

Localization schemes

Simons Institute - Beyond the Boolean Cube Workshop

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1. Spectral independence via **coordinate-by-coordinate localization**
2. Glauber dynamics mixing in Ising model via **Eldan's stochastic localization**
3. Glauber dynamics mixing in hardcore model via **negative fields localization**

Setup: sampling from a target measure

Given a target measure μ (possibly unnormalized), on a state space $\mathcal{X} = \{-1, +1\}^n$ or \mathbb{R}^n , we want to **draw samples** $X \sim \mu$.

Glauber dynamics for sampling μ on $\{-1, +1\}^n$

At current state $x \in \{-1, +1\}^n$, draw index i uniformly from $[n]$

- move to $y = x \oplus e_i$ with probability $\frac{\mu(y)}{\mu(y) + \mu(x)}$
- otherwise, stay at x

Denote this transition kernel $P_{x \rightarrow y}$.

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Mixing time: starting from initial measure μ_{ini} , let $\mu_{\text{ini}} P^k$ denote the measure at time, how many iterations does it take so that

$$\text{TV}(\mu, \mu_{\text{ini}} P^k) \leq \epsilon?$$

Mixing time analysis via functional inequalities (1)

Define the Dirichlet form

$$\mathcal{E}_P(f, g) = \langle (I - P)f, g \rangle_\mu$$

Poincaré inequality (or spectral gap)

$$\lambda \operatorname{Var}_\mu(f) \leq \mathcal{E}_P(f, f), \quad \forall f$$

For reversible lazy Markov chain, it implies variance decay:

$$\operatorname{Var}_\mu Pf \leq (1 - \lambda) \operatorname{Var}_\mu f, \quad \forall f$$

Take $f = \frac{\mu_{\text{ini}} P^k}{\mu}$, we can bound chi-squared divergence decay, leading to mixing time

$$\frac{1}{\lambda} \left(\log \frac{1}{\mu_{\text{ini}, \min}} + \log \frac{1}{\epsilon} \right)$$

Modified Log-Sobolev inequality (MLSI)

$$\rho_{\text{MLSI}} \text{Ent}_{\mu}(f) \leq \mathcal{E}_P(f, \log f), \quad \forall f \geq 0$$

We can bound KL-divergence decay, leading to mixing time

$$\frac{1}{\rho_{\text{MLSI}}} \left(\log \log \frac{1}{\mu_{\text{ini}, \min}} + \log \frac{1}{\epsilon} \right)$$

From now on, we focus on functional inequalities

- Target measure μ
- $2^n \times 2^n$ Markov transition kernel P
- To prove mixing time, it suffice to prove

$$\lambda \operatorname{Var}_\mu(f) \leq \mathcal{E}_P(f, f)$$

For product measure, it is easy.

Other than that, for what kind of target measure, can we prove spectral gap?

Coordinate-by-coordinate localization

Define the $n \times n$ pairwise influence matrix Ψ_μ

$$\Psi_\mu[i, j] = \mathbb{P}_{x \sim \mu}(x_j = +1 \mid x_i = +1) - \mathbb{P}_{x \sim \mu}(x_j = +1 \mid x_i = -1)$$

μ is η -spectrally independent if

$$\|\Psi_\mu\|_2 \leq \eta$$

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A sufficient condition for proving spectral gap: if all conditionals of μ (the law of $X \mid X_i = \pm 1$ and $X \mid X_i = \pm 1, X_j = \pm 1$, etc.) are η -spectrally independent, then spectral gap

$$\lambda \geq \prod_{i=0}^{n-2} \left(1 - \frac{\eta}{n-i}\right)$$

Spectral independence is a condition on covariance

Since

$$\text{Cov}_\mu = \text{diag}(\text{Cov}_\mu)(\Psi_\mu + \mathbb{I}_n)$$

we have

$$\text{Cov}_\mu \preceq (1 + \eta) \text{diag}(\text{Cov}_\mu) \Leftrightarrow \|\Psi_\mu + \mathbb{I}_n\|_2 \leq 1 + \eta.$$

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Constraining the covariance makes sense, but

Q1: why do we have to put assumptions on all conditionals?

...trickling down, HDX, local-to-global

Q2: what are other ways to put assumptions to prove spectral gap, when direct proof is difficult?

What are localization schemes?

A **localization scheme** is a mapping from measure ν to a stochastic process $(\nu_t)_{t \geq 0}$ such that

- $\nu_0 = \nu$
- For any measurable A , $\nu_t(A)$ is a **martingale** (in other words, $\mathbb{E}[\nu_t(A) \mid \{\nu_\tau(A), \tau \leq s\}] = \nu_s(A), \forall 0 \leq s \leq t$)

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Our main standpoint:

- You pick a localization scheme
- Study the evolution of the variance $\text{Var}_{\nu_t}(f)$ along the process $(\nu_t)_t$
- Put **assumptions to approximately conserve variance**, then you can prove spectral gap!

Spectral independence assumption comes from coordinate-by-coordinate localization

Coordinate-by-coordinate localization

Start from ν on $\{-1, +1\}^n$. Let (k_1, \dots, k_n) be a random permutation of $[n]$, and X is a random draw from ν , independent of the rest. Define

$$\nu_i = \text{law of } \{X \mid X_{k_1}, \dots, X_{k_i}\}$$

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We claim that

In [Anari, Liu, Oveis Gharan '20], η -spectrally independence for every conditional of ν is a condition to conserve variance along the coordinate-by-coordinate localization

$$\left(1 - \frac{\eta}{n-i}\right) \mathbb{E}[\text{Var}_{\nu_i}(f)] \leq \mathbb{E}[\text{Var}_{\nu_{i+1}}(f)]$$

Derivation: approximate conservation of variance

Similarly,

- Semi-log-concavity [Eldan, Shamir '20]
- Fractional log-concavity [Alimohammadi, Anari, Shiragur, Vuong '21]
- Entropic independence [Anari, Jain, Koehler, Pham, Vuong '21]

which bounds covariance of all tilted measures,
are sufficient conditions to approximately conserve **entropy**
along the **coordinate-by-coordinate** localization
so that one could prove MLSI

Beyond coordinate-by-coordinate localization?

Let's first take a tour **beyond the Boolean cube** to \mathbb{R}^n , where Eldan first introduced stochastic localization [Eldan '13]

Eldan's stochastic localization

Given an density ν on \mathbb{R}^n , the density at time t is the solution of the SDE

$$d\nu_t(x) = (x - \mathbf{b}(\nu_t))^\top C_t^{\frac{1}{2}} dW_t \cdot \nu_t(x), \quad \forall x \in \mathbb{R}^n$$

where $\mathbf{b}(\nu_t)$ is the mean of ν_t and W_t is the Brownian motion. Take $C_t = \mathbb{I}_n$ to simplify explanation.

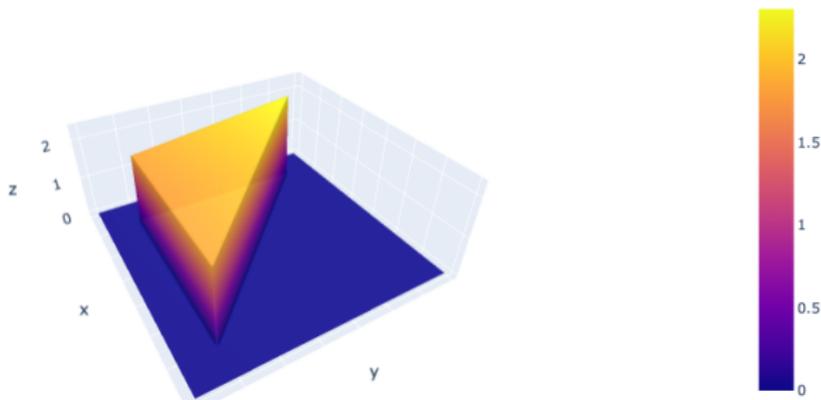
ν_t has an explicit form

$$\nu_t(x) = \frac{1}{Z(c_t, t)} \exp\left(-\frac{t}{2} |x|^2 + c_t^\top x\right) \nu(x)$$
$$dc_t = dW_t + \mathbf{b}(\nu_t)dt$$

At time t , the initial density is multiplied by a Gaussian with $1/t$ variance, while the center of the Gaussian is random.

Demonstration of Eldan's stochastic localization in 2 dimension

Initialized with uniform distribution over a convex set ($n = 2$)



Stochastic localization are used in high dimensional probability

Say we want to show a “property A” of the density ν

- **Transform** via stochastic localization
- **Prove** “property A” for ν_t (usually easier)
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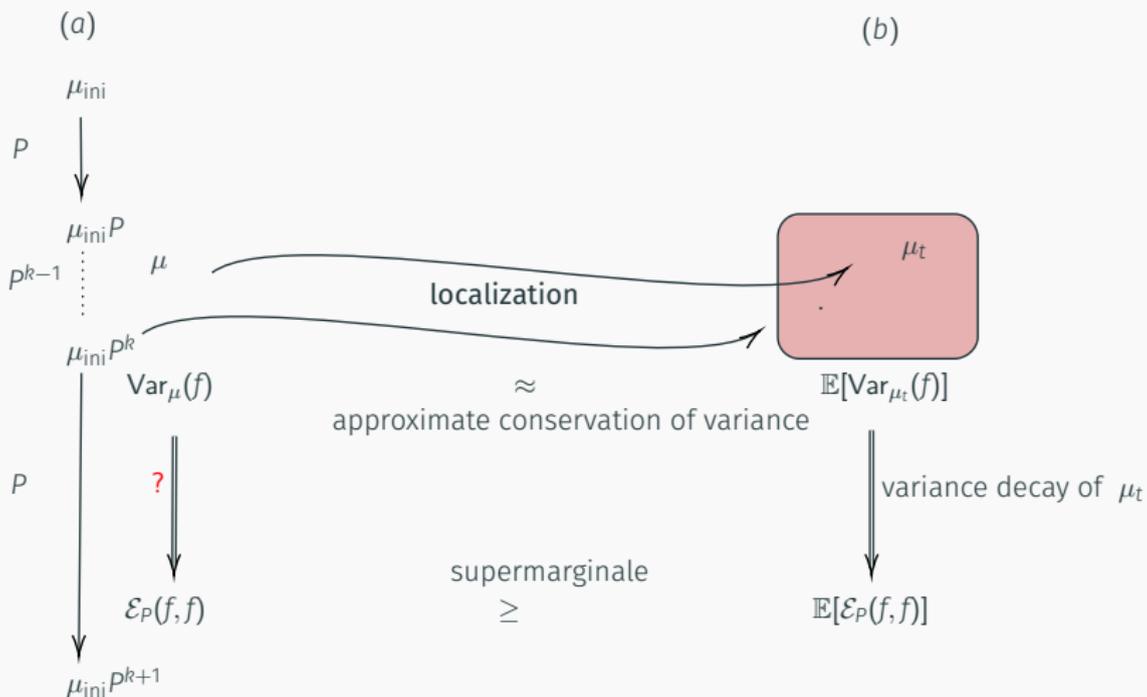
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See survey paper in 2022 ICM proceedings [Eldan], “property A” can be

- isoperimetric inequality (e.g. KLS conjecture [KLS '95])
- concentration of Lipschitz functions in Gaussian space
- noise stability inequality
- Poincaré inequality ...

1. The desired **functional inequality** is then our “property A”
2. Hopefully, this “property A” is easier to prove for the process at some time t
3. We put assumptions to make the approximate conservation of variance analysis go through

Use of localization schemes for sampling proofs



The probability measure on $\{-1, +1\}^n$ defined as

$$\mu(x) \propto \exp(\langle x, Jx \rangle + \langle h, x \rangle)$$

is called **Ising model** with interaction matrix $J \in \mathbb{R}^{n \times n}$ and external field $h \in \mathbb{R}^n$.

Theorem

Let $\nu_{\tau,v}(x) \propto \mu(x) \exp(-\tau \langle x, Jx \rangle + \langle v, x \rangle)$ If

$$\text{Cov}_{\nu_{\tau,v}} \preceq \alpha(\tau) \mathbb{I}_n, \quad \forall \tau \in [0, 1], \forall v$$

Then the MLSI constant of Glauber dynamics

$$\rho_{\text{MLSI}} \geq \frac{1}{n} \exp \left(-2 \|J\|_2 \int_0^1 \alpha(\tau) d\tau \right)$$

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For J be a positive-definite matrix with $\|J\|_2 < \frac{1}{2}$ and $v \in \mathbb{R}^n$, adapting Bauerschmidt, Dagallier '22, we have

$$\|\text{Cov}(\nu_{\tau,v})\|_2 \leq \frac{1}{1 - 2(1 - \tau) \|J\|_2},$$

leading to $\rho_{\text{MLSI}} \geq \frac{1}{n} (1 - 2 \|J\|_2)$.

- The condition $\|J\|_2 \leq \frac{1}{2}$ is tight in general, as it is tight for Curie-Weiss model
- However, for the Sherrington-Kirkpatrick model, which assumes $J = \frac{\beta}{2}A$ where A is drawn from $\text{GOE}(n)$. The above approach only gets fast mixing of Glauber dynamics for $\beta < \frac{1}{4}$, while the conjectured phase transition is at $\beta < 1$.

What happens when we apply Eldan's stochastic localization?

Take control matrix $C_t = (2J)$, for $t \in [0, 1]$,

$$\begin{aligned}\nu_t(x) &\propto \mu(x) \exp(-t \langle x, Jx \rangle + \langle C_t, x \rangle) \\ &\propto \exp((1-t) \langle x, Jx \rangle + \langle h + C_t, x \rangle)\end{aligned}$$

where $c_t = C_t^{\frac{1}{2}} dW_t + \mathbf{b}(\nu_t) dt$.

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At time $t = 1$, ν_t becomes a product measure (so easy to show MLSI).

Let's take a look at the evolution of entropy

Evolution of entropy along Eldan's SL

For $f: \mathcal{X} \rightarrow \mathbb{R}_+$

$$d\text{Ent}_{\nu_t}[f] = -\frac{1}{2}\mathbb{E}_{\nu_t}[f] \left| C_t^{\frac{1}{2}}(\mathbf{b}(\omega_t) - \mathbf{b}(\nu_t)) \right|^2 dt + \text{martingale}$$

where ω_t is the probability measure $\propto f\nu_t$.

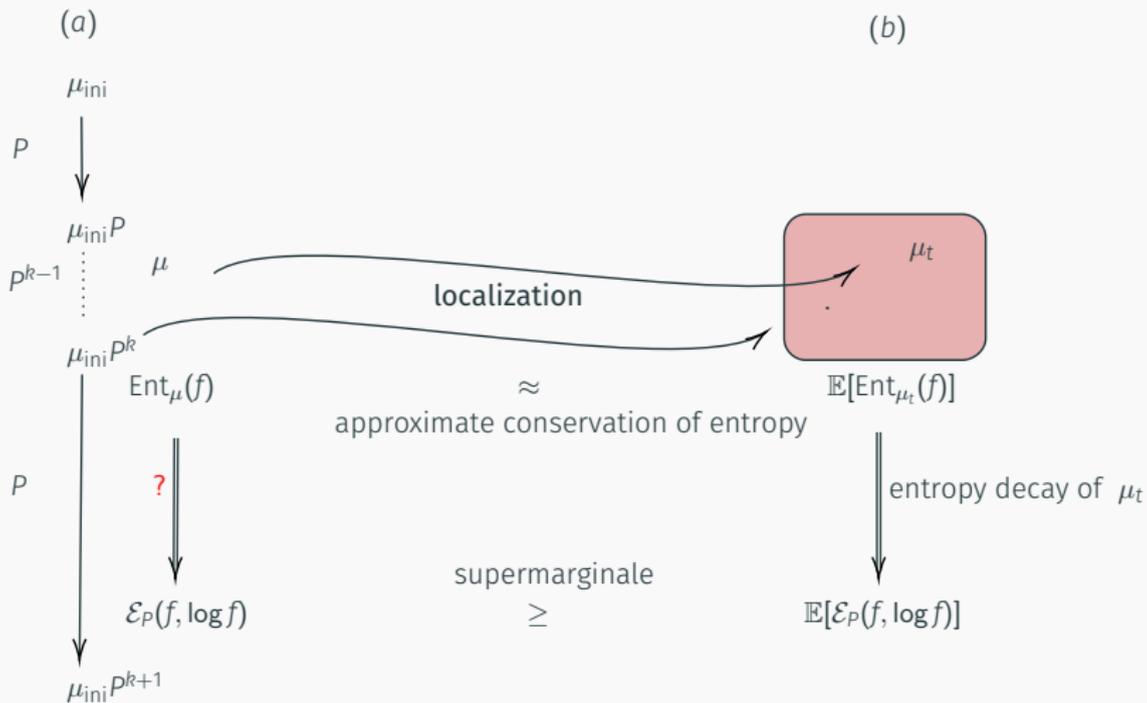
Additionally, if $\text{Cov}(\mathcal{T}_V\nu_t) \preceq A_t, \forall t$, then

$$\frac{1}{2}\mathbb{E}_{\nu_t}[f] \left| C_t^{\frac{1}{2}}(\mathbf{b}(\omega_t) - \mathbf{b}(\nu_t)) \right|^2 \leq \left\| C_t^{\frac{1}{2}} A_t C_t^{\frac{1}{2}} \right\|_2 \text{Ent}_{\nu_t}[f]$$

Solving the equation, we obtain approximate conservation of entropy

$$\mathbb{E}[\text{Ent}_{\nu_t}[f]] \geq e^{-2\|J\|_2 \int_0^t \alpha(\tau) d\tau} \text{Ent}_{\nu_0}[f]$$

Use of localization schemes for entropy decay



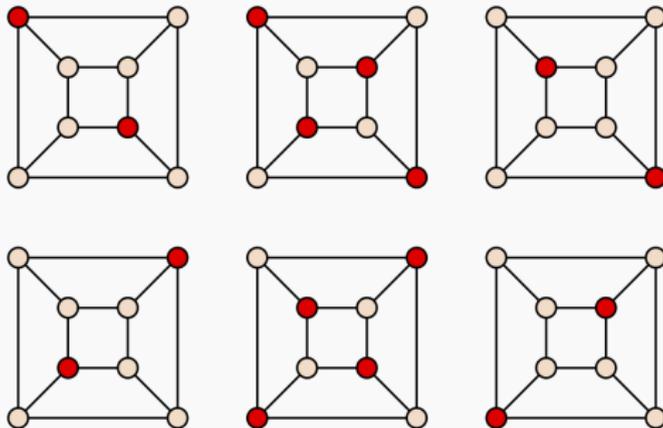
Negative-fields localization

The hardcore model

Given a graph $G = (V, E)$ with $|V| = n$, a **hardcore model with fugacity λ** on $\{-1, +1\}^n$ is

$$\mu(\sigma) \propto \lambda^{|I_\sigma|},$$

where $\mu(\sigma) > 0$ if the set $I_\sigma = \{v \in V \mid \sigma_v = +1\}$ corresponds to an independent set of G .



Negative-fields localization

Given a measure ν on $\{-1, 1\}^n$, the process $\{\nu_t\}_{t \geq 0}$ evolves as

- For $x \in \{-1, 1\}^n$, ν_t solves the SDE

$$d\nu_s(x) = \nu_s(x) \langle x - \mathbf{b}(\nu_s), dJ_s \rangle,$$

where

$$dJ_{s,i} = -ds + \frac{1}{1 + \mathbf{b}(\nu_s)_i} N_{s,i}$$

where $N_{s,i}$ is a **Poisson point process** with intensity $1 + \mathbf{b}(\nu_s)_i$

Inspired by field dynamics in Chen, Feng, Yin, and Zhang '21

How does the measure ν_t look like?

- At time t , define $A_t = \{i \in \{1, \dots, n\} \mid N_{t,i} \geq 1\}$.
Since $N_{t,i}$ is non-decreasing, A_t is an almost surely non-decreasing process of subsets of $\{1, \dots, n\}$.
- We can write ν_t as

$$\nu_t = \mathcal{T}_{-t\vec{1}} \mathcal{R}_{A_t} \nu$$

“ ν_t is the density obtained by pinning all coordinates in A_t to +1 and then tilt by $-t\vec{1}$ ”

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What is remaining?

- The mixing analysis on measures with large tilts are well-known in [Erbar, Henderson, Menz and Tetali '17]
- We need to study the evolution of the process: this is where we use properties of the hardcore model to ensure approximate conservation of entropy.

Summary

- Introduced localization schemes to analyze mixing
- For each localization scheme,
 - we can study the evolution of variance (or entropy)
 - assumptions to ensure the **approximate conservation of variance** (or entropy) are usually the key assumptions
- Designing **Localization schemes** allows us to take advantage of our insights about target distributions
 - Recover results of spectral independence/fractional log-concavity
 - Optimal $O(n \log n)$ Glauber dynamics mixing bound for Ising models in the uniqueness regime under any external fields
 - $O(n \log n)$ Glauber dynamics mixing bound for the hardcore model in the tree-uniqueness regime

Thank you!

