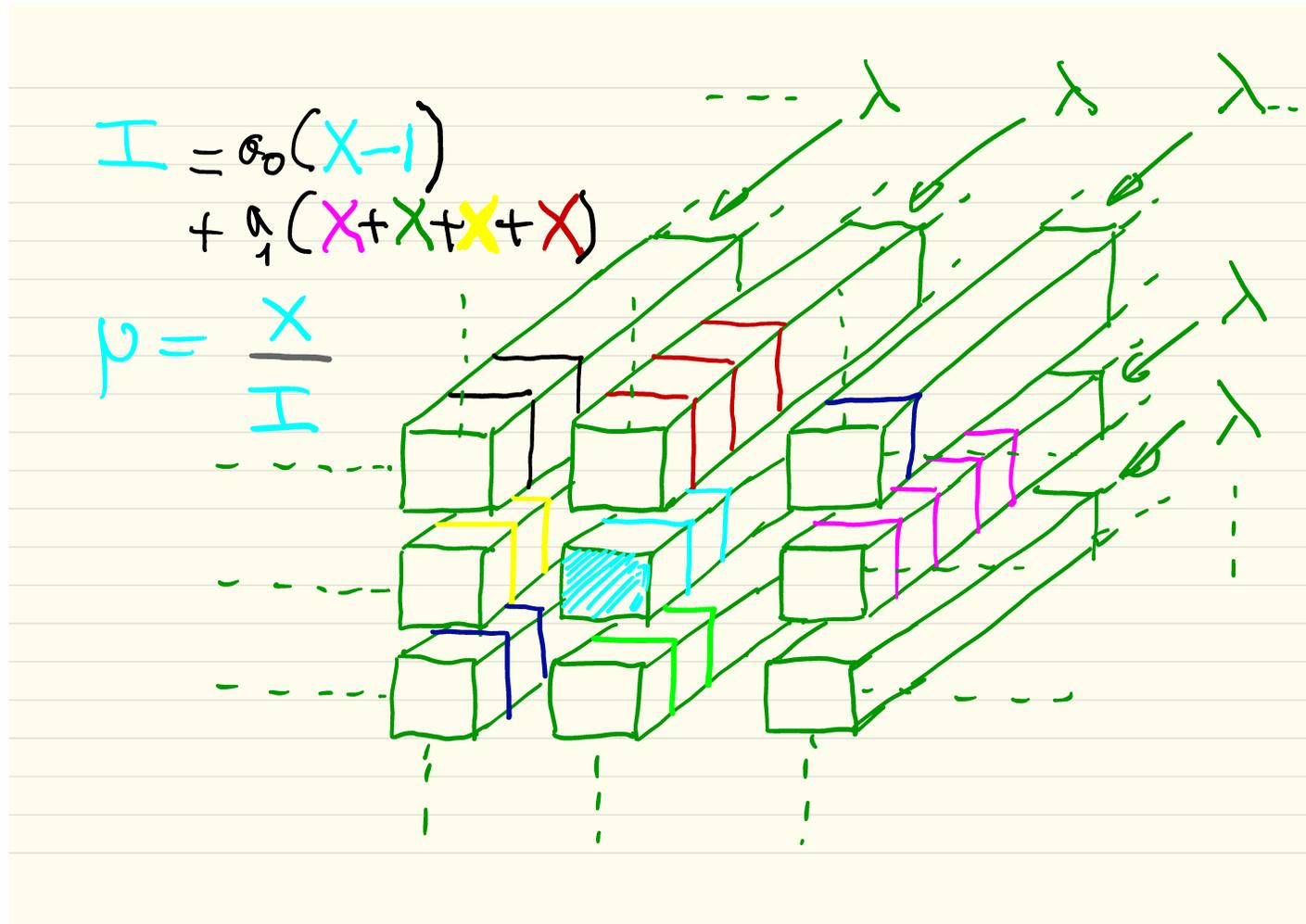
- The formula for β_s follows from **Rate Conservation for $\rho_1 = \beta_s$**



95% confidence interval when $l(r) = (r + 1)^{-4}$

II. Interference Queuing Networks

- **Aim:** extension of dynamics to \mathbb{R}^2 (scalability)
- **Setting**
 - **Discretization:** queuing dynamics on a grid
 - **Low SINR:** linearization of the log
- **Mathematical Tools**
 - Interacting particle systems
 - Coupling from the past
 - Rate conservation principle



Assumptions, Notation

- Queue i at $i \in \mathbb{Z}^d$ has state $\mathbf{x}_i(\mathbf{t}) \in \mathbb{N}$ at time t
- Arrivals to queues:
i.i.d. **Poisson processes of rate $\lambda > 0$**
- Interference sequence:
 $\{\mathbf{a}_i\}_{i \in \mathbb{Z}^d}$, non-negative, symmetric ($\mathbf{a}_i = \mathbf{a}_{-i}$), and irreducible
- Service discipline:
generalized processor-sharing with rate of queue i at time t :

$$\frac{\mathbf{x}_i(\mathbf{t})}{\sum_{j \in \mathbb{Z}^d} \mathbf{a}_j \mathbf{x}_{i-j}(\mathbf{t})}$$

Stability, Minimal Stationary Regime

- **Stability:** when starting the system empty at time 0, weak convergence of the state of any finite set of queues as $t \rightarrow \infty$

- **Theorem** If

$$\lambda < \frac{1}{\sum_{i \in \mathbb{Z}^d} a_i}$$

- The network is **stable**
- The weak limit is the **minimal stationary regime**

- **Proof:** CFP

- The stability condition $\lambda < \frac{1}{\sum_{i \in \mathbb{Z}^d} a_i}$ is **sharp** (current proof in special cases only)

Quantitative Properties of Minimal Stationary Regime

- **Theorem** The weak limit, when it exists, satisfies

$$\mathbb{E}[\mathbf{x}_0] = \frac{\lambda \mathbf{a}_0}{1 - \lambda \sum_{i \in \mathbb{Z}^d} \mathbf{a}_i}$$

In addition its coordinates $(\mathbf{x}_i)_{i \in \mathbb{Z}^d}$ are **associated**

- **Proof:** RCP
- **Association:** analogue of of clustering in the continuum
- **Remarkable fact:** **closed form for the mean** for this infinite-dimensional, non-reversible, non-asymptotically independent particle system

Uniqueness

- Below, assume that $\lambda < \frac{1}{\sum_{i \in \mathbb{Z}^d} a_i}$
- **Proposition** If $\mathbb{E}[x_0^2] < \infty$, then the minimal solution is the **unique** stationary solution with finite second moment
- **Proposition** If

$$\lambda < \frac{2}{3} \frac{1 + c}{\sum_{j \in \mathbb{Z}^d} a_j} \quad \text{where} \quad c = \frac{\sqrt{a_0^2 + a_0 \sum_{j \in \mathbb{Z}^d \setminus \{0\}} a_j} - a_0}{\sum_{j \in \mathbb{Z}^d \setminus \{0\}} a_j}$$

then $\mathbb{E}[x_0^2] < \infty$

Domain of Attraction of the Minimal Solution

- **Theorem** If $\lambda < \frac{2}{3} \frac{1+c}{\sum_{j \in \mathbb{Z}^d} a_j}$ and the initial condition satisfies

$$\sup_{i \in \mathbb{Z}^d} \mathbf{x}_i(\mathbf{0}) < \infty$$

then $\{\mathbf{x}_i(\cdot)\}_{i \in \mathbb{Z}^d}$ **converges weakly to the minimal stationary solution**

- **Theorem** For $d = 1$, for all $\lambda > 0$, there exists

1. A deterministic sequence $(\alpha_i)_{i \in \mathbb{Z}}$ such that if $\mathbf{x}_i(\mathbf{0}) \geq \alpha_i$ for all $i \in \mathbb{Z}$, then $\lim_{t \rightarrow \infty} \mathbf{x}_0(t) = \infty$ a.s.
2. A distribution ξ on \mathbb{N} s.t. if $\{\mathbf{x}_i(\mathbf{0})\}_{i \in \mathbb{Z}}$ is i.i.d. with marginal distr. ξ , then $\lim_{t \rightarrow \infty} \mathbf{x}_0(t) = \infty$ a.s.

Summary

- A new basic representation of **space-time interactions** in wireless networks
- A **generative model for clustering** as assumed in simulation standards
- A new **dynamic notion of capacity** involving both queuing and IT
- **First exact analytical results** in the low SINR case and good **heuristics** in general
- A new **particle system dynamics** with closed form although no reversibility, no asymptotic independence

Thanks Jean

**MERCI JEAN POUR NOS PREMIERS ~ 40 ANS
D'INTERACTIONS AMICALES ET
SCIENTIFIQUES!**