Lower Bounds for Tractable Arithmetic Circuits

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The talk is **not** intended to be an exhaustive list of all lower bounds techniques for ACs. I will mostly cover results from [dC and Mengel, 2021].

- Tractable arithmetic circuits (AC)
- Reduction to tractable Boolean circuits (the boring trick)
- Lower bounds via the rank technique
- Separating classes of tractable ACs

Arithmetic Circuits

An arithmetic circuit (AC) is a computational directed acyclic graph s.t.

- it has a single sink (the output gate)
- its sources correspond to Boolean 0/1 literals (the input gates)
- its internal nodes correspond to \times or + operations (\times -gates and +-gates)
- the input connectors of its +-gates are weighted by rational numbers



These circuits have been given different names: $(+, \times)$ -programs [Valiant, 1980], AC [Nisan and Wigderson, 1997; Darwiche 2002], sum-product networks [Poon and Domingos, 2011; Dennis 2016], etc.

In this talk, all ACs represent non-negative functions. Though we allow negative weights on the edges.

An AC is called monotone if it only uses non-negative weights.

It is known that allowing negative weights (\simeq allowing subtraction) can result in a more-than-polynomial decrease in the size of the AC [Valiant, 1980]. So we aim for lower bounds on the size of AC representing non-negative functions but where negative weights are allowed.

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- Determinism: every +-gate w₁C₁ + w₂C₂ verifies that ∀X, C₁(X) · C₂(X) = 0 (i.e., C₁ and C₂ have disjoint supports)
- Smoothness: every +-gate $C_1 + C_2$ verifies $var(C_1) = var(C_2)$



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- there would be a node in T that separates $\{X_1\}$ from $\{X_3, X_4\}$,
- and there would be a node in T that separates $\{X_1, X_4\}$ from $\{X_3\}$,

this is not possible.

Roadmap

• Tractable arithmetic circuits (AC)

• Reduction to tractable Boolean circuits (the boring trick)

• Lower bounds via the rank technique

Reduction to Tractable Boolean Circuits – the Boring Trick

There is a trivial poly-time transformation from a tractable AC that uses only positive weights to a tractable Boolean circuit.



Thus, if the support of a function f coincides with the true points of a Boolean function that admits only exponential size DNNF circuits, then f admits only exponential size decomposable AC that use only positive weights.

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Reduction to Tractable Boolean Circuits - the Boring Trick

This works only for AC with positive weights.

Note that when the AC is deterministic, the weights can always be taken positive with no impact on the size of the AC.



Also, for deterministic decomposable AC with integer weights, there is a poly-time transformation to a d-DNNF circuit computing $\mathbb{1}[C(X) \ge k]$ for any constant k (not just 0) while this is generally intractable for decomposable AC.

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• Lower bounds via the rank technique

The rank technique allows one to prove lower bounds on the size of structured-decomposable AC (possibly using negative weights) for a function F.

We use the notion of value matrix for a function F.

Definition (Value Matrix)

Let $F(\mathbf{X})$ be a function and $\Pi = (\mathbf{A}, \mathbf{B})$ be a partition of \mathbf{X} . A value matrix $M_{\Pi}(F)$ is a $2^{|\mathbf{B}|} \times 2^{|\mathbf{A}|}$ matrix whose columns are indexed by the complete assignments to \mathbf{A} , whose rows are indexed by the complete assignments to \mathbf{B} and such that the entry at column $\vec{X}_{\mathbf{A}}$ and row $\vec{X}_{\mathbf{B}}$ is $F(\vec{X}_{\mathbf{A}}, \vec{X}_{\mathbf{B}})$.

Example: $F(X_1, X_2, X_3, X_4, X_5) = \frac{1}{2}(X_1 + X_5)(X_2 + 3X_4) + X_2X_3$ and $\Pi = (X_1X_2X_3, X_4X_5)$. A value matrix $M_{\Pi}(F)$ is

	$\begin{array}{c} X_1 \\ X_2 \\ X_3 \end{array}$	$\begin{array}{c} 0\\ 0\\ 0\\ 0 \end{array}$	$\begin{array}{c} 1 \\ 0 \\ 0 \end{array}$	$\begin{array}{c} 0 \\ 1 \\ 0 \end{array}$	$\begin{array}{c} 0 \\ 0 \\ 1 \end{array}$	$\begin{array}{c} 0 \\ 1 \\ 1 \end{array}$	$\begin{array}{c} 1 \\ 0 \\ 1 \end{array}$	$\begin{array}{c} 1 \\ 1 \\ 0 \end{array}$	$\begin{array}{c} 1 \\ 1 \\ 1 \end{array}$	
X_4X_5	/									`
0 0		0	0	1	0	$\frac{3}{2}$	0	$\frac{3}{2}$	$\frac{1}{2}$	
1 0		0	$\frac{1}{2}$	1	0	3	$\frac{3}{2}$	3	2	
0 1		0	0	$\frac{3}{2}$	0	2	0	2	1	
1 1		$\frac{3}{2}$	3	3	$\frac{3}{2}$	5	3	5	4	

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Theorem

Let T be a vtree and let $\Pi = (A, B)$ of X be a partition induced by T. Every structured-decomposable AC respecting T and representing F(X) contains at least rank $(M_{\Pi}(F))$ gates.



Corollary

Every structured-decomposable AC representing $F(\mathbf{X})$ contains at least

 $\min_\Pi \operatorname{\mathsf{rank}}(M_\Pi(F))$

gates where Π ranges over all **balanced** partitions (i.e., $\frac{|\mathbf{X}|}{3} \leq |\mathbf{A}|, |\mathbf{B}| \leq \frac{2|\mathbf{X}|}{3}$).

Example of "hard" functions: consider a simple graphs G and let

$$F_G(\boldsymbol{X}) = \prod_{(i,j)\in E(G)} (1 + \max(X_i, X_j)).$$

Note that F_G never takes value 0.

Theorem

If G is a (c,d)-expander graph with d = O(1), then for all balanced partitions Π of X,

$$\mathsf{rank}(M_{\Pi}(F_G(oldsymbol{X}))) \geq 2^{\Omega(n)}$$

where $n = |\mathbf{X}|$.

Corollary

There exists an infinite class of (c,3)-expander graphs for some constant c, so there exists an infinite class of functions $F_G(\mathbf{X})$ computed only by structured-decomposable AC of size $2^{\Omega(n)}$, where $n = |\mathbf{X}|$.

The proof of the rank theorem uses a decomposition of the AC as sum of "arithmetic rectangles" (for lack of better term)

str.-dec.
AC C
$$circuit = C \equiv \sum_{i=1}^{k} f_i(A) \cdot g_i(B), \quad M_{\Pi}(P_i) = k \geq i \text{ rank}(M_{\Pi}(C))$$

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This is similar to the lower bound techniques for DNNF circuits using combinatorial rectangles.

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Showing a separation between two classes of tractable AC = finding an infinite class of functions that admit polynomial-size representations in one class but only super-polynomial-size representations in the other.

Building on the previous result, we can show the separation between the class of decomposable ACs and that of structured-decomposable ACs.

Theorem (dec. AC exponentially separated from str-dec. ACs)

There is an infinite class of functions that have small decomposable ACs but only exponential-size structured-decomposable ACs.

We just need the following results...

Lemma (Conditioning str-dec. ACs)

Conditioning is done in linear-time on str-dec. AC and preserve structured-decomposability.

$$C(\mathbf{X}) \xrightarrow{\text{linear-time}} C'(\mathbf{X} \setminus var(\alpha)) \equiv C(\mathbf{X})|\alpha$$

where α is a partial assignment to $oldsymbol{X}$.

Lemma (Conjunction of str-dec. ACs)

Taking the product of two str-dec. AC while preserving structured-decomposability is tractable when they respect the same vtree.

$$C_1(\mathbf{X}), C_2(\mathbf{X}) \xrightarrow[quadratic-time]{} C(\mathbf{X}) \equiv C_1(\mathbf{X}) \cdot C_2(\mathbf{X})$$

[Vergari, Choi, Liu, Teso and Van den Broeck, 2021]

...and some knowledge about expander graphs.



Lemma

When G_2 is chosen uniformly at random, $G_1 \oplus G_2$ is an expander graph with high probability.

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- 3. So for every vtree T, $F_{G'_1}(X)$ or $F_{G_2}(X)$ admits only exponential-size structured-decomposable ACs respecting T.

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- 5. Let y be a fresh variable, then $F(X, y) := (y \cdot F_{G'_1}(X)) + (\neg y \cdot F_{G_2}(X))$ has small decomposable AC.
- 6. If F had a small structured-decomposable AC respecting some T then F|(y=1) and F|(y=0) would both have small structured-decomposable AC respecting T, which is not possible due to 3.

So this proves the separation of structured-decomposable ACs and decomposable ACs.

Theorem (dec. AC exponentially separated from str-dec. ACs)

There is an infinite class of functions that have small decomposable ACs but only exponential-size structured-decomposable ACs.

Again, we have made no assumption on the sign of the weights used in our ACs.

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Thank you