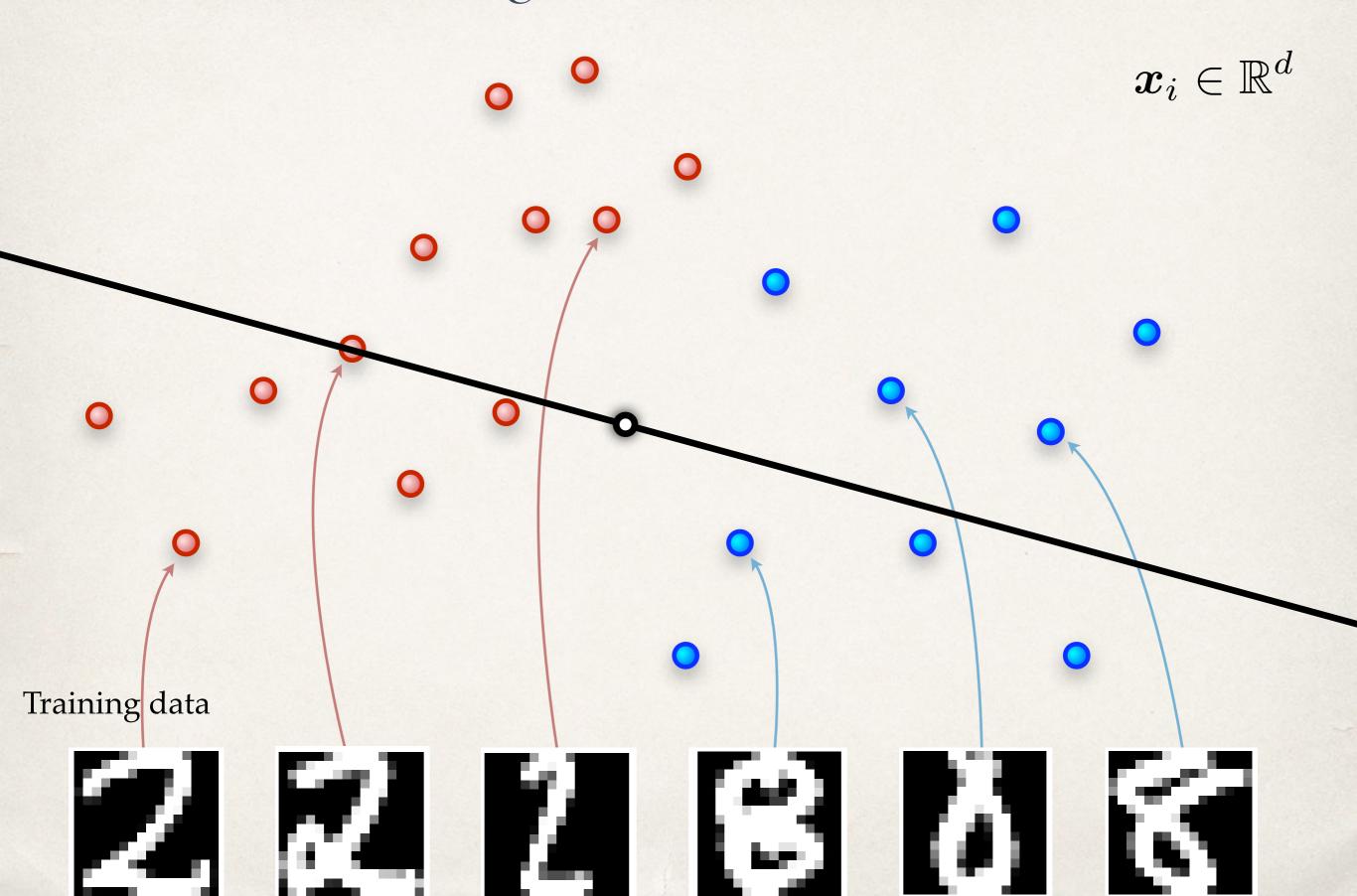
# Communication-Efficient Distributed Optimization

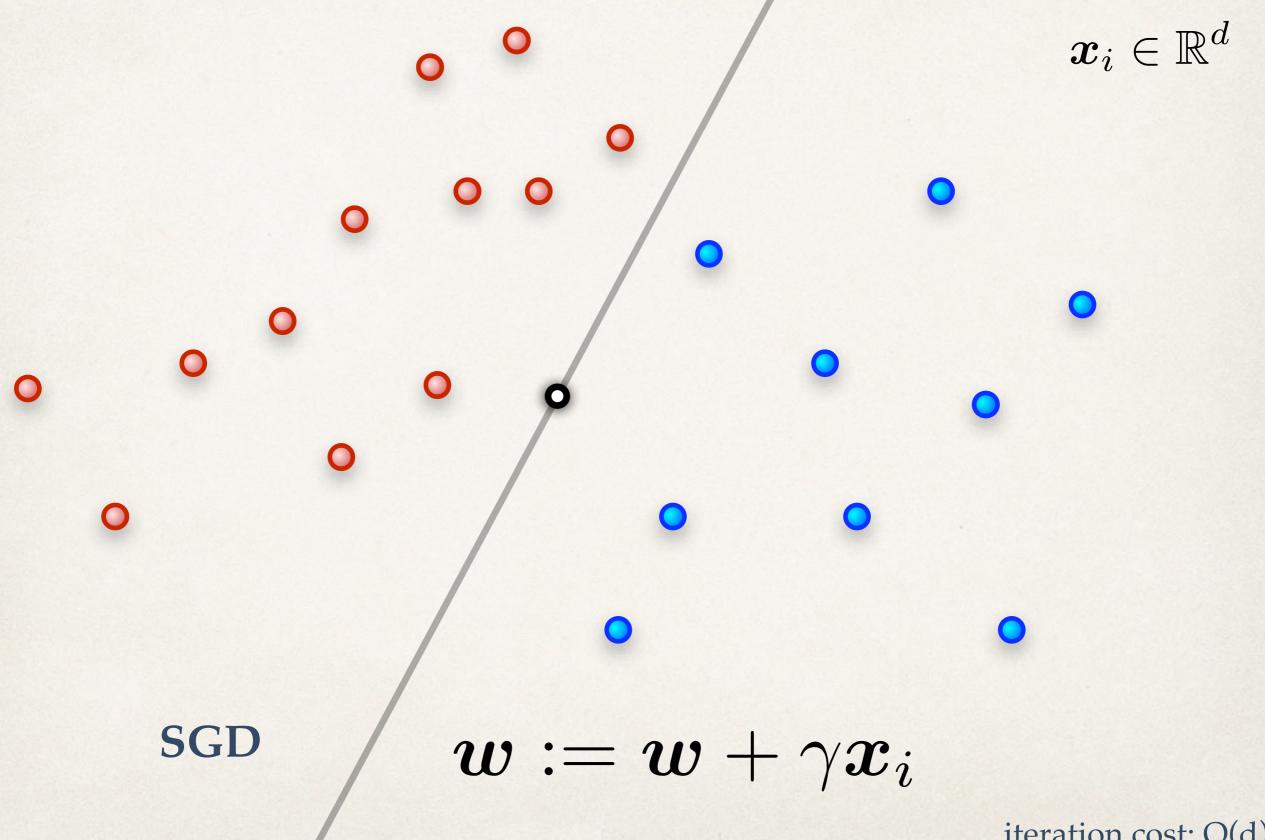
(CoCoA)

Martin Jaggi ETH Zurich Virginia Smith, UC Berkeley
Martin Takáč, Lehigh Univ.
Jonathan Terhorst, UC Berkeley
Sanjay Krishnan, UC Berkeley
Thomas Hofmann, ETH Zurich
Michael I. Jordan, UC Berkeley

## Training Linear Classifiers



## Stochastic Optimization / Online Learning



iteration cost: O(d)

## Supervised Machine Learning

SVM, Logistic Regression Ridge Regression, Lasso / Least Squares

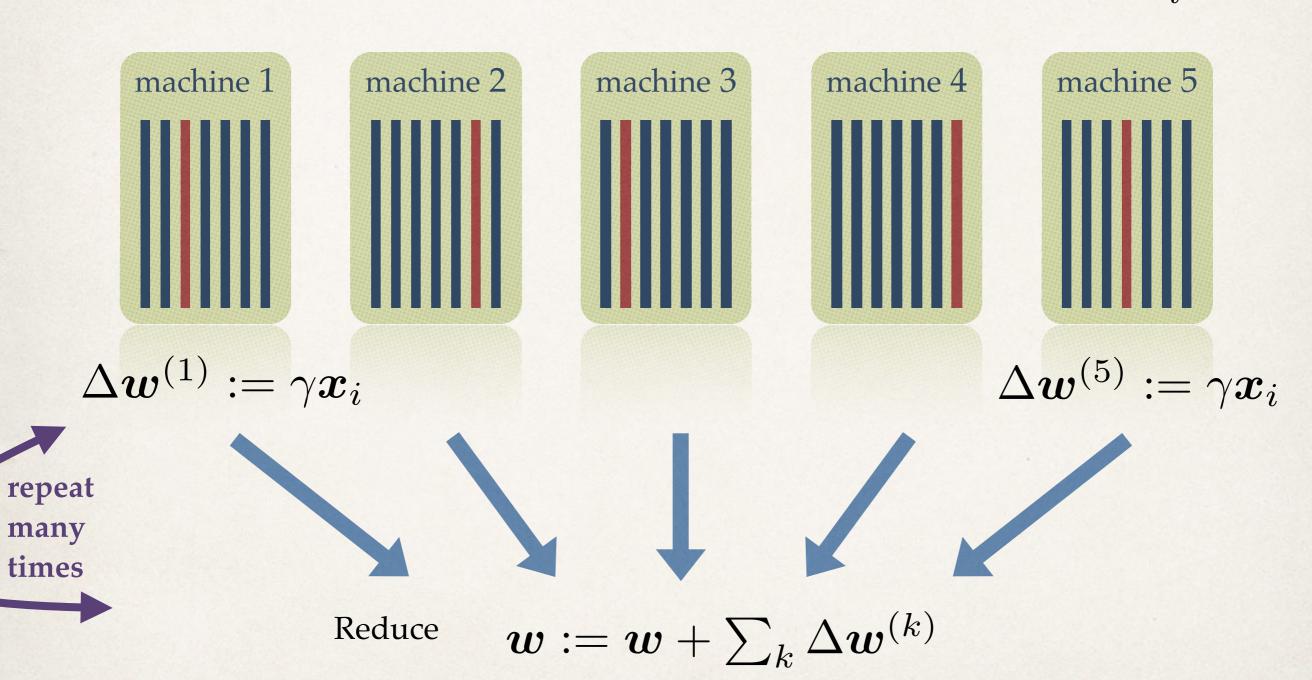
$$\min_{\boldsymbol{w} \in \mathbb{R}^d} \quad \left[ P(\boldsymbol{w}) := \frac{\lambda}{2} \|\boldsymbol{w}\|^2 + \frac{1}{n} \sum_{i=1}^n \ell_i(\boldsymbol{w}^T \boldsymbol{x}_i) \right]$$

Convergence Rate: (single machine case)

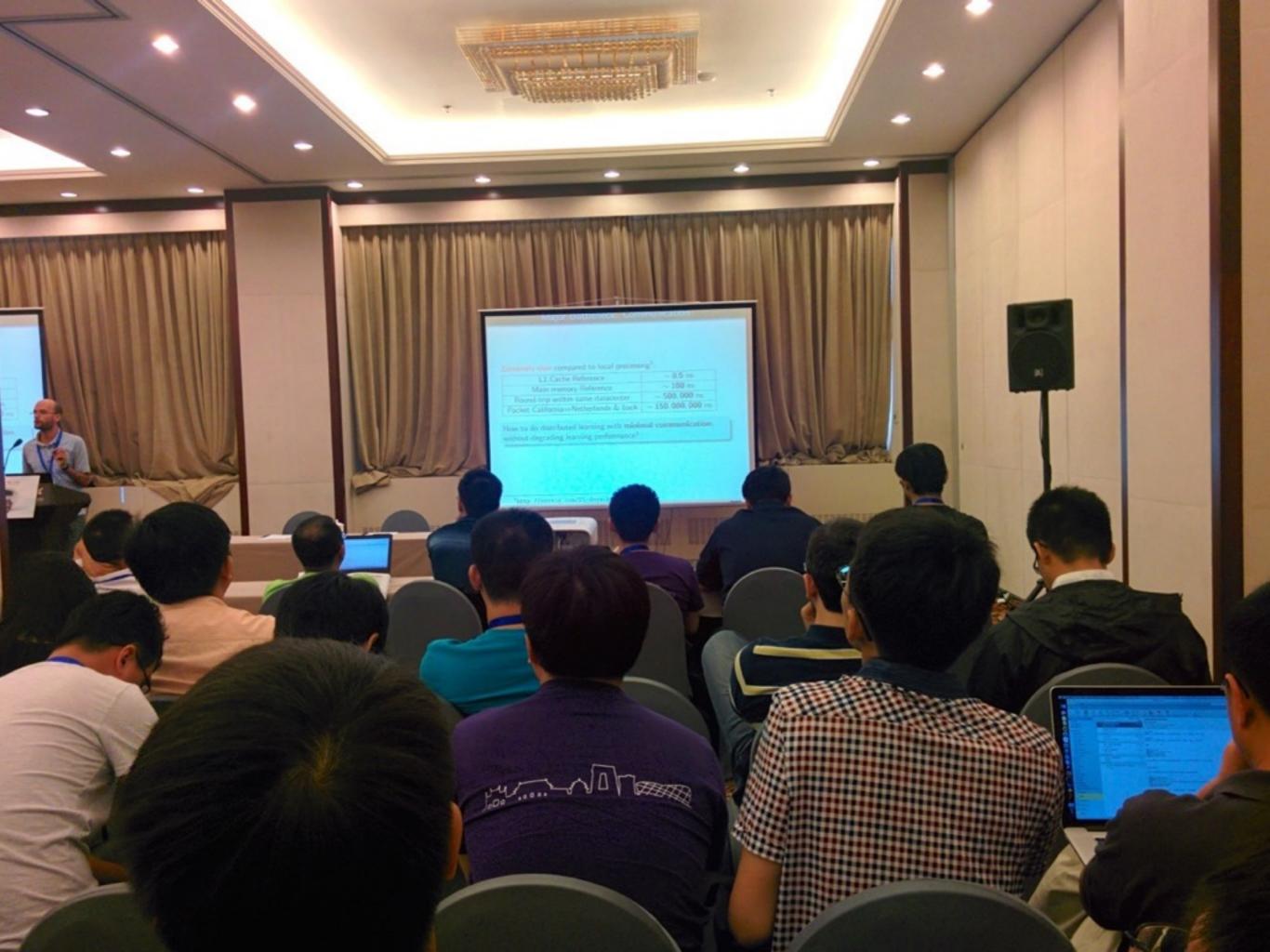
$$P(\boldsymbol{w}^{(T)}) - P(\boldsymbol{w}^*) \le C^{-T}[P(\boldsymbol{w}^{(0)}) - P(\boldsymbol{w}^*)]$$
  
 $\ell_i \text{ smooth}$  SAG, SDCA, SVRG, S2GD, SAGA

## Distributed Stochastic Optimization

 $oldsymbol{x}_i \in \mathbb{R}^d$ 



Naive Distributed SGD



#### iviajor Bottleneck: Communication

Extremely slow compared to local processing1:

	$\sim 0.5$ ns	
L1 Cache Reference	$\sim$ 100 ns $\sim$ 500,000 ns	
Main memory Reference		
Round-trip within same datacenter		
Packet California⇒Netherlands & back	$\sim 150,000,000 \; \text{ns}$	

How to do distributed learning with minimal communication, without degrading learning performance?

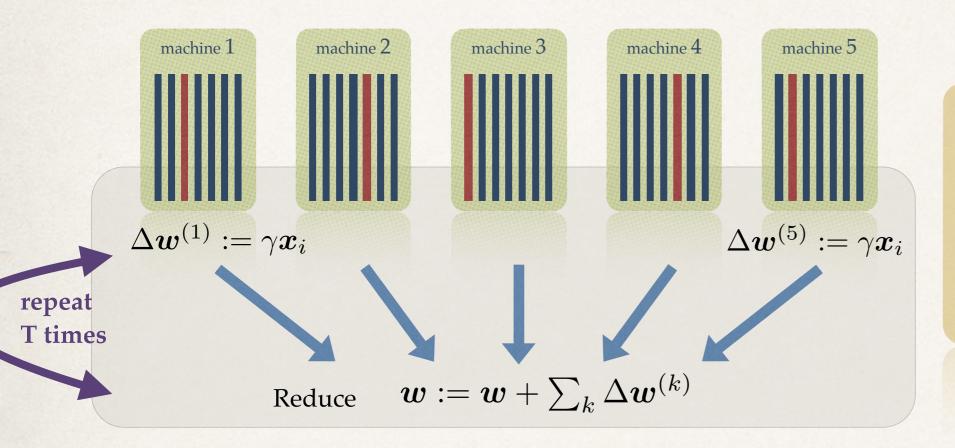
http://norvig.com/21-days.h

## The Cost of Communication

 $oldsymbol{v} \in \mathbb{R}^{100}$ 

- Reading v from Memory (RAM)
   100 ns
- Sending v to another Machine 500'000 ns
- One Typical Map-Reduce Iteration (*Hadoop*) 10'000'000'000 ns

## Distributed Stochastic Optimization

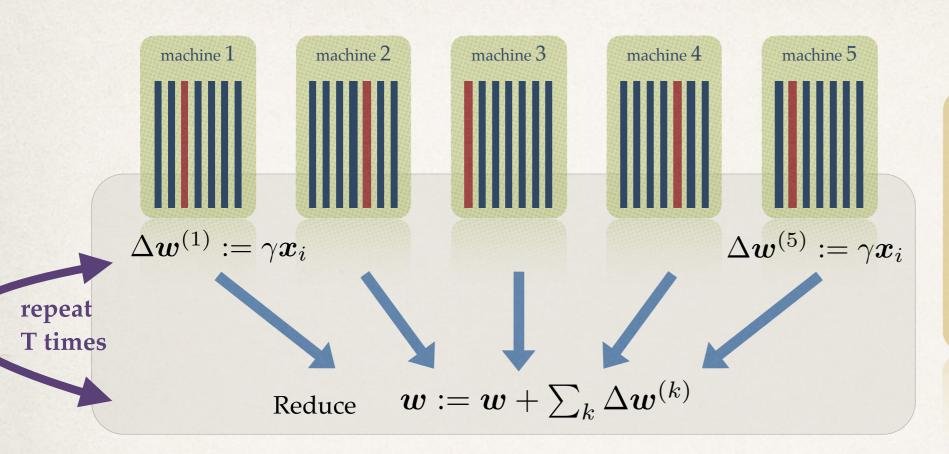


#### Naive Distributed SGD

# local datapoints read: T
# communications: T
convergence:

"always communicate"

## Communication: Always / Never



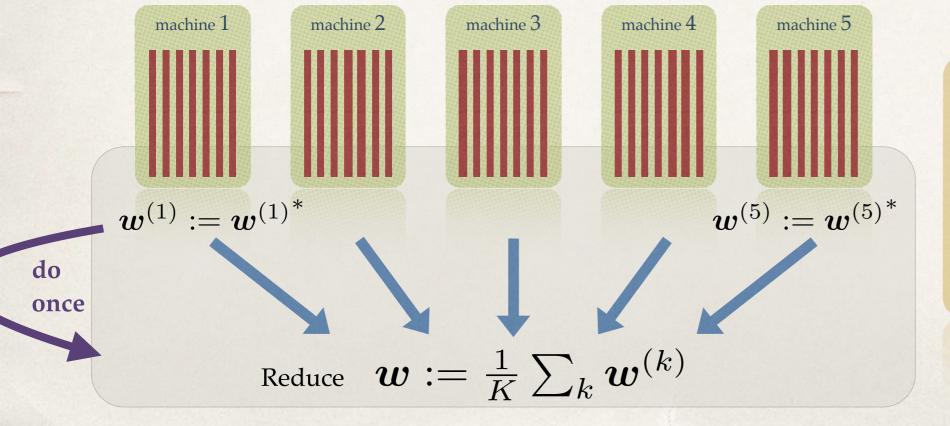
#### Naive Distributed SGD

# local datapoints read: T # communications: T

convergence:

nicato"

"always communicate"



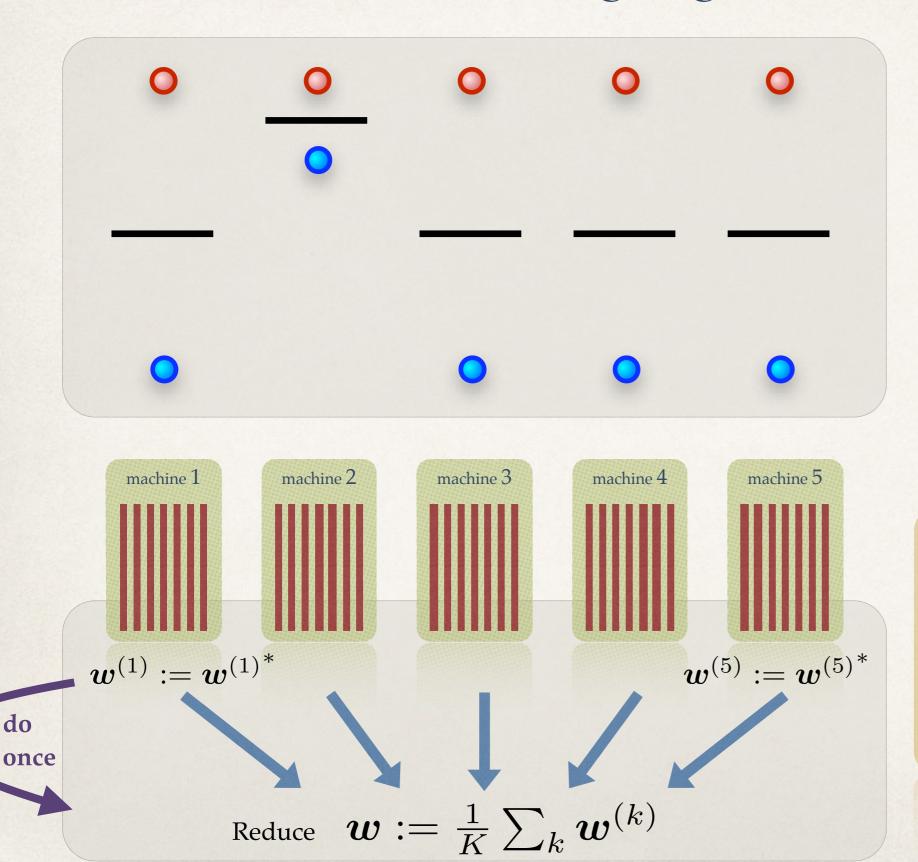
## One-Shot Averaged Distributed Optimization

# local datapoints read: T # communications: 1

convergence:

"never communicate"

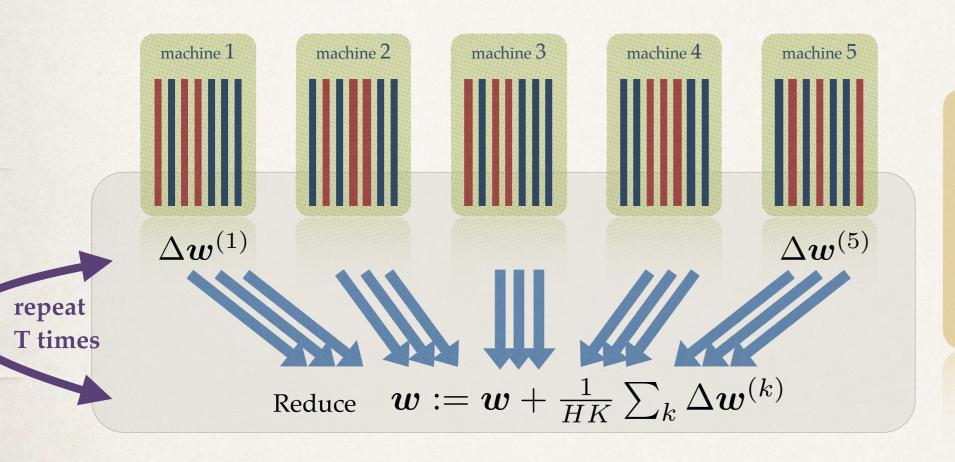
## One-Shot Averaging Does Not Work



## One-Shot Averaged Distributed Optimization

#local datapoints read: T
#communications: 1
convergence:

## The Middle Ground



#### Mini-Batch SGD / CD

#local datapoints read: TH

# communications:

convergence:

## Primal-Dual Structure

#### **Primal**

$$\min_{\boldsymbol{w} \in \mathbb{R}^d} \quad \left[ P(\boldsymbol{w}) := \frac{\lambda}{2} \|\boldsymbol{w}\|^2 + \frac{1}{n} \sum_{i=1}^n \ell_i(\boldsymbol{w}^T \boldsymbol{x}_i) \right]$$

#### **Optimization Algorithms:**

**SGD** 

#### correspondence

$$w_{(\alpha)} := A\alpha$$

#### Dual

$$\max_{\boldsymbol{\alpha} \in \mathbb{R}^n} \quad \left[ D(\boldsymbol{\alpha}) := -\frac{\lambda}{2} \|A\boldsymbol{\alpha}\|^2 - \frac{1}{n} \sum_{i=1}^n \ell_i^*(-\alpha_i) \right]$$

#### **Coordinate Descent**

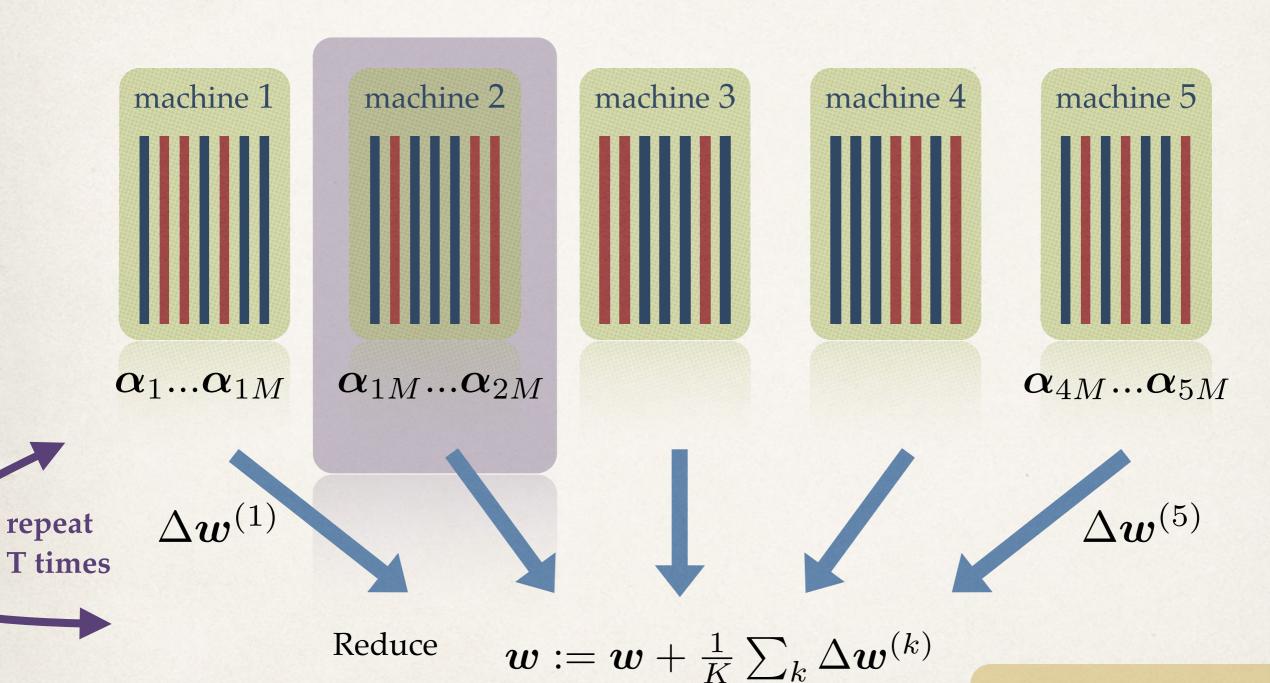
SVM dual: LibLinear '08

structSVM dual: BCFW '13

Lasso primal: GLMnet '10

Theory: SDCA '13

## Communication Efficient Distributed Dual Coordinate Ascent



# local datapoints read: TH
# communications: T
convergence: ✓

## Primal-Dual Structure

#### **Primal**

$$\min_{\boldsymbol{w} \in \mathbb{R}^d} \quad \left[ P(\boldsymbol{w}) := \frac{\lambda}{2} \|\boldsymbol{w}\|^2 + \frac{1}{n} \sum_{i=1}^n \ell_i(\boldsymbol{w}^T \boldsymbol{x}_i) \right]$$

#### **Optimization Algorithms:**

**SGD** 

correspondence

$$w_{(\alpha)} := A\alpha$$

#### Dual

$$\max_{oldsymbol{lpha}\in\mathbb{R}^n}$$

$$\max_{\boldsymbol{\alpha} \in \mathbb{R}^n} \quad \left[ D(\boldsymbol{\alpha}) := -\frac{\lambda}{2} \| \boldsymbol{A} \boldsymbol{\alpha} \|^2 - \frac{1}{n} \sum_{i=1}^n \ell_i^*(-\alpha_i) \right]$$

$$A_{ ext{loc}}oldsymbol{lpha}_{ ext{loc}}'+oldsymbol{w}$$

#### **Coordinate Descent**

SVM dual: LibLinear '08

structSVM dual: BCFW '13

Lasso primal: GLMnet '10

SDCA '13 Theory:

## Convergence Rate

**Theorem** 

T outer iterations

 $\ell_i(.)$  are  $1/\gamma$  smooth

 $\Theta$  local improvement in inner step

e.g. for localSDCA: 
$$\Theta = \left(1 - \frac{\lambda n \gamma}{1 + \lambda n \gamma} \frac{1}{\tilde{n}}\right)^H$$

$$\mathbf{E}[D(\boldsymbol{\alpha}^*) - D(\boldsymbol{\alpha}^{(T)})] \le \left(1 - (1 - \Theta)\frac{1}{K}\frac{\lambda n\gamma}{\sigma + \lambda n\gamma}\right)^T \left(D(\boldsymbol{\alpha}^*) - D(\boldsymbol{\alpha}^{(0)})\right)$$

and also for duality gap

measure

$$0 \leq \sigma \leq n/K$$

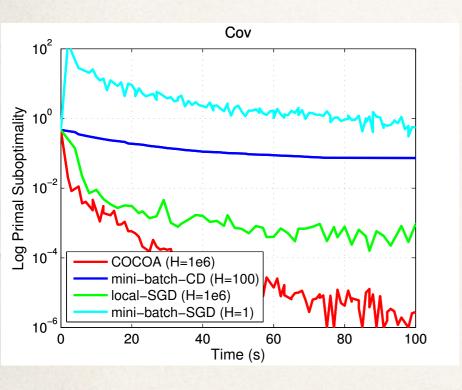
of difficulty of the data partition

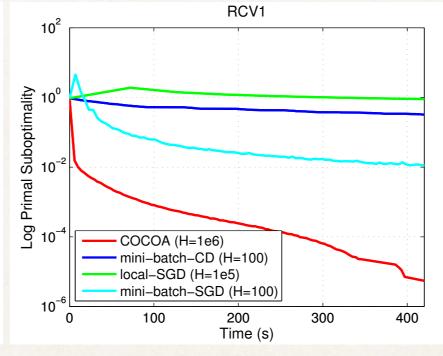
Proof Idea:

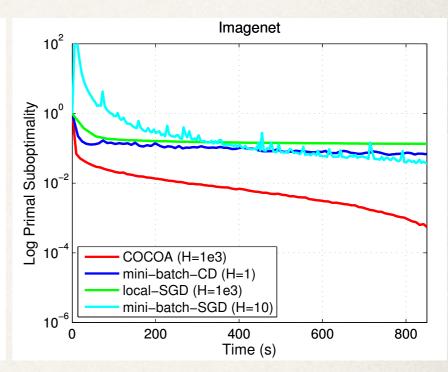
Distributing the proof of [SDCA 2013] using some block-coordinate descent ideas

## Experiments

Dataset	Training $n$	<b>Features</b> d	Sparsity	$  \lambda  $	Workers $K$
cov	522,911	54	22.22%	1e-6	4
rcv1	677,399	47,236	0.16%	1 <i>e</i> -6	8
imagenet	32,751	160,000	100%	1 <i>e</i> -5	32









## Conclusion

- full adaptivity to the communication cost
- theoretical and practical efficiency

#### **Open Research**

- \* slight generalizations to non-smooth losses, Lasso
- purely primal algorithm?
- balancing between adding and averaging
- rates on test error instead of training error?

### Thanks

"CoCoA - Communication-Efficient Distributed Dual Coordinate Ascent"

NIPS 2014 paper arxiv.org/abs/1409.1458

spork code is available on github