# Primal-Dual Symmetric Interior-Point Methods from SDP to Hyperbolic Cone Programming and Beyond

Tor Myklebust Levent Tunçel

September 26, 2014

Tor Myklebust, Levent Tuncel Primal-Dual IPMs for convex optim.

$$\begin{array}{rcl} (P) & \inf & \langle c, x \rangle \\ & & \mathcal{A}(x) &= b, \\ & & x \in K, \end{array}$$

э

$$\begin{array}{rcl} (P) & \inf & \langle c, x \rangle \\ & & \mathcal{A}(x) &= b, \\ & & x \in K, \end{array}$$

 $\mathsf{and}$ 

Tor Myklebust, Levent Tuncel Primal-Dual IPMs for convex optim.

э

$$\begin{array}{rcl} (P) & \inf & \langle c, x \rangle \\ & & \mathcal{A}(x) & = & b, \\ & & x & \in & K, \end{array}$$

and

$$\begin{array}{rcl} (D) & \sup & \langle b,y\rangle_D \\ & \mathcal{A}^*(y) & + & s & = & c, \\ & s & \in & K^*. \end{array}$$

æ

$$\begin{array}{rcl} (P) & \inf & \langle c, x \rangle \\ & & \mathcal{A}(x) & = & b, \\ & & x & \in & K, \end{array}$$

and

$$\begin{array}{rcl} (D) & \sup & \langle b,y\rangle_D \\ & \mathcal{A}^*(y) & + & s & = & c, \\ & s & \in & K^*. \end{array}$$

 ${\mathcal K}^*:=ig\{s\in {\mathbb E}^*: \langle s,x
angle \geq 0, \ orall x\in {\mathcal K}ig\}$  Dual Cone

3) 3

$$\begin{array}{rcl} (P) & \inf & \langle c, x \rangle \\ & & \mathcal{A}(x) & = & b, \\ & & x & \in & K, \end{array}$$

and

$$\begin{array}{rcl} (D) & \sup & \langle b,y\rangle_D \\ & & \mathcal{A}^*(y) & + & s & = & c, \\ & & s & \in & K^*. \end{array}$$

 $\mathcal{K}^* := \left\{ s \in \mathbb{E}^* : \langle s, x 
angle \geq 0, \ \forall x \in \mathcal{K} 
ight\}$  Dual Cone

 ${\it F}_{*}(s):=-{\rm inf}_{x\in {\rm int}({\it K})}\left\{\langle s,x\rangle+{\it F}(x)\right\} \ {\rm Legendre-Fenchel \ Conjugate}$ 

- **→** → **→** 

< ∃ > 3

One of the most important concepts in interior-point methods is *the central path*.

One of the most important concepts in interior-point methods is *the central path*. We arrive at this concept via another central concept *barrier*.

One of the most important concepts in interior-point methods is *the central path*. We arrive at this concept via another central concept *barrier*.

Let  $\mu > 0$ . Consider

$$egin{array}{rcl} (P_\mu) & \min & rac{1}{\mu} \langle c, x 
angle & + & F(x) \ & \mathcal{A}(x) & = & b, \ & (x & \in & \operatorname{int}(K)), \end{array}$$

One of the most important concepts in interior-point methods is *the central path*. We arrive at this concept via another central concept *barrier*.

Let  $\mu > 0$ . Consider

$$egin{array}{rcl} (P_\mu) & \min & rac{1}{\mu} \langle c,x 
angle & + & F(x) \ & \mathcal{A}(x) & = & b, \ & (x & \in & \operatorname{int}(K)), \end{array}$$

and

One of the most important concepts in interior-point methods is *the central path*. We arrive at this concept via another central concept *barrier*.

Let  $\mu > 0$ . Consider

$$egin{array}{rcl} (P_\mu) & \min & rac{1}{\mu} \langle c,x 
angle & + & F(x) \ & \mathcal{A}(x) & = & b, \ & (x & \in & \operatorname{int}(K)), \end{array}$$

and

$$egin{array}{rcl} (D_\mu) & \min & -rac{1}{\mu}\langle b,y
angle_D & + & F_*(s) \ & \mathcal{A}^*(y) & + & s=c, \ & (& s\in \operatorname{int}(\mathcal{K}^*) &). \end{array}$$

Under the assumption that  $\mathcal{F}_+ \neq \emptyset$ ,

Tor Myklebust, Levent Tuncel Primal-Dual IPMs for convex optim.

< 注→

æ

Under the assumption that  $\mathcal{F}_+ \neq \emptyset$ , both  $(P_\mu)$  and  $(D_\mu)$  have unique solutions for every  $\mu > 0$ .

 Under the assumption that  $\mathcal{F}_+ \neq \emptyset$ , both  $(P_\mu)$  and  $(D_\mu)$  have unique solutions for every  $\mu > 0$ . Moreover, these solutions define a smooth path, called *central path*, Under the assumption that  $\mathcal{F}_+ \neq \emptyset$ , both  $(P_\mu)$  and  $(D_\mu)$  have unique solutions for every  $\mu > 0$ .

Moreover, these solutions define a smooth path, called *central* path, and each point  $(x_{\mu}, y_{\mu}, s_{\mu})$  on the central path can be characterized as a unique solution of a system of equations (and being in the interior of the underlying cone).

We assume, we are given  $x^{(0)}$ ,  $s^{(0)}$  both strictly feasible in the problems (P) and (D), respectively. Define  $\mu_k := \frac{\langle x^{(k)}, s^{(k)} \rangle}{\vartheta}$ , we will compute  $x^{(k)}$  and  $s^{(k)}$  by an interior-point algorithm, which follows the central path approximately, such that both vectors are feasible and for a given desired accuracy  $\epsilon \in (0, 1)$ , we have  $\mu_k \leq \epsilon \mu_0$ .

We assume, we are given  $x^{(0)}$ ,  $s^{(0)}$  both strictly feasible in the problems (P) and (D), respectively. Define  $\mu_k := \frac{\langle x^{(k)}, s^{(k)} \rangle}{\vartheta}$ , we will compute  $x^{(k)}$  and  $s^{(k)}$  by an interior-point algorithm, which follows the central path approximately, such that both vectors are feasible and for a given desired accuracy  $\epsilon \in (0, 1)$ , we have  $\mu_k \leq \epsilon \mu_0$ .

Such algorithms (for LP, SDP and Symmetric Cone Programming) with current best complexity compute an  $\epsilon$ -solution  $(x^{(k)}, s^{(k)})$  in  $O\left(\sqrt{\vartheta} \ln\left(\frac{1}{\epsilon}\right)\right)$  iterations.

## A Hierarchical view of conic optimization

Strictly speaking we have,

 $LP \subset SOCP \subset SDP \subset SymCP \subset HomCP \subset HypCP \subset CP$ .

# A Hierarchical view of conic optimization

Strictly speaking we have,

 $LP \subset SOCP \subset SDP \subset SymCP \subset HomCP \subset HypCP \subset CP$ .

However, in some sense,

 $LP \subset SOCP \subseteq SDP = SymCP = HomCP \subseteq HypCP \subset CP$ .

# A Hierarchical view of conic optimization

Strictly speaking we have,

 $LP \subset SOCP \subset SDP \subset SymCP \subset HomCP \subset HypCP \subset CP$ .

However, in some sense,

 $LP \subset SOCP \subseteq SDP = SymCP = HomCP \subseteq HypCP \subset CP$ .

Yet in an another sense,

 $LP = SOCP \subseteq SDP = SymCP = HomCP \subseteq HypCP \subseteq CP$ .

See, Ben-Tal and Nemirovski; Chua; Faybusovich; Nesterov and Nemirovski; Vinnikov; Helton and Vinnikov; Lewis, Parrilo and Ramana; Gurvits; Gouveia, Parrilo and Thomas; Netzer and Sanyal; Netzer, Plaumann and Schweighofer; Plaumann, Sturmfels and Vinzant; ... Pinnacle of Symmetric Primal-Dual IPMs

Pinnacle of Symmetric Primal-Dual IPMs

Nesterov-Todd [1997-1998]: Primal-dual interior-point methods for self-scaled cones.

A key property of self-scaled barriers is "the Long-step Hessian Estimation property" which hinges on the following "compatibility" property of the underlying barrier

 $\langle -F'(x), y \rangle$  is convex for every  $y \in K$ .

A key property of self-scaled barriers is "the Long-step Hessian Estimation property" which hinges on the following "compatibility" property of the underlying barrier

 $\langle -F'(x), y \rangle$  is convex for every  $y \in K$ .

Krylov [1995], Güler [1997] showed that the above property holds for all hyperbolic barriers (in this sense, "generalizing" self-scaled barriers).

A key property of self-scaled barriers is "the Long-step Hessian Estimation property" which hinges on the following "compatibility" property of the underlying barrier

 $\langle -F'(x), y \rangle$  is convex for every  $y \in K$ .

Krylov [1995], Güler [1997] showed that the above property holds for all hyperbolic barriers (in this sense, "generalizing" self-scaled barriers).

Nesterov [1997] showed that we can't have this property for both F and  $F_*$  unless we are in the self-scaled case.



・ロト ・四ト ・ヨト ・ヨト

æ

 Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)

- Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)
- Extension of v-space based primal-dual ipms maintaining the long-step Hessian estimation property (New for HomCP, HypCP)

- Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)
- Extension of v-space based primal-dual ipms maintaining the long-step Hessian estimation property (New for HomCP, HypCP)
- Software (some of the Primal-Dual metrics *T*<sup>2</sup> utilized by these algorithms are new even for LP!)

- Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)
- Extension of v-space based primal-dual ipms maintaining the long-step Hessian estimation property (New for HomCP, HypCP)
- Software (some of the Primal-Dual metrics *T*<sup>2</sup> utilized by these algorithms are new even for LP!)
- Connections to other research areas in mathematics and mathematical sciences.

For every pointed closed convex cone K with nonempty interior, there is an associated function  $F : int(K) \to \mathbb{R}$  with the following properties:

For every pointed closed convex cone K with nonempty interior, there is an associated function  $F : int(K) \to \mathbb{R}$  with the following properties:

• F is continuously differentiable on int(K);

For every pointed closed convex cone K with nonempty interior, there is an associated function  $F : int(K) \to \mathbb{R}$  with the following properties:

- F is continuously differentiable on int(K);
- **2** F is strictly convex on int(K);

For every pointed closed convex cone K with nonempty interior, there is an associated function F : int $(K) \rightarrow \mathbb{R}$  with the following properties:

- F is continuously differentiable on int(K);
- **2** F is strictly convex on int(K);

● *F* is a barrier function for *K* (for every sequence  $\{x^{(k)}\} \subset int(K)$  converging to a boundary point of *K*, *F*  $(x^{(k)}) \rightarrow +\infty$ ).

#### Theorem

(T. [2001]) Let  $K \subset \mathbb{E}$  be a pointed closed convex cone with nonempty interior and let  $F : int(K) \to \mathbb{R}$  be a function with the properties listed in the lemma  $(+ \vartheta$ -log.-homogeneity). Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ , there exists  $T : \mathbb{E} \to \mathbb{E}^{\frac{*}{2}}$  linear, such that

### Theorem

(T. [2001]) Let  $K \subset \mathbb{E}$  be a pointed closed convex cone with nonempty interior and let  $F : int(K) \to \mathbb{R}$  be a function with the properties listed in the lemma  $(+ \vartheta$ -log.-homogeneity). Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ , there exists  $T : \mathbb{E} \to \mathbb{E}^{\frac{*}{2}}$  linear, such that

$$T^* = T,$$
(T. [2001]) Let  $K \subset \mathbb{E}$  be a pointed closed convex cone with nonempty interior and let  $F : int(K) \to \mathbb{R}$  be a function with the properties listed in the lemma  $(+ \vartheta$ -log.-homogeneity). Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ , there exists  $T : \mathbb{E} \to \mathbb{E}^{\frac{*}{2}}$  linear, such that

$$\bullet T^* = T,$$

I is positive definite,

(T. [2001]) Let  $K \subset \mathbb{E}$  be a pointed closed convex cone with nonempty interior and let  $F : int(K) \to \mathbb{R}$  be a function with the properties listed in the lemma  $(+ \vartheta$ -log.-homogeneity). Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ , there exists  $T : \mathbb{E} \to \mathbb{E}^{\frac{*}{2}}$  linear, such that

$$\bullet T^* = T,$$

I is positive definite,

3 
$$T(s) = T^{-1}(x)$$
 or equivalently,  $T^2(s) = x$ ,

(T. [2001]) Let  $K \subset \mathbb{E}$  be a pointed closed convex cone with nonempty interior and let  $F : int(K) \to \mathbb{R}$  be a function with the properties listed in the lemma  $(+ \vartheta$ -log.-homogeneity). Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ , there exists  $T : \mathbb{E} \to \mathbb{E}^{\frac{*}{2}}$  linear, such that

$$T^* = T,$$

I is positive definite,

• 
$$T(s) = T^{-1}(x)$$
 or equivalently,  $T^2(s) = x$ ,

•  $T(F'(x)) = T^{-1}(F'_{*}(s))$  or equivalently,  $T^{2}(F'(x)) = F'_{*}(s)$ .

(T. [2001]) Let  $K \subset \mathbb{E}$  be a pointed closed convex cone with nonempty interior and let  $F : int(K) \to \mathbb{R}$  be a function with the properties listed in the lemma  $(+ \vartheta$ -log.-homogeneity). Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ , there exists  $T : \mathbb{E} \to \mathbb{E}^{\frac{*}{2}}$  linear, such that

$$T^* = T,$$

I is positive definite,

3 
$$T(s) = T^{-1}(x)$$
 or equivalently,  $T^2(s) = x$ ,

•  $T(F'(x)) = T^{-1}(F'_{*}(s))$  or equivalently,  $T^{2}(F'(x)) = F'_{*}(s)$ .

The set of solutions  $T^2$  of the above problems are denoted by  $T_0(x, s)$  and  $T_1(x, s)$ .

This theorem allows very wide generalizations of symmetric primal-dual interior-point algorithms to general convex (conic) optimization setting

This theorem allows very wide generalizations of symmetric primal-dual interior-point algorithms to general convex (conic) optimization setting (linear operator T generalizes the notion of primal-dual symmetric local metric—primal-dual scaling).

For convenience, we sometimes write  $\mu := \frac{\langle x, s \rangle}{\vartheta}$ ,

$$ilde{x}:=-F_{*}^{'}(s)$$
 and  $ilde{s}:=-F^{'}(x).$ 

For convenience, we sometimes write  $\mu := \frac{\langle x, s \rangle}{\vartheta}$ ,

$$\tilde{x} := -F'_*(s)$$
 and  $\tilde{s} := -F'(x)$ .

One can think of  $\tilde{x}$  and  $\tilde{s}$  as *shadow* iterates.

For convenience, we sometimes write  $\mu := \frac{\langle x, s \rangle}{\vartheta}$ ,

$$ilde{x} := -F_*^{'}(s)$$
 and  $ilde{s} := -F^{'}(x)$ .

One can think of  $\tilde{x}$  and  $\tilde{s}$  as *shadow* iterates. Since  $\tilde{x} \in int(K)$  and  $\tilde{s} \in int(K^*)$  and if (x, s) is a feasible pair, then

 $\mu \tilde{x} = x$  iff  $\mu \tilde{s} = s$  iff (x, s) lies on the central path.

For convenience, we sometimes write  $\mu := \frac{\langle x, s \rangle}{\vartheta}$ ,

$$ilde{x}:=-F_{*}^{'}(s)$$
 and  $ilde{s}:=-F^{'}(x).$ 

One can think of  $\tilde{x}$  and  $\tilde{s}$  as *shadow* iterates. Since  $\tilde{x} \in int(K)$  and  $\tilde{s} \in int(K^*)$  and if (x, s) is a feasible pair, then

 $\mu \tilde{x} = x$  iff  $\mu \tilde{s} = s$  iff (x, s) lies on the central path.

We also denote

$$ilde{\mu} := rac{\langle ilde{x}, ilde{s} 
angle}{artheta}.$$

"Proof' (for every *H* symmetric, positive definite):

$$T_{H}^{2} := H + a_{1}xx^{\top} + g_{1}Hss^{\top}H + \tilde{a}_{1}\tilde{x}\tilde{x}^{\top} + \tilde{g}_{1}H\tilde{s}\tilde{s}^{\top}H + a_{2}\left(x\tilde{x}^{\top} + \tilde{x}x^{\top}\right) + g_{2}\left(Hs\tilde{s}^{\top}H + H\tilde{s}s^{\top}H\right),$$

where

$$\begin{aligned} a_1 &:= \frac{\tilde{\mu}}{\vartheta(\mu\tilde{\mu}-1)}, \tilde{a}_1 &:= \frac{\mu}{\vartheta(\mu\tilde{\mu}-1)}, a_2 &:= -\frac{1}{\vartheta(\mu\tilde{\mu}-1)}, \\ g_1 &:= -\frac{\bar{s}^\top H\bar{s}}{(\bar{s}^\top H\bar{s})(\bar{s}^\top H\bar{s}) - (\bar{s}^\top H\bar{s})^2}, g_1 &:= -\frac{\bar{s}^\top H\bar{s}}{(\bar{s}^\top H\bar{s})(\bar{s}^\top H\bar{s}) - (\bar{s}^\top H\bar{s})^2}, g_2 &:= \frac{\bar{s}^\top H\bar{s}}{(\bar{s}^\top H\bar{s})(\bar{s}^\top H\bar{s}) - (\bar{s}^\top H\bar{s})^2}. \end{aligned}$$

글 > - < 글 >

## Nicer Hessian update formulas

Take

$$\delta_D := s - \mu \tilde{s}$$

$$\delta_P := x - \mu \tilde{x}.$$

Consider two consecutive DFP/BFGS-like updates:

$$\begin{aligned} H_1 &:= H + \frac{1}{\langle s, x \rangle} x x^\top - \frac{1}{\langle s, Hs \rangle} Hss^\top H \\ H_2 &:= H_1 + \frac{1}{\langle \delta_P, \delta_D \rangle} \delta_P \delta_P^\top - \frac{1}{\langle \delta_D, H_1 \delta_D \rangle} H_1 \delta_D \delta_D^\top H_1 \end{aligned}$$

# Nicer Hessian update formulas

Take

$$\delta_D := s - \mu \tilde{s}$$

$$\delta_P := x - \mu \tilde{x}.$$

Consider two consecutive DFP/BFGS-like updates:

#### Theorem

They're equivalent! I.e.,  $H_2 = T^2$ .

However, this new form is much more revealing!

# Complexity Analysis via Hessian update formulas

What will it reveal?

글 > - < 글 >

# Complexity Analysis via Hessian update formulas

What will it reveal? Iteration complexity bounds for primal-dual symmetric short-step algorithms.

What will it reveal? Iteration complexity bounds for primal-dual symmetric short-step algorithms.

It suffices to get an upper bound on the optimal objective value of the following SDP ([T. 2001]):

What will it reveal? Iteration complexity bounds for primal-dual symmetric short-step algorithms.

It suffices to get an upper bound on the optimal objective value of the following SDP ([T. 2001]):

$$\begin{array}{rcl} \inf & \boldsymbol{\xi} & & \\ & \boldsymbol{T}^2(s) & = & \boldsymbol{x}, \\ & \boldsymbol{T}^2(-F'(\boldsymbol{x})) & = & -F'_*(s), \\ & & \frac{1}{\xi h(\boldsymbol{x},s)} F''_*(s) & \preceq & \boldsymbol{T}^2 & \preceq & \boldsymbol{\xi} h(\boldsymbol{x},s) \left[ F''(\boldsymbol{x}) \right]^{-1}, \\ & & \boldsymbol{\xi} \geq 1, \qquad \boldsymbol{T} \in \mathbb{S}^n, \end{array}$$

where h(x, s) is a certain proximity measure for the central path.

・ロ・・聞・・聞・・聞・ 白・

Any upper bound by an absolute constant in a constant-sized neighbourhood of the central path leads to an iteration complexity bound of  $O\left(\sqrt{\vartheta} \ln \frac{1}{\epsilon}\right)$ .

Any upper bound by an absolute constant in a constant-sized neighbourhood of the central path leads to an iteration complexity bound of  $O\left(\sqrt{\vartheta} \ln \frac{1}{\epsilon}\right)$ .

In our language today,

#### Theorem

(Nesterov and Todd [1997, 1998]) Let  $K \subseteq \mathbb{E}$  be a symmetric (homogeneous self-dual) cone. Further let F be a  $\vartheta$ -self-scaled barrier for K. Then for every  $x \in int(K)$ ,  $s \in int(K^*)$ ,

$$\xi^* \leq \frac{4}{3}.$$

### We now have:

## Theorem

Let  $K \subseteq \mathbb{E}$  be a convex cone. Further let F be a  $\vartheta$ -self-concordant barrier for K. There are absolute constants  $C_1$  and  $C_2$  such that, for every  $x \in int(K)$  and  $s \in int(K^*)$  lying in a constant size  $(C_1)$ neighbourhood of the central path, we have

$$\xi^* \leq C_2.$$

## We now have:

#### Theorem

Let  $K \subseteq \mathbb{E}$  be a convex cone. Further let F be a  $\vartheta$ -self-concordant barrier for K. There are absolute constants  $C_1$  and  $C_2$  such that, for every  $x \in int(K)$  and  $s \in int(K^*)$  lying in a constant size  $(C_1)$ neighbourhood of the central path, we have

$$\xi^* \leq C_2.$$

Therefore, we obtain  $O\left(\sqrt{\vartheta}\ln(1/\epsilon)\right)$  iteration-complexity primal-dual symmetric ipms for general convex optimization problems.

Therefore, we obtain  $O\left(\sqrt{\vartheta}\ln(1/\epsilon)\right)$  iteration-complexity primal-dual symmetric ipms for general convex optimization problems.

Therefore, we obtain  $O\left(\sqrt{\vartheta}\ln(1/\epsilon)\right)$  iteration-complexity primal-dual symmetric ipms for general convex optimization problems.

So far, our proofs only work for short-step algorithms.

Therefore, we obtain  $O\left(\sqrt{\vartheta}\ln(1/\epsilon)\right)$  iteration-complexity primal-dual symmetric ipms for general convex optimization problems.

So far, our proofs only work for short-step algorithms.

How about the long-step Hessian estimation property?

# Hyperbolic cone programming and beyond

How about the long-step Hessian estimation property?

# Hyperbolic cone programming and beyond

How about the long-step Hessian estimation property?

Indeed, for hyperbolic programming problems there can be a clear distinction between the primal and the dual problems, if F is not a self-scaled barrier.

# Hyperbolic cone programming and beyond

How about the long-step Hessian estimation property?

Indeed, for hyperbolic programming problems there can be a clear distinction between the primal and the dual problems, if F is not a self-scaled barrier. (Recall, only symmetric cones admit self-scaled barriers.)

How about the long-step Hessian estimation property?

Indeed, for hyperbolic programming problems there can be a clear distinction between the primal and the dual problems, if F is not a self-scaled barrier. (Recall, only symmetric cones admit self-scaled barriers.)

#### Theorem

(Güler [1997]) Let p be a homogeneous hyperbolic polynomial of degree  $\vartheta$ . Then,  $F(x) := -\ln(p(x))$  is a  $\vartheta$ -LHSCB for the hyperbolicity cone of p. Moreover, F has the long-step Hessian estimation property.

How about the long-step Hessian estimation property?

Indeed, for hyperbolic programming problems there can be a clear distinction between the primal and the dual problems, if F is not a self-scaled barrier. (Recall, only symmetric cones admit self-scaled barriers.)

#### Theorem

(Güler [1997]) Let p be a homogeneous hyperbolic polynomial of degree  $\vartheta$ . Then,  $F(x) := -\ln(p(x))$  is a  $\vartheta$ -LHSCB for the hyperbolicity cone of p. Moreover, F has the long-step Hessian estimation property.

Is there any hope for maintain this long-step Hessian estimation property in a primal-dual *v*-space based algorithm?

Let F be a LHSCB for K and  $(x, s) \in int(K) \oplus int(K^*)$ . Then, the linear transformation

$$T_D^2 := \mu \int_0^1 F_*''(s - t\delta_D) dt$$

Let F be a LHSCB for K and  $(x, s) \in int(K) \oplus int(K^*)$ . Then, the linear transformation

$$T_D^2 := \mu \int_0^1 F_*''(s - t\delta_D) dt$$

is self-adjoint, positive definite, maps s to x, and maps  $\tilde{s}$  to  $\tilde{x}$ . Therefore, its unique self-adjoint, positive definite square root  $T_D$  is in  $\mathcal{T}_1(x, s)$ . Using the fundamental theorem of calculus (for the second equation below) followed by the property  $-F'_*(-F'(x)) = x$  (for the third equation below), we obtain

$$T_D^2 \delta_D = \mu \int_0^1 F_*''(s - t\delta_D) \delta_D dt$$
  
=  $\mu \left( F_*'(s - \delta_D) - F_*'(s) \right)$   
=  $\mu \left( x/\mu - \tilde{x} \right)$   
=  $\delta_P.$ 

- A 3 N

э

# Proof ... continued

We next compute, using the substitution u = 1/t,

$$T_D^2 s = \mu \int_0^1 F_*''(s - t\delta_D) s dt$$
  
=  $\mu \int_0^1 \frac{1}{t^2} F_*''(s/t - \delta_D) s dt$   
=  $\mu \int_1^\infty F_*''(us - \delta_D) s du$   
=  $-\mu F'(s - \delta_D) = x.$ 

(《聞》 《문》 《문》 - 문

# Proof ... continued

We next compute, using the substitution u = 1/t,

$$T_D^2 s = \mu \int_0^1 F_*''(s - t\delta_D) s dt$$
  
=  $\mu \int_0^1 \frac{1}{t^2} F_*''(s/t - \delta_D) s dt$   
=  $\mu \int_1^\infty F_*''(us - \delta_D) s du$   
=  $-\mu F'(s - \delta_D) = x.$ 

Further,  $T_D^2$  is the mean of some self-adjoint, positive definite linear transformations, so  $T_D^2$  itself is self-adjoint and positive definite.

高 と く ヨ と く ヨ と

# Proof ... continued

We next compute, using the substitution u = 1/t,

$$T_D^2 s = \mu \int_0^1 F_*''(s - t\delta_D) s dt$$
  
=  $\mu \int_0^1 \frac{1}{t^2} F_*''(s/t - \delta_D) s dt$   
=  $\mu \int_1^\infty F_*''(us - \delta_D) s du$   
=  $-\mu F'(s - \delta_D) = x.$ 

Further,  $T_D^2$  is the mean of some self-adjoint, positive definite linear transformations, so  $T_D^2$  itself is self-adjoint and positive definite.

高 と く ヨ と く ヨ と
Note that each of the sets  $\mathcal{T}_0$ ,  $\mathcal{T}_1$ ,  $\mathcal{T}_2$  of all such primal-dual local metrics is geodesically convex!

Note that each of the sets  $\mathcal{T}_0$ ,  $\mathcal{T}_1$ ,  $\mathcal{T}_2$  of all such primal-dual local metrics is geodesically convex!

Hence, any specific choice of  $T^2$  (which may not be primal-dual symmetric) from any one this sets can be made into a primal-dual symmetric local metric via taking the operator geometric mean with the inverse of its counterpart.

 Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)

- Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)
- Extension of v-space based primal-dual ipms maintaining the long-step Hessian estimation property (New for HomCP, HypCP)

- Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)
- Extension of v-space based primal-dual ipms maintaining the long-step Hessian estimation property (New for HomCP, HypCP)
- Software (some of the Primal-Dual metrics *T*<sup>2</sup> utilized by these algorithms are new even for LP!)

- Complexity analysis of v-space based primal-dual ipms matching the iteration complexity bounds for LPs! (New for HomCP, HypCP, CP.)
- Extension of v-space based primal-dual ipms maintaining the long-step Hessian estimation property (New for HomCP, HypCP)
- Software (some of the Primal-Dual metrics *T*<sup>2</sup> utilized by these algorithms are new even for LP!)
- Connections to other research areas in mathematics and mathematical sciences.